

OPTIMIZED DRIE PROCESS FOR TAPERED WALLS THROUGH WAFER VIA HOLES MANUFACTURING

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Lucrarea prezintă o metodă nouă de realizare a unor treceri prin plachetele de siliciu cu pereți înclinați, utilizând un proces de corodare uscată de tip DRIE (Deep Reactive Ion Etching) cu izotropie variabilă.

Sunt prezentate principiul de realizare a trecerilor (bazat pe utilizarea unei corodări anisotrope de tip Bosch) și optimizarea procesului pentru obținerea unui control bun al unghiurilor de înclinare a pereților.

This paper presents a new method of tapered walls through silicon wafers via holes (TSV) manufacturing, using a variable isotropy DRIE (Deep Reactive Ion Etching) process type.

TSV manufacturing method is presented (based on Bosch type anisotropic etching), as well as process optimization for a very good control over the wall angles.

Keywords: DRIE, TSV, variable isotropy

1. Introduction

Last generations of mobile phones or multifunctional computers were achieved due to the availability of technology development. One important aspect in recent years was the increasing of integration level, mainly by miniaturization through the LSI (Large Scale Integration) processes providing very small dimensions. Because in plane miniaturization it is close to arrive to its technological limits, tridimensional technology can offer a new breakthrough enabling to increase the integration density.

Conductive through silicon via's (TSV's) are the key component for electrical connections in stacking devices - replacing wire bonding with TSV's, it is possible to save the space that would be necessary for bonding wires and to reduce connections lengths [1].

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Two aspects should be solved during TSV's fabrication: through wafer via (TWV) manufacturing and holes filling with a conductive layer.

TWV were manufactured in last 20 years using different techniques - wet etching, powder blasting, laser processing or plasma etching, each with advantages and disadvantages in terms of aspect ratio, wall roughness, minimum size or positioning accuracy [2]. Due to the very good performances (aspect ratio higher than 20:1, positioning accuracy provided by photolithography, minimum size or roughness), DRIE began to be the main technique used in recent years.

Copper and doped polysilicon are commonly used as conductive materials for via holes filling due to the deposition features of these materials: electrochemical deposition for copper (with a much higher deposition rate in narrow areas) and LPCVD for polysilicon (very good coverage of the walls due to the conformal deposition) [3-5]. Unfortunately, due to the contamination problem is not easy to implement copper electroplating technology anywhere, while for high frequencies applications doped polysilicon cannot be used due to the large resistivity.

Although problems of adhesion, diffusion or holes filling were not fully resolved, gold was also used as conductive material [6-7].

Our aim was to develop a new type of conductive TSV using gold, allow depositing a barrier layer – Cr or Ti – on the walls.

In this paper a new process of tapered walls TSV manufacturing is described. A variable isotropy process was developed in order to obtain a very good control of the walls angles, based on alternatively using of anisotropic Bosch type process and isotropic etchings. After optimization, process showed a very good agreement with designed via's – deviation smaller than 10% were obtained.

2. TSV manufacturing method

Among other advantages offered by DRIE techniques, the ability to change the isotropy during processing allow manufacturing of structures which cannot be obtained using other techniques [8].

This unique feature can be exploited for tapered walls TSV, using isotropic etchings steps for a controlled enlargement of the via's.

The proposed method consist in alternatively using of anisotropic and isotropic etchings to achieve the required depth and to enlarge the holes on the top side of the wafer; during anisotropic etchings, due to the process directivity, silicon will be removed just in the vertical direction, while during isotropic steps etchings will act on all surfaces of the walls.

Anisotropic etching steps are based on the Bosch type process, consisting of etching and passivation of the walls sequences to achieve large rates etching and anisotropies. To enable etching of the entire walls surface during isotropic

steps, the passivation layer deposited during anisotropic steps must be removed first - this can be done using oxygen plasma before each isotropic etching step.

