

AN APPROXIMATION SCHEME FOR SOLVING QUASI-VARIATIONAL INCLUSIONS AND QUASIMONOTONE VARIATIONAL INEQUALITIES

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In this article, we discuss iterative schemes for solving quasi-variational inclusions and quasimonotone variational inequalities in Hilbert spaces. An iterative scheme is presented which consists of resolvent technique, extragradient-type algorithm and self-adaptive linear search rule. Under several appropriate conditions, we prove the convergence of the investigated scheme.

Keywords: quasi-variational inclusions, quasimonotone variational inequalities, extragradient-type method, linear search rule.

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1. Introduction

In this article, we are concerned with iterative schemes for the quasi-variational inclusion

$$\text{Find a point } s^* \in 2^{\mathcal{H}} \text{ such that } 0 \in U(s^*) + G(s^*), \quad (1)$$

where \mathcal{D} is a nonempty, convex and closed subset of a real Hilbert space \mathcal{H} with inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$ and $U: \mathcal{D} \rightarrow \mathcal{H}$ and $G: \mathcal{H} \rightrightarrows 2^{\mathcal{H}}$ be two nonlinear operators. The solution set of (1) is expressed by $(U + G)^{-1}(0)$.

A great variety of problems originating from natural science, engineering applications and management services can be converted to this kind of quasi-variational inclusion problems, see, [18, 19]. Iterative algorithms for seeking $s^* \in (U + G)^{-1}(0)$ are studied in ([6, 19, 32, 54, 57]). These algorithms define a procedure through the following way

$$t_0 \in \mathcal{D}, \quad t_{n+1} = \text{Res}_{\alpha}^G(t_n - \alpha U(t_n)), \quad n \geq 0, \quad (2)$$

where $\alpha > 0$ is any constant and the operator $\text{Res}_{\alpha}^G := (I + \alpha U)^{-1}$ is the resolvent of G . This way is so-called the resolvent method.

Let $F: \mathcal{D} \rightarrow \mathcal{H}$ be a nonlinear operator. Now, we focus on the following variational inequality

$$\text{Find } s^* \in \mathcal{D} \text{ such that } \langle F(s^*), s - s^* \rangle \geq 0, \quad \forall s \in \mathcal{D}, \quad (3)$$

The prologue of variational inequality occurred in 1964 when Stampacchia ([24]) utilized it as a technique for solving partial differential equations. As we know, variational inequality theory has become a central concept in numerous problems such as optimization ([2, 7, 11, 14, 21, 30, 40, 42, 48, 56]), equilibrium problems ([33, 39, 54]), fixed point problems ([8, 20, 22, 26–28, 31, 36, 38, 41]) and so on. Various numerical approaches have been put forward for computing a solution of variational inequality. For some related valuable methods and techniques, please refer to [1, 4, 17, 25, 34, 37, 43–46, 52, 53, 55].

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Now, we all know that finding a solution s^* of (3) can be translated into solving a fixed point problem, i.e.,

$$s^* \in \text{VI}(F, \mathcal{D}) \Leftrightarrow s^* = \text{proj}_{\mathcal{D}}(s^* - \alpha F(s^*)), \quad (4)$$

where $\text{VI}(F, \mathcal{D})$ denotes the set of solution of (3), $\text{proj}_{\mathcal{D}}$ means the metric projection from \mathcal{H} onto \mathcal{D} and α is a positive constant. Based on the equivalent relation (4), we can compute a solution of (3) by utilizing the following projection algorithm ([16, 23, 35])

$$t_0 \in \mathcal{D}, t_{n+1} = \text{proj}_{\mathcal{D}}(t_n - \alpha F(t_n)), \forall n \geq 0. \quad (5)$$

In fact, if F is strongly monotone or inverse strongly monotone ([3]), we can guarantee that $\text{proj}_{\mathcal{D}}(I - \alpha F)$ is a contractive operator provided $\alpha \in (0, 1/\nu)$ with ν being the Lipschitz constant of F . In this sense, the projection algorithm (5) is a popular method that can be easily implemented. In 1976, Korpelevich ([15]) designed an iterative algorithm below for computing a solution of (3)

$$\begin{cases} t_0 \in \mathcal{D}, \\ s_n = \text{proj}_{\mathcal{D}}(t_n - \alpha F(t_n)), \\ t_{n+1} = \text{proj}_{\mathcal{D}}(t_n - \alpha F(s_n)), n \geq 0. \end{cases} \quad (6)$$

This novel algorithm (6) named ‘‘extragradient algorithm’’ is remarkable because it can be performed to compute a solution of pseudomonotone variational inequalities but the projection algorithm (5) fails. As a matter of fact, the projection algorithm (5) may be divergent if F is pseudomonotone ([13, 29]). In this meaning, the extragradient algorithm (6) is easier to perform and it has been extensively used and generalized, see, e.g., [5, 10, 12, 47, 50, 51, 58]. On the other hand, in order to ensure the convergence of the sequence $\{t_n\}$, an additional condition

$$\text{VI}(F, \mathcal{D}) \subset \text{DVI}(F, \mathcal{D}) \quad (7)$$

was employed where $\text{DVI}(F, \mathcal{D})$ is the solution set of the following variational inequality

$$\text{Find } s^* \in \mathcal{D} \text{ such that } \langle F(s), s - s^* \rangle \geq 0, \forall s \in \mathcal{D}. \quad (8)$$

The variational inequality (8) is so-called the dual variational inequality of (3). From (8), it is easy to see that $\text{DVI}(F, \mathcal{D})$ is a closed convex set. It is known that if \mathcal{D} is convex and F is continuous, then $\text{DVI}(F, \mathcal{D}) \subset \text{VI}(F, \mathcal{D})$. Note that the assumption (7) holds when F is pseudomonotone however it may not hold when F is quasimonotone.

