

END POINT OF SOME GENERALIZED WEAKLY CONTRACTIVE MULTIVALUED MAPPINGS

M. Eslamian¹, A. Abkar²

In this paper, we prove the existence of a common end point for a pair of multivalued mappings satisfying a new generalized weakly contractive condition in a complete metric space. Our result generalizes some results of Dutta and Choudhury (2008), and Zhang, Song (2010).

Keywords: : end point, weakly contractive mapping, multivalued mapping

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1. Introduction

Banach contraction principle is a remarkable result in metric fixed point theory. Over the years, it has been generalized in different directions and spaces by mathematicians.

In 1997, Alber and Guerre-Delabriere [1] introduced the concept of weak contraction in the following way:

Definition 1.1. *Let (E, d) be a metric space. A mapping $T : E \longrightarrow E$ is said to be weakly contractive provided that*

$$d(Tx, Ty) \leq d(x, y) - \varphi(d(x, y))$$

where $x, y \in E$ and $\varphi : [0, \infty) \longrightarrow [0, \infty)$ is a continuous nondecreasing function such that $\varphi(t) = 0$ if and only if $t = 0$.

Using the concept of weakly contractiveness, they succeeded to establish the existence of fixed points for such mappings in Hilbert spaces. Later on Rhoades [10] proved that the result of [1] is also valid in complete metric spaces. Rhoades [10] also proved the following fixed point theorem which is a generalization of the Banach contraction principle, because it contains contractions as a special case when we assume that $\varphi(t) = (1 - k)t$ for some $0 < k < 1$.

Theorem 1.1. *Let (E, d) be a complete metric space and let $T : E \longrightarrow E$ be a weakly contractive mapping. Then T has a fixed point.*

Since then, fixed point theory for single valued, as well as for multivalued weakly contractive type mappings was studied by many authors; see [2-9], and [11-13].

¹, Corresponding author, Department of Applied Mathematics, University of Science and Technology, Behshahr, Iran. Email: mhmdeslamian@gmail.com

²Department of Mathematics, Imam Khomeini International University, Qazvin 34149, Iran. Email: abkar@ikiu.ac.ir

Let (E, d) be a metric space, and let $B(E)$ denote the family of all nonempty bounded subsets of E . For $A, B \in B(E)$, define the distance between A and B by

$$D(A, B) = \inf\{d(a, b) : a \in A, b \in B\},$$

and the diameter of A and B by

$$\delta(A, B) = \sup\{d(a, b) : a \in A, b \in B\}.$$

Let $T : E \longrightarrow B(E)$ be a multivalued operator, then an element $x \in E$ is said to be a *fixed point* of T provided that $x \in T(x)$ and it is called an *end point* of T if $T(x) = \{x\}$. The purpose of this paper is to prove the existence of a common end point for a pair of multivalued mappings satisfying a new generalized weakly contractive condition in a complete metric space. Our result generalizes and extends some results of Dutta and Choudhury [6], and Zhang, Song [13].

2. Main Results

In this sequel, we denote by Φ the class of all mappings $\varphi : [0, \infty) \longrightarrow [0, \infty)$ satisfying the following conditions:

- (i) $\varphi(t) = 0$ if and only if $t = 0$;
- (ii) φ is a lower semi continuous function ;
- (iii) for any sequence $\{t_n\}$ with $\lim_{n \rightarrow \infty} t_n = 0$, there exist $k \in (0, 1)$ and $n_0 \in \mathbb{N}$, such that $\varphi(t_n) \geq kt_n$ for each $n \geq n_0$.

Examples of such mappings are $\varphi(x) = kx$ for $0 < k < 1$ and $\varphi(x) = \ln(x + 1)$ (see also [9]). Let Ω denote the class of all mappings $f : [0, \infty) \longrightarrow [0, \infty)$ satisfying the following conditions:

- (i) $f(t) = 0$ if and only if $t = 0$;
- (ii) f is non-decreasing;
- (iii) f is continuous;
- (iv) $f(x + y) \leq f(x) + f(y)$.

