

ON α -LOCALLY DOUBLY DIAGONALLY DOMINANT MATRICES

Lei-Lei Wang¹, Bo-Yan Xi², Feng Qi³

In the paper, the authors introduce a new type of α -locally doubly diagonally dominant matrices, which is indeed a new subclass of H -matrices, present several new criteria for judging non-singular H -matrices according to the theory of the new type of α -locally doubly diagonally dominant matrices, and illustrate effectiveness and advantages of the proposed criteria by some numerical examples.

Keywords: non-singular H -matrix, α -locally doubly diagonally dominant matrix, criteria, irreducibility, non-zero element chain, numerical example

MSC2010: 15A45, 15A48, 15B48, 15B57, 65F05, 65F10, 65F99

1. Introduction

It is well known that H -matrices play an important role in the matrix theory, computational mathematics, and mathematical physics. See [1, 2, 11]. In recent years, a lot of work devoted to giving direct and iterative criteria for judging whether a certain matrix A is a non-singular H -matrix or not. See [3, 5, 6, 7, 8, 9, 10, 12, 13, 15, 16, 17, 18, 19, 20, 21]. In practice, if the coefficient matrix A of the linear system $Ax = b$ is an H -matrix, then many classical iterative methods are convergent. See [2, Chapters 7] and [4]. Therefore, it is significant to look for numerical methods of judging non-singular H -matrices and to provide effective and practical criteria.

In this paper, we will introduce a new type of α -locally doubly diagonally dominant matrices, present several new criteria for non-singular H -matrices, and illustrate effectiveness and advantages of the proposed criteria by numerical examples.

¹College of Mathematics, Inner Mongolia University for Nationalities, Tongliao City, Inner Mongolia Autonomous Region, 028043, China; School of Mathematics and Computational Science, Xiangtan University, Xiangtan City, Hunan Province, 411105, China; E-mail: wangleilei501@qq.com, wangleilei501@163.com

²College of Mathematics, Inner Mongolia University for Nationalities, Tongliao City, Inner Mongolia Autonomous Region, 028043, China; E-mail: baoyintu78@qq.com, baoyintu68@sohu.com, baoyintu78@imun.edu.cn

³Department of Mathematics, College of Science, Tianjin Polytechnic University, Tianjin City, 300387, China; Institute of Mathematics, Henan Polytechnic University, Jiaozuo City, Henan Province, 454010, China; E-mail: qifeng618@gmail.com, qifeng618@hotmail.com, qifeng618@qq.com; URL: <http://qifeng618.wordpress.com>

2. Definitions and lemmas

We recall some notation, definitions, and lemmas.

Let $\mathbb{C}^{n \times n}$ be the set of all $n \times n$ complex matrices, \mathbb{N} the set of all positive integers, and $A = (a_{ij}) \in \mathbb{C}^{n \times n}$. For $i \in \mathbb{N}$, let

$$P_i(A) = \sum_{j \neq i} |a_{ij}|, \quad R_i(A) = \sum_{j \neq i} |a_{ji}|, \quad q_i = \frac{P_i(A)}{|a_{ii}|}.$$

Definition 2.1 ([17, p. 294]). Let $A = (a_{ij}) \in \mathbb{C}^{n \times n}$. The comparison matrix of A , denoted by $\mu(A) = (m_{ij})_{n \times n}$, is defined by

$$m_{ij} = \begin{cases} |a_{ij}|, & i = j, \\ -|a_{ij}|, & i \neq j. \end{cases}$$

A matrix A is said to be an M -matrix if $A = \mu(A)$ and the real parts of eigenvalues of A are positive. A matrix A is said to be an H -matrix if $\mu(A)$ is an M -matrix.

Remark 1. By Definition 2.1, it is easy to see that every H -matrix is non-singular. If A is an H -matrix such that $\mu(A)$ is non-singular, then all diagonal entries of A are non-zero. See [3, p. 2361]. Thus, in what follows, we always assume that $a_{ii} \neq 0$ for all $i \in \mathbb{N}$.