The aim of this article is to introduce an iterative procedure for solving the quasivariational inclusion problem (1) and the quasimonotone variational inequality (3) in Hilbert spaces. Our procedure consists of resolvent technique, extragradient-type algorithm and self-adaptive linear search rule. Under several appropriate conditions, we prove the convergence of the investigated scheme.

2. Preliminaries

Let \mathcal{H} be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\|\cdot\|$. In the sequel, we use the symbols ‘‘ \rightharpoonup ’’ and ‘‘ \rightarrow ’’ to indicate weak convergence and strong convergence, respectively. Let $G: \mathcal{H} \rightrightarrows 2^{\mathcal{H}}$ be a multi-valued operator with domain $D(G) = \{s^* \in \mathcal{H} : G(s^*) \neq \emptyset\}$. Set $G^{-1}(0) := \{s^* \in \mathcal{H} : 0 \in G(s^*)\}$. G is said to be monotone if and only if $\langle p - q, s - t \rangle \geq 0, \forall p, q \in D(G)$ where $s \in G(p)$ and $t \in G(q)$. An operator $G: \mathcal{H} \rightrightarrows 2^{\mathcal{H}}$ is said to be maximal monotone ([19]) if and only if G is monotone and its graph is not strictly contained in the graph of any other monotone operator.

For a maximal monotone operator $G: \mathcal{H} \rightrightarrows 2^{\mathcal{H}}$, we can define its resolvent $\text{Res}_{\alpha}^G: \mathcal{H} \rightarrow D(G)$ by $\text{Res}_{\alpha}^G := (I + \alpha G)^{-1}$ where $\alpha > 0$ is any constant.

Next, we list several important conclusions on Res_{α}^G :

(c1): Res_α^G is a single-valued operator.
 (c2): For any $\alpha > 0$, $G^{-1}(0) = \text{Fix}(\text{Res}_\alpha^G) := \{t \in \mathcal{H} : \text{Res}_\alpha^G(t) = t\}$.
 (c3): Res_α^G fulfills the following inequality, for all $s, t \in \mathcal{H}$,

$$\|\text{Res}_\alpha^G(s) - \text{Res}_\alpha^G(t)\|^2 \leq \langle \text{Res}_\alpha^G(s) - \text{Res}_\alpha^G(t), s - t \rangle.$$

(c4): For all $\alpha, \tau > 0$, we have, for all $s \in \mathcal{H}$,

$$\|\text{Res}_\alpha^G(s) - \text{Res}_\tau^G(s)\|^2 \leq \frac{\alpha - \tau}{\tau} \langle \text{Res}_\alpha^G(s) - \text{Res}_\tau^G(s), \text{Res}_\alpha^G(s) - s \rangle.$$

Let \mathcal{D} be a nonempty convex and closed subset of a real Hilbert space \mathcal{H} . Let $F : \mathcal{D} \rightarrow \mathcal{H}$ be a single-valued mapping. Recall that F is said to be

(f1): λ -inverse strongly monotone if $\langle F(s) - F(t), s - t \rangle \geq \lambda \|F(s) - F(t)\|^2$ for all $s, t \in \mathcal{D}$.
 (f2): monotone if $\langle F(s) - F(t), s - t \rangle \geq 0$ for all $s, t \in \mathcal{D}$.
 (f3): pseudomonotone if $\langle F(s), t - s \rangle \geq 0$ implies that $\langle F(t), t - s \rangle \geq 0$ for all $s, t \in \mathcal{D}$.
 (f4): quasimonotone if $\langle F(s), t - s \rangle > 0$ implies that $\langle F(t), t - s \rangle \geq 0$ for all $s, t \in \mathcal{D}$.

Recall that an operator $F : \mathcal{D} \rightarrow \mathcal{H}$ is said to be ν -Lipschitz continuous if $\|F(s) - F(t)\| \leq \nu \|s - t\|$, $\forall s, t \in \mathcal{D}$, where $\nu > 0$ is a constant. If $\nu = 1$, F is nonexpansive.

Let $U : \mathcal{D} \rightarrow \mathcal{H}$ be a λ -inverse strongly monotone operator. For the composition operator $\text{Res}_\alpha^G(I - \alpha U) : \mathcal{D} \rightarrow \mathcal{D}$, we have the following conclusions:

(c5): $\text{Res}_\alpha^G(I - \alpha U)$ is an averaged operator provided $\alpha \in (0, 2\lambda)$.
 (c6): $s^* \in (U + G)^{-1}(0) \Leftrightarrow s^* = \text{Res}_\alpha^G(I - \alpha U)(s^*)$ for all $\alpha \in (0, 2\lambda)$.