Finally, let Ψ denote the class of mappings $\psi : [0, \infty) \longrightarrow [0, \infty)$ which are continuous and non-decreasing with $\psi(t) = 0$ if and only if $t = 0$.

Let (E, d) be a metric space, and let $T, S : E \longrightarrow B(E)$ be two multivalued mappings, we define

$$M(x, y) = \max \left\{ d(x, y), \delta(Tx, x), \delta(y, Sy), \frac{D(y, Tx) + D(x, Sy)}{2} \right\},$$

and

$$N(x, y) = \min\{D(y, Tx), D(x, Sy)\}.$$

We now state the main result of this paper.

Theorem 2.1. *Let (E, d) be a complete metric space, and let $T, S : E \longrightarrow B(E)$ be two mappings such that for all $x, y \in E$*

$$f(\delta(Tx, Sy)) \leq f(M(x, y)) - \varphi(f(M(x, y))) + \psi(N(x, y)) \quad (2.1)$$

where $\varphi \in \Phi$, $\psi \in \Psi$ and $f \in \Omega$. Then S and T have a common end point $z \in E$, i.e., $Sz = Tz = \{z\}$.

Proof. We construct a sequence $\{x_n\}$ as follows. Take $x_0 \in E$ and for $n \geq 1$ we choose $x_{2n+1} \in Tx_{2n} := A_{2n}$ and $x_{2n+2} \in Sx_{2n+1} := A_{2n+1}$. Now we have

$$\begin{aligned}
M(x_{2n}, x_{2n+1}) &= \max\{d(x_{2n}, x_{2n+1}), \delta(Tx_{2n}, x_{2n}), \delta(Sx_{2n+1}, x_{2n+1}), \\
&\quad \frac{D(Tx_{2n}, x_{2n+1}) + D(Sx_{2n+1}, x_{2n})}{2}\} \\
&\leq \max\{\delta(A_{2n-1}, A_{2n}), \delta(A_{2n-1}, A_{2n}), \delta(A_{2n+1}, A_{2n}), \\
&\quad \frac{D(Tx_{2n}, x_{2n+1}) + D(Sx_{2n+1}, x_{2n})}{2}\} \\
&\leq \max\{\delta(A_{2n-1}, A_{2n}), \delta(A_{2n+1}, A_{2n}), \frac{\delta(A_{2n+1}, A_{2n-1})}{2}\} \\
&\leq \max\{\delta(A_{2n-1}, A_{2n}), \delta(A_{2n+1}, A_{2n}), \\
&\quad \frac{\delta(A_{2n}, A_{2n-1}) + \delta(A_{2n}, A_{2n+1})}{2}\} \\
&= \max\{\delta(A_{2n-1}, A_{2n}), \delta(A_{2n+1}, A_{2n})\}
\end{aligned}$$

and

$$N(x_{2n}, x_{2n+1}) = \min\{D(Tx_{2n}, x_{2n+1}), D(Sx_{2n+1}, x_{2n})\} = 0.$$

By assumption

$$\begin{aligned}
f(\delta(A_{2n}, A_{2n+1})) &= f(\delta(Tx_{2n}, Sx_{2n+1})) \\
&\leq f(M(x_{2n}, x_{2n+1})) - \varphi(f(M(x_{2n}, x_{2n+1}))) + \psi(N(x_{2n}, x_{2n+1})) \\
&= f(M(x_{2n}, x_{2n+1})) - \varphi(f(M(x_{2n}, x_{2n+1}))) \\
&\leq f(M(x_{2n}, x_{2n+1})).
\end{aligned}$$