The technological flow is presented in figure 1. Manufacturing process starts with thermal oxidation, photoresist deposition and patterning, followed by SiO₂ etching from the via windows – figure 1 a and b. Both SiO₂ and photoresist layers are used as masks during DRIE process, only one of them not being enough for TSV manufacturing. More than this, because photoresist is easily removed by oxygen plasma, SiO₂ layer thickness should be chosen as function of etching cycles number. DRIE processing (figure 1 c-g) starts and ends with anisotropic etching steps for a better definition of TSV on both sides.

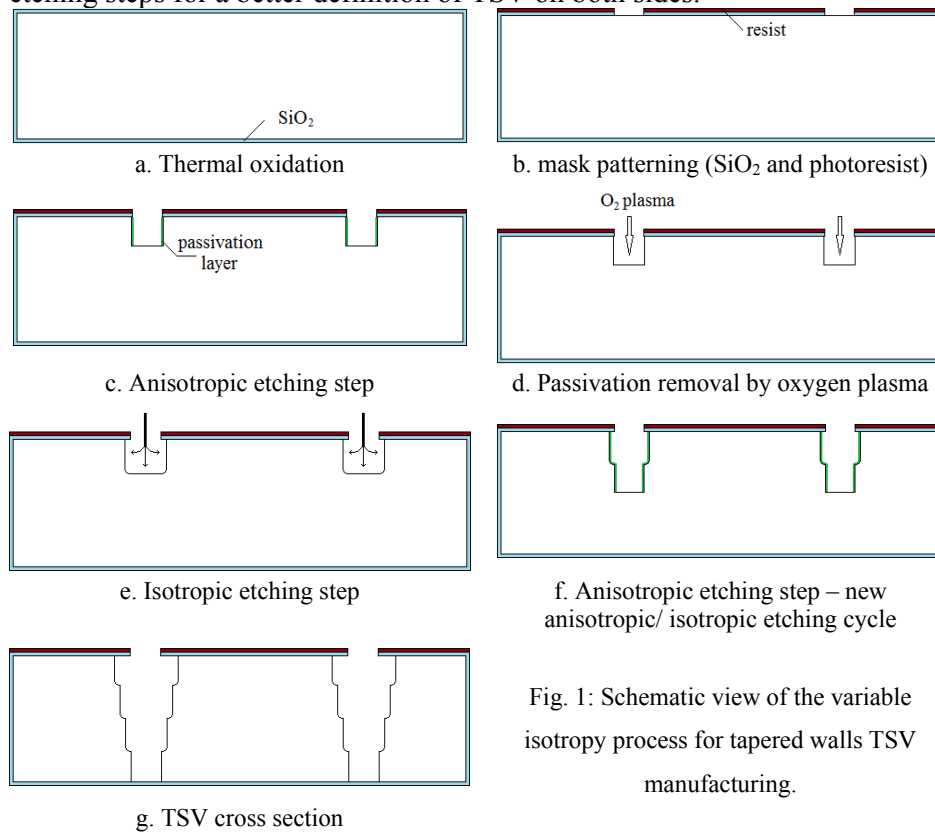


Fig. 1: Schematic view of the variable isotropy process for tapered walls TSV manufacturing.

One problem of DRIE processes is ARDE effect (Aspect Ratio Dependent Effect) – etching rate is strongly influenced by window area through which the etching is performed, significantly decreasing with surface; due to this effect is almost impossible to use different small size of the windows during the same process run. To estimate this effect, the process was performed and optimized for two different circular windows, having 20µm and 100µm diameter.

The second problem to achieve our purpose comes from the roughness of the wall after processing – depending of etching rate, Bosch type processes produce a specific roughness of the walls (scalloping) which can be up to $1\mu\text{m}$. To reduce walls roughness different anisotropic etching recipes were used.

3. Experimental results and process optimization

First step in TSV manufacturing consist in etching rates finding for the specific windows used. Silicon wafers ($\langle 100 \rangle$ oriented, $200\mu\text{m}$ thick) and $100\mu\text{m}$ diameter circular masks were used for TSV manufacturing.