Let \mathcal{H} be a Hilbert space and $\mathcal{D} \subset \mathcal{H}$ be a closed convex set. A metric projection from \mathcal{H} onto \mathcal{D} , denoted by $\text{proj}_{\mathcal{D}}$ satisfies, for $z \in \mathcal{H}$, $\|z - \text{proj}_{\mathcal{D}}(z)\| \leq \|\hat{z} - z\|$, $\forall \hat{z} \in \mathcal{D}$. It is well known that $\text{proj}_{\mathcal{D}}$ has the following characteristic inequality ([49])

$$z \in \mathcal{H}, \langle z - \text{proj}_{\mathcal{D}}(z), \hat{z} - \text{proj}_{\mathcal{D}}(z) \rangle \leq 0, \forall \hat{z} \in \mathcal{D}. \quad (9)$$

In any Hilbert space \mathcal{H} , we have the following equality

$$\|tu + (1-t)u^\dagger\|^2 = t\|u\|^2 + (1-t)\|u^\dagger\|^2 - t(1-t)\|u - u^\dagger\|^2, \quad (10)$$

$\forall u, u^\dagger \in \mathcal{H}$ and $\forall t \in \mathbb{R}$.

Lemma 2.1 ([9]). *Assume that \mathcal{H} is a Hilbert space and $\mathcal{D} \subset \mathcal{H}$ is a nonempty, convex and closed set. Suppose that T is a nonexpansive self-mapping of \mathcal{D} . For a given sequence $\{t_n\} \subset \mathcal{D}$, $t_n \rightarrow z \in \mathcal{D}$ and $t_n - T(t_n) \rightarrow 0$ imply that $z \in \text{Fix}(T)$.*

3. Main results

In this section, we demonstrate an iterative algorithm and a relevant convergence theorem for solving (1) and (3). Let \mathcal{D} be a nonempty closed convex subset of a real Hilbert space \mathcal{H} . Assume that the following assumptions are fulfilled:

(a1): $G : \mathcal{H} \rightrightarrows 2^\mathcal{H}$ is a maximal monotone operator fulfilling $\text{D}(G) \subset \mathcal{D}$.
 (a2): $U : \mathcal{D} \rightarrow \mathcal{H}$ is a λ -inverse strongly-monotone operator.
 (a3): F is a quasimonotone operator on \mathcal{H} and F is ν -Lipschitz on \mathcal{D} .
 (a4): If $\{t_n\} \subset \mathcal{H}$ is a sequence satisfying $t_n \rightarrow t^\dagger$ and $\liminf_{n \rightarrow +\infty} \|F(t_n)\| = 0$, then $F(t^\dagger) = 0$.
 Set $\Delta := (U + G)^{-1}(0) \cap \text{DVI}(F, \mathcal{D})$. Suppose that $\Delta \neq \emptyset$ and the set $\{p \in \mathcal{D} : F(p) = 0\} \setminus \text{DVI}(F, \mathcal{D})$ is finite. Let ϑ, ϱ and κ be three constants in $(0, 1)$. Let $\{\gamma_n\} \subset (0, 2)$, $\{\alpha_n\} \subset (0, 1)$ and $\{\tau_n\} \subset (0, 1)$ be three real number sequences satisfying $0 < \liminf_{n \rightarrow \infty} \gamma_n \leq \lim_{n \rightarrow \infty} \gamma_n < 2$, $0 < \liminf_{n \rightarrow \infty} \tau_n \leq \lim_{n \rightarrow \infty} \tau_n < 1$ and $0 < \underline{\alpha} < \alpha_n < \bar{\alpha} < 2\lambda$ for all $n \geq 0$.

Now, we first present an iterative procedure for finding a point in Δ .

Algorithm 3.1. *Select an initial guess $t_0 \in \mathcal{D}$. Let $n = 0$.*

Step 1. Assume that t_n is obtained. Compute

$$s_n = (1 - \tau_n)t_n + \tau_n \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n, \quad (11)$$

and

$$r_n = \text{proj}_{\mathcal{D}}[s_n - \vartheta \varrho_n F(s_n)], \quad (12)$$

where $\varrho_n = \max\{1, \varrho, \varrho^2, \dots\}$ such that

$$\vartheta \varrho_n \|F(r_n) - F(s_n)\| \leq (1 - \kappa) \|r_n - s_n\|. \quad (13)$$

Step 2. (i) If $r_n = s_n$, then set $t_{n+1} = s_n$ and skip to step 1. (ii) If $r_n \neq s_n$, then compute

$$t_{n+1} = \text{proj}_{\mathcal{D}}(s_n - \kappa \gamma_n q_n), \quad (14)$$

where

$$q_n = \left(\frac{\|r_n - s_n\|}{\|p_n\|} \right)^2 p_n, \quad (15)$$

and

$$p_n = s_n - r_n + \vartheta \varrho_n F(r_n). \quad (16)$$

Set $n := n + 1$ and return to Step 1.