Since f is non-decreasing, we have

$$\delta(A_{2n}, A_{2n+1}) \leq M(x_{2n}, x_{2n+1}).$$

Now, if $\delta(A_{2n-1}, A_{2n}) < \delta(A_{2n+1}, A_{2n})$ then

$$M(x_{2n}, x_{2n+1}) \leq \delta(A_{2n+1}, A_{2n}),$$

from which we obtain

$$M(x_{2n}, x_{2n+1}) = \delta(A_{2n+1}, A_{2n}) > \delta(A_{2n-1}, A_{2n}) \geq 0,$$

and

$$\begin{aligned}
f(\delta(A_{2n}, A_{2n+1})) &= f(\delta(Tx_{2n}, Sx_{2n+1})) \\
&\leq f(M(x_{2n}, x_{2n+1})) - \varphi(f(M(x_{2n}, x_{2n+1}))) + \psi(N(x_{2n}, x_{2n+1})) \\
&= f(M(x_{2n}, x_{2n+1})) - \varphi(f(M(x_{2n}, x_{2n+1}))) \\
&< f(M(x_{2n}, x_{2n+1})) = f(\delta(A_{2n+1}, A_{2n}))
\end{aligned}$$

which is a contradiction. So we have

$$\delta(A_{2n+1}, A_{2n}) \leq M(x_{2n}, x_{2n+1}) \leq \delta(A_{2n}, A_{2n-1}).$$

Similarly we obtain

$$\delta(A_{2n+1}, A_{2n+2}) \leq M(x_{2n+1}, x_{2n+2}) \leq \delta(A_{2n+1}, A_{2n+2}).$$

Therefore the sequence $\{\delta(A_n, A_{n+1})\}$ is monotone decreasing and bounded below. So there exists $r \geq 0$ such that

$$\lim_{n \rightarrow \infty} \delta(A_n, A_{n+1}) = \lim_{n \rightarrow \infty} M(x_n, x_{n+1}) = r.$$

We now claim that $r = 0$. In fact taking upper limits as $n \rightarrow \infty$ on either sides of the inequality

$$\begin{aligned} f(\delta(A_{2n}, A_{2n+1})) &= f(\delta(Tx_{2n}, Sx_{2n+1})) \\ &\leq f(M(x_{2n}, x_{2n+1})) - \varphi(f(M(x_{2n}, x_{2n+1}))) + \psi(N(x_{2n}, x_{2n+1})) \\ &= f(M(x_{2n}, x_{2n+1})) - \varphi(f(M(x_{2n}, x_{2n+1}))) \end{aligned}$$

we have

$$f(r) \leq f(r) - \varphi f(r)$$

which is a contradiction unless $r = 0$. Thus $\lim_{n \rightarrow \infty} \delta(A_n, A_{n+1}) = 0$ and hence $\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = 0$. Now we shall prove that $\{x_n\}$ is a Cauchy sequence. Indeed, Since $\lim_{n \rightarrow \infty} f(M(x_n, x_{n+1})) = 0$ by the property of φ there exist $0 < k < 1$ and $n_0 \in \mathbb{N}$, such that $\varphi(f(M(x_n, x_{n+1}))) \geq kf(M(x_n, x_{n+1}))$ for all $n > n_0$. On the other hand, for any given $\varepsilon > 0$, we can choose $\eta > 0$ in such a way that $f(\eta) \leq \frac{k}{1-k}f(\varepsilon)$. Moreover, there exists n_0 such that $\delta(A_n, A_{n-1}) \leq \eta$ for each $n > n_0$. For any natural number $m > n > n_0$ if n is even, we have

$$\begin{aligned} f(\delta(A_n, A_{n+1})) &\leq f(\delta(Tx_n, Sx_{n+1})) \\ &\leq f(M(x_n, x_{n+1})) - \varphi(f(M(x_n, x_{n+1}))) + \psi(N(x_n, x_{n+1})) \\ &\leq (1-k)f(M(x_n, x_{n+1})) \leq (1-k)f(\delta(A_n, A_{n-1})). \end{aligned}$$

By this inequality, we get for $l > n$

$$f(\delta(A_l, A_{l-1})) \leq (1-k)f(\delta(A_{l-1}, A_{l-2})) \leq \cdots \leq (1-k)^{l-n}f(\delta(A_n, A_{n-1}))$$