300nm thermal silicon oxide layer was grown on the wafers and a $10\mu\text{m}$ thick photoresist was used for etching windows patterning.

Two processes, with a different number of steps, were used in this stage, for a easier characterization: first one had three steps of anisotropic etching and two of isotropic etching (two etching cycles), while the second one had five steps of anisotropic etching and four of isotropic etching (four etching cycles) [9].

A high etching rate recipe (more than $10\mu\text{m}/\text{min}$) was used for anisotropic etching steps.

Measurements performed on the manufactured structures (figure 2) showed etching depths of $\sim 104\mu\text{m}$ in 6min for the process with two etching cycles, while for the process with four etching cycles etching depth of each anisotropic step was $\sim 52\mu\text{m}$ in 3 min, leading in both cases to an etching rate of $17.33\mu\text{m}/\text{min}$.

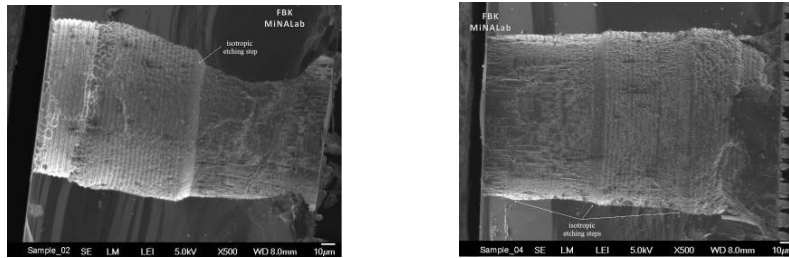


Fig. 2: SEM photo of TSV's performed using two (left) and four(right) etching cycles.

Regarding the isotropic etching steps, due to the much bigger anisotropic etching rates than the considered ones (almost double), can be seen just one isotropic etching step for the first process type and three for the second one (instead two and four respectively). Measurements performed showed an etching rate of about $2\mu\text{m}/\text{min}$ for this process type.

In fig 2 we can see the specific scalloping obtained after Bosch type anisotropic etching, providing a roughness of about $1\mu\text{m}$.

One method to reduce walls roughness was to modify the anisotropic etching recipe: using lower gas flow and power it is possible to obtain smoother

walls, although in this way etching rates will decrease. Also, when bigger angles are needed (in first experiments obtained angles were between 1.8° and 2.9° ; walls angles are computed considering top and bottom size of the TSV), isotropic etching acts to reduce the roughness, having a polishing effect.

In the next step two different anisotropic etching recipes were used, the first one providing a roughness of about 500nm, the second with a roughness lower than 100nm.

During this optimization step 500 μm thick silicon wafers were used and mask with both 20 μm and 100 μm windows diameter on the same wafer; the aim was to obtain 100 μm diameter holes with a 200 μm depths, using variable isotropy process with 4 etching cycles. In addition to roughness reduction, other targets for this stage were to find exactly etching rates for these processes and to estimate the ARDE effect for these two windows dimensions.

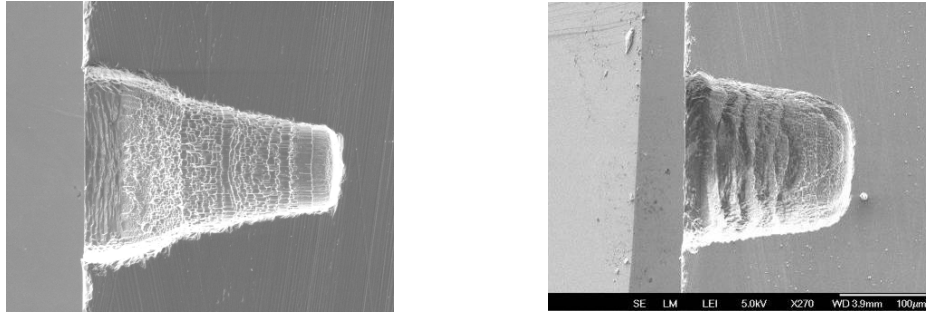


Fig. 3: SEM photos of the holes performed in 500 μm silicon wafers using a variable isotropy process and anisotropic etching recipe with medium roughness, having 20 μm (left) and 100 μm (right) diameters.