Proposition 3.1. *There exists ϱ_n satisfying (13). Meanwhile, $\frac{(1-\kappa)\varrho}{\vartheta\nu} < \varrho_n \leq \frac{1-\kappa}{\vartheta\nu}$.*

Proof. Since F is ν -Lipschitz, $\|F(r_n) - F(t_n)\| \leq \nu \|r_n - t_n\|$. Then, there exists ϱ_n such that $\vartheta \varrho_n \nu \|r_n - t_n\| \leq (1 - \kappa) \|r_n - t_n\|$ which implies that $\varrho_n \leq \frac{1-\kappa}{\vartheta\nu}$. By the definition of ϱ_n , ϱ_n/ϱ does not satisfy (13), that is, $\vartheta \frac{\varrho_n}{\varrho} \nu \|r_n - t_n\| \geq \vartheta \frac{\varrho_n}{\varrho} \|F(r_n) - F(t_n)\| > (1 - \kappa) \|r_n - t_n\|$. It follows that $\frac{(1-\kappa)\varrho}{\vartheta\nu} < \varrho_n$. Therefore, $\frac{(1-\kappa)\varrho}{\vartheta\nu} < \varrho_n \leq \frac{1-\kappa}{\vartheta\nu}$. \square

Proposition 3.2. (a) If $r_n = s_n$, then $s_n \in \text{VI}(F, \mathcal{D})$. (b) If $r_n \neq s_n$, then $p_n \neq 0$.

Proof. (a) If $r_n = \text{proj}_{\mathcal{D}}[s_n - \vartheta \varrho_n F(s_n)] = s_n$, utilizing (9) we attain that $\langle s_n - [s_n - \vartheta \varrho_n F(s_n)], p - s_n \rangle \geq 0, \forall p \in \mathcal{D}$, i.e., $\vartheta \varrho_n \langle F(s_n), p - s_n \rangle \geq 0, \forall p \in \mathcal{D}$. By Proposition 3.1, $\vartheta \varrho_n > \frac{(1-\kappa)\varrho}{\nu} > 0$. This together with the last inequality implies that $s_n \in \text{VI}(F, \mathcal{D})$. (b) Let $q^* \in \text{DVI}(F, \mathcal{D})$. Since $s_n \in \mathcal{D}$ and $r_n \in \mathcal{D}$, from (8), we obtain that $\langle F(s_n), s_n - q^* \rangle \geq 0$ and $\langle F(r_n), r_n - q^* \rangle \geq 0$. Thanks to (16), we gain

$$\begin{aligned} \langle p_n, s_n - q^* \rangle &= \langle s_n - r_n + \vartheta \varrho_n F(r_n), s_n - q^* \rangle \\ &= \langle s_n - r_n - \vartheta \varrho_n F(s_n), s_n - q^* \rangle + \vartheta \varrho_n \langle F(r_n), s_n - r_n \rangle \\ &\quad + \vartheta \varrho_n \langle F(s_n), s_n - q^* \rangle + \vartheta \varrho_n \langle F(r_n), r_n - q^* \rangle \\ &\geq \langle s_n - r_n - \vartheta \varrho_n F(s_n), s_n - q^* \rangle + \vartheta \varrho_n \langle F(r_n), s_n - r_n \rangle \\ &= \langle s_n - r_n - \vartheta \varrho_n (F(s_n) - F(r_n)), s_n - r_n \rangle \\ &\quad + \langle s_n - r_n - \vartheta \varrho_n F(s_n), r_n - q^* \rangle \\ &= \|s_n - r_n\|^2 - \vartheta \varrho_n \langle F(s_n) - F(r_n), s_n - r_n \rangle \\ &\quad + \langle s_n - r_n - \vartheta \varrho_n F(s_n), r_n - q^* \rangle. \end{aligned} \quad (17)$$

Taking into account (13), we have

$$\langle F(s_n) - F(r_n), s_n - r_n \rangle \leq \|F(s_n) - F(r_n)\| \|s_n - r_n\| \leq \frac{1 - \kappa}{\vartheta \varrho_n} \|r_n - s_n\|^2. \quad (18)$$

Since $q^* \in \mathcal{D}$, from (12) and (9), we deduce

$$\langle s_n - r_n - \vartheta \varrho_n F(s_n), r_n - q^* \rangle \geq 0. \quad (19)$$

According to (17)-(19), we acquire

$$\langle p_n, s_n - q^* \rangle \geq \kappa \|r_n - s_n\|^2. \quad (20)$$

If $r_n \neq s_n$, then from (20) we get $\langle p_n, s_n - q^* \rangle > 0$ which results in that $p_n \neq 0$. \square

In the sequel, we prove a convergence result.

Theorem 3.1. *The sequence $\{t_n\}$ defined by Algorithm 3.1 converges weakly to a point in $(U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$.*

Proof. Let $q^* \in \Delta$. Take into account of (14) and (15), we have

$$\begin{aligned} \|t_{n+1} - q^*\|^2 &= \|\text{proj}_{\mathcal{D}}(s_n - \kappa\gamma_n q_n) - \text{proj}_{\mathcal{D}}(q^*)\|^2 \\ &\leq \|s_n - q^* - \kappa\gamma_n q_n\|^2 \\ &= \|s_n - q^*\|^2 - 2\kappa\gamma_n \langle q_n, s_n - q^* \rangle + (\kappa\gamma_n)^2 \|q_n\|^2 \\ &= \|s_n - q^*\|^2 - 2\kappa\gamma_n \frac{\|r_n - s_n\|^2}{\|p_n\|^2} \langle p_n, s_n - q^* \rangle + (\kappa\gamma_n)^2 \frac{\|r_n - s_n\|^4}{\|p_n\|^2}. \end{aligned} \quad (21)$$