Therefore we have

$$\begin{aligned} f(\delta(A_n, A_m)) &\leq f(\delta(A_n, A_{n+1}) + \delta(A_{n+1}, A_{n+2}) + \cdots + \delta(A_{m-1}, A_m)) \\ &\leq f(\delta(A_n, A_{n+1})) + f(\delta(A_{n+1}, A_{n+2})) + \cdots + f(\delta(A_{m-1}, A_m)) \\ &\leq (1-k)f(\delta(A_n, A_{n-1})) + \cdots \\ &\quad + (1-k)^{m-n-1}f(\delta(A_n, A_{n-1})) + (1-k)^{m-n}f(\delta(A_n, A_{n-1})) \\ &= \frac{(1-k) - (1-k)^{m-n+1}}{1 - (1-k)}f(\delta(A_n, A_{n-1})) \\ &< \frac{1-k}{k}f(\delta(A_n, A_{n-1})) \leq \frac{1-k}{k}f(\eta) < f(\varepsilon). \end{aligned}$$

Now, by the nondecreasingness of f we obtain $\delta(A_n, A_m) < \varepsilon$. From the construction of the sequence $\{x_n\}$, it follows that the same conclusion holds for $\{x_n\}$, i.e. for each $\varepsilon > 0$ there exist n_0 such that for any natural numbers $m > n > n_0$, $d(x_n, x_m) < \varepsilon$. This shows that $\{x_n\}$ is a Cauchy sequence. Notice that E is complete, hence $\{x_n\}$ is convergent. Let us denote its limit by $\lim_{n \rightarrow \infty} x_n = z$ for some $z \in E$. Now we

prove that $\delta(Tz, z) = 0$. Suppose that this is not true, then $\delta(Tz, z) > 0$. For large enough n , we claim that the following equations hold true:

$$M(z, x_{2n+1}) = \max\{d(z, x_{2n+1}), \delta(z, Tz), \delta(Sx_{2n+1}, x_{2n+1}), \frac{D(Tz, x_{2n+1}) + D(Sx_{2n+1}, z)}{2}\} = \delta(z, Tz).$$

Indeed, since

$$\delta(Sx_{2n+1}, x_{2n+1}) \leq \delta(A_{2n+1}, A_{2n}) \longrightarrow 0,$$

and

$$\begin{aligned} \lim_{n \rightarrow \infty} \frac{D(Tz, x_{2n+1}) + D(Sx_{2n+1}, z)}{2} \\ \leq \lim_{n \rightarrow \infty} \frac{\delta(Tz, z) + d(z, x_{2n+1}) + \delta(Sx_{2n+1}, x_{2n+1}) + d(x_{2n+1}, z)}{2} \\ = \frac{\delta(Tz, z)}{2}, \end{aligned}$$

it follows that there exists $k \in \mathbb{N}$ such that $M(z, x_{2n+1}) = \delta(z, Tz)$ for $n > k$. Note that

$$\begin{aligned} f(\delta(Tz, x_{2n+2})) &\leq f(\delta(Tz, Sx_{2n+1})) \\ &\leq f(M(z, x_{2n+1})) - \varphi(f(M(z, x_{2n+1})) - \psi(N(z, x_{2n+1}))). \end{aligned}$$

Letting $n \rightarrow \infty$, we have

$$f(\delta(Tz, z)) \leq f(\delta(Tz, z)) - \varphi(f(\delta(Tz, z)))$$

i.e., $\varphi(f(\delta(Tz, z))) \leq 0$. This is a contradiction, therefore $\delta(Tz, z) = 0$ i.e., $Tz = \{z\}$. And since

$$\begin{aligned} M(z, z) &= \max\{d(z, z), \delta(Tz, z), \delta(z, Sz), \frac{D(Tz, z) + D(Sz, z)}{2}\} \\ &= \max\{\delta(Sz, z), \frac{D(Sz, z)}{2}\} = \delta(Sz, z) \end{aligned}$$

and

$$N(z, z) = \min\{D(z, Tz), D(z, Sz)\} = 0$$

we conclude that

$$\begin{aligned} f(\delta(z, Sz)) &\leq f(\delta(Tz, Sz)) \\ &\leq f(M(z, z)) - \varphi(f(M(z, z))) + \psi(N(z, z)) \\ &\leq f(\delta(z, Sz)) - \varphi(f(\delta(Sz, z))), \end{aligned}$$

which in turn implies that $Sz = \{z\}$. Hence the point z is a common end point of S and T . □

Theorem 2.2. *Let (E, d) be a complete metric space, and let $T, S : E \rightarrow B(E)$ be two mappings such that for all $x, y \in E$*

$$f(\delta(Tx, Sy)) \leq f(M(x, y)) - \varphi(f(M(x, y))) \quad (2.2)$$

where $\phi \in \Phi$ and $f \in \Omega$. Then S and T have a unique common end point $z \in E$. i.e., $Sz = Tz = \{z\}$.