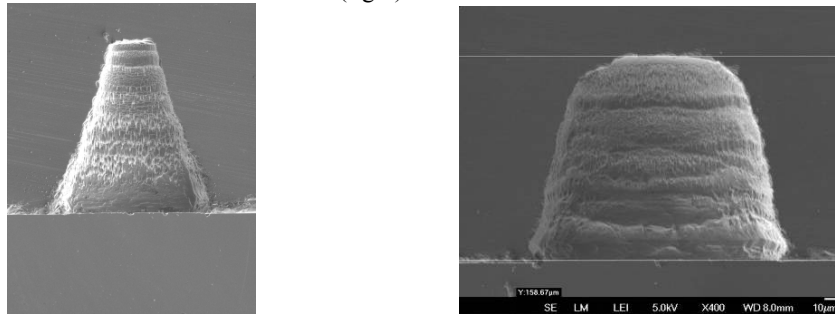


Fig. 4: SEM photos of the holes performed using a four cycles variable isotropy process with a low roughness anisotropic etching recipe, with 20 μm (left) and 100 μm (right) diameters.

Results obtained are presented in figures 3 for the recipe with a medium roughness and in figure 4 for the recipe with low roughness.

In all SEM photos can be seen a strong improvement of the walls roughness, but also the appearance of some nanometer peaks on the walls - mainly on 20 μm diameter holes.

Measurements performed on the manufactured holes by medium roughness recipe showed a depth of about $195\mu\text{m}$ for $100\mu\text{m}$ diameter, while for the $20\mu\text{m}$ diameter depth obtained was of about $128\mu\text{m}$. Using the recipe providing low roughness etching rates were smaller, obtaining a depth of about $159\mu\text{m}$ for $100\mu\text{m}$ diameter holes and $109\mu\text{m}$ for $20\mu\text{m}$ diameter. Both recipes provides a etching rates dropping of about 33% for the smaller holes diameter respect to the bigger ones due to the ARDE effect.

A very close ratio was obtained also regarding the isotropic etching rates: $45\div 50\mu\text{m}$ lateral etching for $100\mu\text{m}$ diameter holes and $30\div 35\mu\text{m}$ for $20\mu\text{m}$ diameter ones. A strong attenuation of the isotropic etchings was observed which should be taken into consideration in the final step – the process was designed to obtain wall angles of 21.8° , but angles obtained were between 14° and 18° (for $100\mu\text{m}$ diameter holes, lateral etching was between $45\mu\text{m}$ and $50\mu\text{m}$ instead of $80\mu\text{m}$ as was designed).

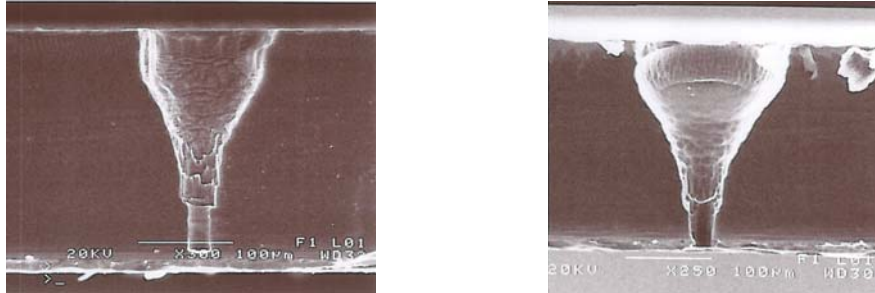


Fig. 5: TSV manufactured on $300\mu\text{m}$ thick silicon wafers using $20\mu\text{m}$ diameter masks; obtained wall angles: 10.3° (left) and 15.2° (right).