In view of (20) and (21), we receive

$$\|t_{n+1} - q^*\|^2 \leq \|s_n - q^*\|^2 - \kappa^2(2 - \gamma_n)\gamma_n \frac{\|r_n - s_n\|^4}{\|p_n\|^2}. \quad (22)$$

By (c6), we obtain $q^* = \text{Res}_{\alpha_n}^G(I - \alpha_n U)(q^*)$, $\forall n \geq 0$. Furthermore, $\text{Res}_{\alpha_n}^G(I - \alpha_n U)$ is nonexpansive. By (10) and (11), we have

$$\begin{aligned} \|s_n - q^*\|^2 &= \|(1 - \tau_n)(t_n - q^*) + \tau_n(\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - q^*)\|^2 \\ &= (1 - \tau_n)\|t_n - q^*\|^2 - \tau_n(1 - \tau_n)\|t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\|^2 \\ &\quad + \tau_n\|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)q^*\|^2 \\ &\leq (1 - \tau_n)\|t_n - q^*\|^2 + \tau_n\|t_n - q^*\|^2 \\ &\quad - \tau_n(1 - \tau_n)\|t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\|^2 \\ &= \|t_n - q^*\|^2 - \tau_n(1 - \tau_n)\|t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\|^2. \end{aligned} \quad (23)$$

Combining (22) and (23), we get

$$\begin{aligned} \|t_{n+1} - q^*\|^2 &\leq \|t_n - q^*\|^2 - \tau_n(1 - \tau_n)\|t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\|^2 \\ &\quad - \kappa^2(2 - \gamma_n)\gamma_n \frac{\|r_n - s_n\|^4}{\|p_n\|^2}. \end{aligned} \quad (24)$$

By (24), we have $\|t_{n+1} - q^*\| \leq \|t_n - q^*\|$ which leads to that $\lim_{n \rightarrow \infty} \|t_n - q^*\|$ exists. Thus, we have the following results:

- (b1): the sequence $\{t_n\}$ is bounded and so is $\{F(t_n)\}$ due to the Lipschitz continuity of F .
- (b2): the sequence $\{s_n\}$ is bounded by (23) and so is $\{F(s_n)\}$.
- (b3): the sequence $\{r_n\}$ is bounded because of $\|r_n\| \leq \|s_n\| + \vartheta\varrho_n\|F(s_n)\|$ and so is $\{F(r_n)\}$.
- (b4): the sequence $\{p_n\}$ is bounded by (16).

Further, by (24), we deduce

$$\begin{aligned} \tau_n(1 - \tau_n)\|t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\|^2 + \kappa^2(2 - \gamma_n)\gamma_n \frac{\|r_n - s_n\|^4}{\|p_n\|^2} \\ \leq \|t_n - q^*\|^2 - \|t_{n+1} - q^*\|^2 \rightarrow 0. \end{aligned} \quad (25)$$

By the assumptions, we have $\lim_{n \rightarrow \infty} \tau_n(1 - \tau_n) > 0$ and $\lim_{n \rightarrow \infty} (2 - \gamma_n)\gamma_n > 0$. This together with (25) implies that

$$\lim_{n \rightarrow \infty} \|t_n - \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\| = 0 \quad (26)$$

and

$$\lim_{n \rightarrow \infty} \frac{\|r_n - s_n\|^2}{\|p_n\|} = 0. \quad (27)$$

Let $\tau^\dagger > 0$ be any constant. Then, we have

$$\begin{aligned} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \tau^\dagger U)t_n\| \\ \leq \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \alpha_n U)t_n\| \\ + \|\text{Res}_{\tau^\dagger}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \tau^\dagger U)t_n\| \\ \leq \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \alpha_n H)t_n\| + |\alpha_n - \tau^\dagger| \|U(t_n)\|. \end{aligned} \quad (28)$$

Using (c4), we attain

$$\begin{aligned} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \alpha_n U)t_n\|^2 \\ \leq \frac{\alpha_n - \tau^\dagger}{\tau^\dagger} \langle \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \alpha_n U)t_n, \\ \text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - (I - \alpha_n U)t_n \rangle \\ \leq \frac{|\alpha_n - \tau^\dagger|}{\tau^\dagger} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \alpha_n U)t_n\| \\ \times \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - (I - \alpha_n U)t_n\|, \end{aligned}$$

which results in that

$$\begin{aligned} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \alpha_n U)t_n\| \\ \leq \frac{|\alpha_n - \tau^\dagger|}{\tau^\dagger} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - (I - \alpha_n U)t_n\|. \end{aligned} \quad (29)$$

Based on (28) and (29), we receive

$$\begin{aligned} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - \text{Res}_{\tau^\dagger}^G(I - \tau^\dagger U)t_n\| \leq |\alpha_n - \tau^\dagger| \|U(t_n)\| \\ + \frac{|\alpha_n - \tau^\dagger|}{\tau^\dagger} \|\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - (I - \alpha_n U)t_n\|. \end{aligned} \quad (30)$$

Since U is λ -inverse strongly-monotone, U is $1/\lambda$ -Lipschitz continuous. By the boundedness of $\{t_n\}$, we deduce $\{U(t_n)\}$ is bounded. Hence, $\{\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n\}$ is bounded.