Proof. By theorem 2.1, T and S have a common end point z . Now let $y \in E$ be another common end point of S and T . Notice that

$$\begin{aligned} M(y, y) &= \max\{d(y, y), \delta(Ty, y), \delta(y, Sy), \frac{D(Ty, y) + D(Sy, y)}{2}\} \\ &= \max\{\delta(Sy, y), \delta(y, Ty)\}. \end{aligned}$$

Hence

$$\begin{aligned} f(\delta(y, Ty)) &\leq f(\delta(Sy, Ty)) \leq f(M(y, y)) - \varphi(f(M(y, y))) \\ &\leq f(\max\{\delta(y, Sy), \delta(y, Ty)\}) - \varphi(f(\max\{\delta(y, Sy), \delta(y, Ty)\})). \end{aligned}$$

Similarly, we have

$$\begin{aligned} f(\delta(y, Sy)) &\leq f(\delta(Ty, Sy)) \leq f(M(y, y)) - \varphi(f(M(y, y))) \\ &\leq f(\max\{\delta(y, Sy), \delta(y, Ty)\}) - \varphi(f(\max\{\delta(y, Sy), \delta(y, Ty)\})). \end{aligned}$$

Therefore

$$\begin{aligned} f(\max\{\delta(y, Sy), \delta(y, Ty)\}) &\leq \\ &f(\max\{\delta(y, Sy), \delta(y, Ty)\}) - \phi(f(\max\{\delta(y, Sy), \delta(y, Ty)\})) \end{aligned}$$

which implies that $\max\{\delta(y, Sy), \delta(y, Ty)\} = 0$, hence $\delta(Ty, y) = \delta(Sy, y) = 0$. Now we have

$$M(z, y) = \max\{d(z, y), \delta(z, Tz), \delta(y, Sy), \frac{D(y, Tz) + D(z, Sy)}{2}\}$$

and

$$\begin{aligned} f(d(z, y)) &= f(\delta(Sz, Ty)) \leq f(M(z, y)) - \varphi(f(M(z, y))) \\ &= f(d(z, y)) - \varphi(f(d(z, y))) \end{aligned}$$

that imply $d(z, y) = 0$ i.e., $z = y$. Hence z is the unique common end point of S and T . \square

If in Theorem 2.1 we put $f(t) = t$ and $\varphi(t) = (1 - k)t$, for some $0 < k < 1$, then we obtain the following result.

Theorem 2.3. Let (E, d) be a complete metric space, and let $T, S : E \longrightarrow B(E)$ be two mappings such that for all $x, y \in E$

$$\delta(Tx, Sy) \leq k(M(x, y)) + \psi(N(x, y)) \quad (2.3)$$

where $\psi \in \Psi$. Then S and T have a common end point $z \in E$, i.e., $Sz = Tz = \{z\}$.

Let T and S be two single valued mappings, then we obtain the following theorem:

Theorem 2.4. Let (E, d) be a complete metric space, and let $T, S : E \longrightarrow E$ be two mappings such that for all $x, y \in E$

$$f(d(Tx, Sy)) \leq f(M(x, y)) - \varphi(f(M(x, y))) + \psi(N(x, y)) \quad (2.4)$$

where $\varphi \in \Phi$, $\psi \in \Psi$, $f \in \Omega$ and

$$M(x, y) = \max \left\{ d(x, y), d(Tx, x), d(y, Sy), \frac{d(y, Tx) + d(x, Sy)}{2} \right\},$$

$$N(x, y) = \min\{d(Tx, y), d(x, Sy)\}.$$

Then S and T have a common fixed point $z \in E$, i.e., $Sz = Tz = z$.