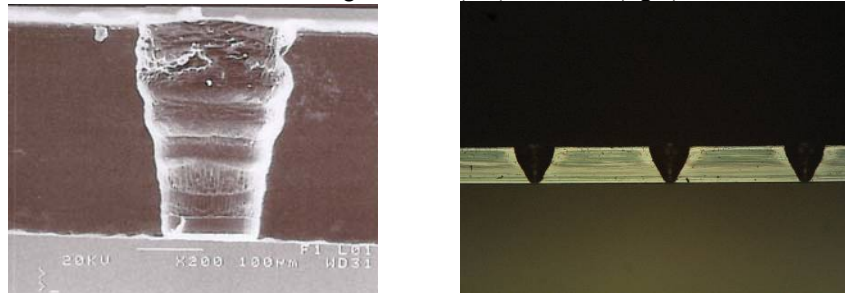


Fig. 6: SEM photos of the manufactured TSV on $300\mu\text{m}$ thick silicon wafers using $100\mu\text{m}$ diameter masks with wall angles of 10.7° (left) and 21.2° (right).

Optimized process was implemented on $300\mu\text{m}$ thick silicon wafers using a six etching cycles process; both etching windows dimensions ($20\mu\text{m}$ and $100\mu\text{m}$) were used for TSV manufacturing. For this last step target was to obtain both 11.3° and 21.8° walls angles, with lateral etching around the mask of $60\mu\text{m}$ and $120\mu\text{m}$ respectively. Results obtained are presented in figures 5 (for $20\mu\text{m}$ mask diameter) and 6 (for $100\mu\text{m}$ diameter).

Measurements performed (table 1) show in almost all cases an enlargement very close to the expected ones: 54.5 μm to 56 μm instead 60 μm for 11.3° angles, while for 21.8° lateral etching was of about 115 μm instead 120 μm (for 100 μm diameter mask). These data lead to errors smaller than 10% - between 9.17% (for 20 μm diameter and 11.3° wall angle) and 6.67% (obtained for 100 μm diameter and

Table 1

Measurements of the manufactured TWV after process optimization				
Parameter	Mask diameter			
	20 μm		100 μm	
Target angle (lateral etching)	11.3° (60 μm)	21.8° (120 μm)	11.3° (60 μm)	21.8° (120 μm)
Bottom size	~25 μm	~27 μm	~140 μm	~100 μm
Top size	~134 μm	~190 μm	~252 μm	~330 μm
Lateral etching	~54.5 μm	~81.5 μm	~56 μm	~115 μm
Measured angle	~10.3°	~15.2°	~10.57°	~20.97°

21.8° wall angle). Strong reduction of the etching rate of isotropic processes can be seen in the much smaller enlargement obtained for 20 μm diameter TSV: 81.5 μm instead 120 μm . Also, cross section of the 20 μm diameter TSV's (figure 5) show the modification of the slope due to the changes of the etching rate with depth.

Computed angles, based on the measured data, were close to the wanted ones in three of four cases: 10.3° and 10.57° instead 11.3° and 20.97° instead 21.8°.

4. Conclusions

A new process for TSV was developed, consisting in alternated using of anisotropic and isotropic etching steps. This process was optimized for two different via sizes (20 μm and 100 μm) on 300 μm thick silicon wafers. Optimization shows the possibility to obtain very small errors - in almost all cases errors were smaller than 10%.

The advantages of this process type reside in a very good control of the walls angles with possibility of barrier and seed layer deposition, thereby improving the adhesion and reducing the diffusion. Also, it can be easily implemented on other kind of DRIE equipments without the need for a long time and significant resources.

Comparing with others TSVs manufacturing techniques recently reported [1, 10-14], we can see the benefits of this technology in thick wafer processing or possibility of manufacturing tapered walls TSVs with a very good control of the angles and a short process optimization; also, the aspect ratio of the manufactured TSVs allow to obtain a minimum dimension of the same magnitude with that reported in the literature.

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