Next, we show that $\omega_w(t_n) \subset \Delta$. First, we prove $\omega_w(t_n) \subset (U + G)^{-1}(0)$. Pick up any $t^\dagger \in \omega_w(t_n)$.

Since $\{t_n\}$ and $\{\alpha_n\}$ are bounded, there exists a common subsequence $\{n_i\} \subset \{n\}$ fulfilling $t_{n_i} \rightharpoonup t^\dagger \in \mathcal{D}$ and $\alpha_{n_i} \rightarrow \alpha^\dagger \in (0, 2\lambda)$ as $i \rightarrow \infty$.

Selecting $\tau^\dagger = \alpha^\dagger$, from (30), we obtain

$$\begin{aligned} \|\text{Res}_{\alpha_{n_i}}^G(I - \alpha_{n_i} U)t_{n_i} - \text{Res}_{\alpha^\dagger}^G(I - \alpha^\dagger U)t_{n_i}\| \leq |\alpha_{n_i} - \alpha^\dagger| \|U(t_{n_i})\| \\ + \frac{|\alpha_{n_i} - \alpha^\dagger|}{\alpha^\dagger} \|\text{Res}_{\alpha_{n_i}}^G(I - \alpha_{n_i} U)t_{n_i} - (I - \alpha_{n_i} U)t_{n_i}\| \rightarrow 0. \end{aligned}$$

This together with (26) implies that

$$\lim_{i \rightarrow \infty} \|t_{n_i} - \text{Res}_{\alpha^\dagger}^G(I - \alpha^\dagger U)t_{n_i}\| = 0. \quad (31)$$

Now, we have the facts that $t_{n_i} \rightharpoonup t^\dagger \in \mathcal{D}$ and $\text{Res}_{\alpha^\dagger}^G(I - \alpha^\dagger U)$ is nonexpansive. Applying Lemma 2.1 to (31), we derive that $t^\dagger \in \text{Fix}(\text{Res}_{\alpha^\dagger}^G(I - \alpha^\dagger U)) = (U + G)^{-1}(0)$. Hence, $\omega_w(t_n) \subset (U + G)^{-1}(0)$. Next, we show $t^\dagger \in \text{VI}(F, \mathcal{D})$. According to (11), we get $s_n - t_n = \tau_n(\text{Res}_{\alpha_n}^G(I - \alpha_n U)t_n - t_n)$. Then, by (26), we have

$$\lim_{n \rightarrow \infty} \|t_n - s_n\| = 0. \quad (32)$$

With the help of (14) and (15), we have

$$\|t_{n+1} - s_n\| = \|\text{proj}_{\mathcal{D}}(s_n - \kappa\gamma_n q_n) - \text{proj}_{\mathcal{D}}(s_n)\| \leq \kappa\gamma_n \|q_n\| \leq \kappa\gamma_n \frac{\|r_n - s_n\|^2}{\|p_n\|}. \quad (33)$$

It follows from (27) and (33) that $\lim_{n \rightarrow \infty} \|s_n - t_{n+1}\| = 0$. Hence, from (32), we receive

$$\lim_{n \rightarrow \infty} \|t_{n+1} - t_n\| = 0. \quad (34)$$

By the boundedness of $p_n = t_n - r_n + \vartheta \varrho_n F(r_n)$, thanks to (27), we attain

$$\lim_{n \rightarrow \infty} \|r_n - s_n\| = 0 \quad (35)$$

which together with the Lipschitz continuity of F results in that

$$\lim_{n \rightarrow \infty} \|F(r_n) - F(s_n)\| = 0. \quad (36)$$

By (9) and (11), we have

$$\langle s_n - \vartheta \varrho_n F(s_n) - r_n, z - r_n \rangle \leq 0, \quad \forall z \in \mathcal{D}.$$

Thus,

$$\langle F(s_n), z - s_n \rangle \geq \frac{1}{\vartheta \varrho_n} \langle s_n - r_n, z - r_n \rangle + \langle F(s_n), r_n - s_n \rangle, \quad \forall z \in \mathcal{D}. \quad (37)$$

Observing that $\{s_n\}$, $\{r_n\}$ and $\{F(s_n)\}$ are bounded, from (35) and (37), we acquire

$$\underline{\lim}_{i \rightarrow +\infty} \langle F(s_{n_i}), z - s_{n_i} \rangle \geq 0, \quad \forall z \in \mathcal{D}. \quad (38)$$

Next, we divide two cases to prove that $t^\dagger \in \text{VI}(F, \mathcal{D})$: (a) $\underline{\lim}_{i \rightarrow +\infty} \|F(s_{n_i})\| = 0$ and (b) $\underline{\lim}_{i \rightarrow +\infty} \|F(s_{n_i})\| > 0$.

For Case (a), since $t_{n_i} \rightharpoonup t^\dagger$, from (32), we have $s_{n_i} \rightharpoonup t^\dagger$. This together with condition (a4) implies that $F(t^\dagger) = 0$.