Example 2.1. Let $E = [0, 1]$ and $d(x, y) = |x - y|$. For each $x \in E$ define $S, T : E \rightarrow B(E)$ by

$$Tx = [\frac{x}{4}, \frac{x}{2}], \quad Sx = [0, \frac{x}{5}].$$

Then

$$\delta(Tx, Sy) = \begin{cases} \frac{x}{2} & 0 \leq \frac{y}{5} \leq \frac{x}{2} \\ \max\{\frac{y}{5} - \frac{x}{4}, \frac{x}{2}\} & \frac{x}{2} \leq \frac{y}{5} \leq 1. \end{cases}$$

and

$$\delta(x, Tx) = \frac{3x}{4}, \quad \delta(y, Sy) = y.$$

We also consider $f(t) = 2t$ and $\phi(t) = \frac{t}{4}$. We note that if $\delta(Tx, Sy) = \frac{x}{2}$ then

$$\begin{aligned} f(\delta(Tx, Sy) = x) &\leq \frac{9x}{8} = \frac{3}{2}\delta(x, Tx) \\ &\leq \frac{3}{2}(M(x, y)) = f(M(x, y)) - \varphi(f(M(x, y))) \end{aligned}$$

and if $\delta(Tx, Sy) = \frac{y}{5} - \frac{x}{4}$ then

$$\begin{aligned} \psi(\delta(Tx, Sy) = \frac{y}{5} - \frac{x}{4}) &\leq \frac{2y}{5} \leq \frac{3y}{2} \\ &= \frac{3}{2}\delta(y, Sy) \leq \frac{3}{2}(M(x, y)) = f(M(x, y)) - \varphi(f(M(x, y))). \end{aligned}$$

This arguments show that the mappings T and S satisfy the conditions of Theorem 2.2. Now it is easy to see that 0 is the only common end point of this two mappings.

In the following we shall see that Theorem 2.1 is a real generalization of Theorem 2.2. We note that by Theorem 2.2, T and S have a unique common end point.

Example 2.2. Let $E = [0, 1]$ and $d(x, y) = |x - y|$. For each $x \in E$ define $T, S : E \rightarrow B(E)$ by

$$Tx = Sx = \begin{cases} [\frac{x}{3}, \frac{x}{2}] & x \neq 1 \\ 1 & 1. \end{cases}$$

We also consider $f(t) = t$, $\phi(t) = \frac{t}{5}$, and $\psi(t) = 2t^2$. We note that if $x, y \neq 1$ and $x \leq y$ then $\delta(y, Ty) = \frac{2y}{3}$ hence

$$\begin{aligned} f(\delta(Tx, Ty) = \frac{y}{2} - \frac{x}{3}) &\leq \frac{8}{15}\delta(y, Ty) \\ &\leq \frac{8}{15}M(x, y) = f(M(x, y)) - \varphi(f(M(x, y))) \end{aligned}$$

Similar result holds if $x, y \neq 1$ and $y \leq x$. Now if $y = 1$ and $x \neq 1$, then $\delta(Tx, Ty) = 1 - \frac{x}{3}$, $D(y, Tx) = 1 - \frac{x}{2}$, $D(x, Ty) = 1 - x$, $d(x, y) = 1 - x$, $\delta(y, Ty) = 0$ and $\delta(x, Tx) = \frac{2x}{3}$. Hence

$$M(x, y) = \begin{cases} 1 - \frac{3x}{4}, & x \leq \frac{12}{17} \\ \frac{2x}{3}, & x \geq \frac{12}{17}. \end{cases}$$

and

$$N(x, y) = 1 - x$$

therefore we have

$$f(\delta(Tx, Ty)) = 1 - \frac{x}{3} \leq 2(1 - x)^2 = \psi(N(x, y)) \leq f(M(x, y)) - \varphi(f(M(x, y))) + \psi(N(x, y)).$$

Similar result holds if $x = 1$ and $y \neq 1$. This arguments show that the mappings T and S satisfy the conditions of Theorem 2.1. We observe that 0 and 1 are two end points for T and S .

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