Now, we study Case (b). We can find an integer $k > 0$ such that $\|F(s_{n_i})\| > 0$ for all $i \geq k$. In terms of (38), we assert

$$\underline{\lim}_{i \rightarrow +\infty} \langle F(s_{n_i}) / \|F(s_{n_i})\|, z - s_{n_i} \rangle \geq 0, \quad \forall z \in \mathcal{D}. \quad (39)$$

Let $\{\beta_j\}$ be a positive real number sequence satisfying $\beta_{j+1} < \beta_j$ and $\beta_j \rightarrow 0$ as $j \rightarrow +\infty$. With the help of (39), there is $\{n_{i_j}\} \subset \{n_i\}$ fulfilling $n_{i_j} \geq k, \forall j \geq 0$ and

$$\forall z \in \mathcal{D}, \langle F(s_{n_{i_j}}) / \|F(s_{n_{i_j}})\|, z - s_{n_{i_j}} \rangle + \beta_j > 0, \quad \forall j \geq 0,$$

which indicates that

$$\forall z \in \mathcal{D}, \langle F(s_{n_{i_j}}), z - s_{n_{i_j}} \rangle + \beta_j \|F(s_{n_{i_j}})\| > 0, \quad \forall j \geq 0. \quad (40)$$

Set $\hat{\beta}_j = F(s_{n_{i_j}}) / \|F(s_{n_{i_j}})\|^2$ for all $j \geq 0$ which implies that $\langle F(s_{n_{i_j}}), \hat{\beta}_j \rangle = 1$ for all $j \geq 0$. Thanks to (40), we obtain

$$\forall z \in \mathcal{D}, \langle F(s_{n_{i_j}}), \beta_j \hat{\beta}_j \|F(s_{n_{i_j}})\| + z - s_{n_{i_j}} \rangle > 0, \quad \forall j \geq 0. \quad (41)$$

Based on (41) and the quasimonotonicity of F , we assert

$$\forall z \in \mathcal{D}, \langle F(z + \beta_j \hat{\beta}_j \|F(s_{n_{i_j}})\|), \beta_j \hat{\beta}_j \|F(s_{n_{i_j}})\| + z - s_{n_{i_j}} \rangle \geq 0, \quad \forall j \geq 0. \quad (42)$$

Notice that $\lim_{j \rightarrow +\infty} \beta_j \hat{\beta}_j \|F(s_{n_{i_j}})\| = \lim_{j \rightarrow +\infty} \beta_j = 0$. Using the Lipschitz continuity of F , we have $F(z + \beta_j \hat{\beta}_j \|F(s_{n_{i_j}})\|) \rightarrow F(z)$ as $j \rightarrow +\infty$. Letting $j \rightarrow +\infty$ in (42), we deduce $\langle F(z), z - t^\dagger \rangle \geq 0, \forall z \in \mathcal{D}$, which implies that $t^\dagger \in \text{DVI}(F, \mathcal{D})$. According to Case (a) and Case (b), we conclude that $\omega_w(t_n) \subset (\{x \in \mathcal{D} : F(x) = 0\} \cup \text{DVI}(F, \mathcal{D})) \subset \text{VI}(F, \mathcal{D})$. Therefore, $\omega_w(t_n) \subset (U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$.

Next, we prove $\{t_n\}$ has at most one weak cluster point in $\text{DVI}(F, \mathcal{D})$. Assume \tilde{t} and \hat{t} are two weak cluster points of $\{t_n\}$ in $\text{DVI}(F, \mathcal{D})$. Then, there are $\{t_{n_i}\} \subset \{t_n\}$ and $\{t_{n_j}\} \subset \{t_n\}$ satisfying $t_{n_i} \rightharpoonup \tilde{t}(i \rightarrow \infty)$ and $t_{n_j} \rightharpoonup \hat{t}(j \rightarrow \infty)$. It is obviously that

$$2\langle t_n, \tilde{t} - \hat{t} \rangle = \|t_n - \hat{t}\|^2 - \|t_n - \tilde{t}\|^2 + \|\tilde{t}\|^2 - \|\hat{t}\|^2, \quad \forall n \geq 0,$$

which results in that $\lim_{n \rightarrow +\infty} \langle t_n, \tilde{t} - \hat{t} \rangle$ exists. Therefore,

$$\lim_{i \rightarrow +\infty} \langle t_{n_i}, \tilde{t} - \hat{t} \rangle = \lim_{j \rightarrow +\infty} \langle t_{n_j}, \tilde{t} - \hat{t} \rangle \quad (43)$$

Taking into account $t_{n_i} \rightharpoonup \tilde{t}$ and $t_{n_j} \rightharpoonup \hat{t}$, by (44), we receive

$$\langle \tilde{t}, \tilde{t} - \hat{t} \rangle = \langle \hat{t}, \tilde{t} - \hat{t} \rangle$$

which yields that $\tilde{t} = \hat{t}$. So, $\{t_n\}$ has no more than one weak cluster point in $\text{DVI}(F, \mathcal{D})$. Since the set $\{x \in \mathcal{D} : F(x) = 0\} \setminus \text{DVI}(F, \mathcal{D})$ is finite, we conclude that $\{t_n\}$ has only finite weak cluster points in $(U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$. Suppose that $t^{(1)}, t^{(2)}, \dots, t^{(m)}$ are weak cluster points of $\{t_n\}$ in $(U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$. Set $I = \{1, 2, \dots, m\}$ and

$$d = \min\{\|t^{(r)} - t^{(s)}\|/3, r, s \in I, r \neq s\}. \quad (44)$$

For $t^{(r)}, r \in I$, there is $\{t_{n_i}^r\} \subset \{t_n\}$ satisfying $t_{n_i}^r \rightharpoonup t^{(r)}$ as $i \rightarrow +\infty$. Then,

$$\lim_{i \rightarrow +\infty} \langle t_{n_i}^r, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle = \langle t^{(r)}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle, \forall s \in I. \quad (45)$$

Note that

$$\begin{aligned} \langle t^{(r)}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle &= \frac{\|t^{(r)} - t^{(s)}\|}{2} + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \\ &> d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|}, \forall s \neq r. \end{aligned} \quad (46)$$

Combining (45) and (46), there is a positive integer $\mathbb{N}_i^r > 0$ fulfilling for all $i \geq \mathbb{N}_i^r$,

$$t_{n_i}^r \in \left\{ \hat{t} : \langle \hat{t}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \right\}, s \in I, s \neq r. \quad (47)$$

Write

$$\Theta_r = \bigcap_{s=1, s \neq r}^m \left\{ \hat{t} : \langle \hat{t}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \right\}. \quad (48)$$

Combining (47) with (48), we deduce that $t_{n_i}^r \in \Theta_r$ for all $i \geq \max\{\mathbb{N}_i^r, r \in I\}$.

Next we show that $t_n \in \bigcup_{r=1}^m \Theta_r$ for large enough n . Suppose that there is $\{t_{n_j}\} \subset \{t_n\}$ verifying $t_{n_j} \notin \bigcup_{r=1}^m \Theta_r$. According to the boundedness of $\{t_{n_j}\}$, there exists a subsequence of $\{t_{n_j}\}$, without loss of generality, still denoted by $\{t_{n_j}\}$, which converges weakly to \hat{v} . Hence $t_{n_j} \notin \Theta_r$ for any $r \in I$. Then, there is a subsequence $\{t_{n_{j_s}}\}$ of $\{t_{n_j}\}$ such that $\forall s \geq 0$,

$$t_{n_{j_s}} \notin \left\{ \hat{t} : \langle \hat{t}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \right\}, s \in I, s \neq r. \quad (49)$$

So,

$$\hat{v} \notin \left\{ \hat{t} : \langle \hat{t}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \right\}, s \in I, s \neq r,$$

which results in that $\hat{v} \neq t^{(r)} (\forall r \in I)$. It is impossible. Thus, there is an integer N_1 large enough such that $t_n \in \bigcup_{r=1}^m \Theta_r$ for all $n \geq N_1$.

Finally, we demonstrate that $\{t_n\}$ has the unique weak cluster point in $(U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$. Assume that $m \geq 2$. From (34), there exists a positive integer $N_2 \geq N_1$ such that $\|t_{n+1} - t_n\| < d$ for all $n \geq N_2$. Then, there exists $p \geq N_2$ such that $t_p \in \Theta_r$ and $t_{p+1} \in \Theta_s$, where $r, s \in I$ and $m \geq 2$, that is,

$$t_p \in \Theta_r = \bigcap_{s=1, s \neq r}^m \left\{ \hat{t} : \langle \hat{t}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \right\}$$

and

$$t_{p+1} \in \Theta_s = \bigcap_{r=1, r \neq s}^m \left\{ \hat{t} : \langle \hat{t}, \frac{t^{(s)} - t^{(r)}}{\|t^{(s)} - t^{(r)}\|} \rangle > d + \frac{\|t^{(s)}\|^2 - \|t^{(r)}\|^2}{2\|t^{(s)} - t^{(r)}\|} \right\}.$$

Thus, we have

$$\langle t_p, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > d + \frac{\|t^{(r)}\|^2 - \|t^{(s)}\|^2}{2\|t^{(r)} - t^{(s)}\|} \quad (50)$$

and

$$\langle t_{p+1}, \frac{t^{(s)} - t^{(r)}}{\|t^{(s)} - t^{(r)}\|} \rangle > d + \frac{\|t^{(s)}\|^2 - \|t^{(r)}\|^2}{2\|t^{(s)} - t^{(r)}\|}. \quad (51)$$

Thanks to (50) and (51), we acquire

$$\langle t_p - t_{p+1}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle > 2d. \quad (52)$$

Note that

$$\|t_{p+1} - t_p\| < d. \quad (53)$$

By virtue of (52) and (53), we receive

$$2d < \langle t_p - t_{p+1}, \frac{t^{(r)} - t^{(s)}}{\|t^{(r)} - t^{(s)}\|} \rangle \leq \|t_p - t_{p+1}\| < d.$$

It leads to a contradiction. Thus, $\{t_n\}$ has a unique weak cluster point in $(U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$. Therefore, $\{t_n\}$ converges weakly to a point in $(U + G)^{-1}(0) \cap \text{VI}(F, \mathcal{D})$. \square

4. Concluding remarks

In this paper, we investigate iterative schemes for finding a common solution of quasi-variational inclusion (1) and quasimonotone variational inequality (3) in a Hilbert space \mathcal{H} . We present an iterative scheme $\{t_n\}$ generated by Algorithm 3.1 which consists of resolvent operator step (11), extragradient step (12)-(14) and self-adaptive search step (13). Under several appropriate conditions, we show that the proposed scheme $\{t_n\}$ defined by Algorithm 3.1 converges weakly to some common solution of quasi-variational inclusion (1) and quasimonotone variational inequality (3).

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