Definition 2.2 ([5, Definition 1.1], [14, p. 233], and [16, p. 120]). A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is called to be (row) diagonally dominant, denoted by $A \in D_0$, if

$$|a_{ii}| \geq P_i(A), \quad i \in \mathbb{N}. \quad (2.1)$$

A matrix A is said to be strictly diagonally dominant, denoted by $A \in D$, if all the inequalities in (2.1) are strict. A matrix A is said to be generalized strictly diagonally dominant, if there exists a positive diagonal matrix X such that AX is strictly diagonally dominant.

Remark 2. It was said in [6, p. 318] and [16, p. 120] that A is a non-singular H -matrix if and only if A is a generalized strictly diagonally dominant matrix.

Definition 2.3 ([5, Definition 1.1]). If \mathbb{N}_1 and \mathbb{N}_2 are non-empty, proper, and disjoint subsets of \mathbb{N} such that $\mathbb{N}_1 \cup \mathbb{N}_2 = \mathbb{N}$, then we say that $(\mathbb{N}_1, \mathbb{N}_2)$ is a separation of \mathbb{N} .

Definition 2.4 ([19, p. 3]). A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be irreducibly diagonally dominant if it is irreducible and at least one of the inequalities in (2.1) strictly holds.

Definition 2.5 ([6, Definition 2]). A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is called diagonally dominant with non-zero element chain, if the inequality (2.1) is valid for all $i \in \mathbb{N}$, where at least one strictly inequality holds and, for every i with $|a_{ii}| = P_i(A)$, there exists a non-zero elements chain $a_{ij_1} a_{j_1 j_2} \dots a_{j_{k-1} j_k} \neq 0$ such that $|a_{j_k j_k}| > P_{j_k}(A)$.

Definition 2.6 ([9, Definition 1]). Let $\alpha \in [0, 1]$, $A = (a_{ij}) \in \mathbb{C}^{n \times n}$, and $(\mathbb{N}_1, \mathbb{N}_2)$ be a separation of \mathbb{N} . If, for all $i \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$,

$$|a_{jj}| - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| > 0$$

and

$$\begin{aligned} \left(P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t \right)^\alpha \left(|a_{jj}| - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| \right)^{1-\alpha} \\ > \left(\sum_{t \in \mathbb{N}_1} |a_{jt}| q_t \right)^{1-\alpha} \left(\sum_{t \in \mathbb{N}_2} |a_{it}| \right)^\alpha, \end{aligned}$$

then A is said to be an α -SGD matrix.

We also need the following lemmas.

Lemma 2.1 ([19, Theorem 1]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is irreducibly diagonally dominant, then A is a non-singular H-matrix.*

Lemma 2.2 ([6, p. 322]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is a diagonally dominant matrix with non-zero element chain, then A is a non-singular H-matrix.*

Lemma 2.3 ([9, Theorem 1]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is an α -SGD matrix, then A is a non-singular H-matrix.*

Lemma 2.4 ([8, p. 241] and [18, Theorem 1]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is a non-singular H-matrix, then there exists at least one $i \in \mathbb{N}$ such that $|a_{ii}| > P_i(A)$.*

Lemma 2.5 ([6, Lemma 1]). *Let $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ be a matrix whose diagonal entries are non-zero, $\delta = \{i | i \in \mathbb{N}, P_i(A) > 0\}$, and $A(\delta)$, whose rows and columns are indexed by δ , a sub-matrix of A . Then A is a non-singular H-matrix if and only if $A(\delta)$ is a non-singular H-matrix.*

3. Main results

We first introduce a new type of α -locally doubly diagonally dominant matrices as follows.

Definition 3.1. Let $\alpha \in [0, 1]$ and $(\mathbb{N}_1, \mathbb{N}_2)$ be a separation of \mathbb{N} . A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be strictly α -locally doubly diagonally dominant, denoted by $A \in SLDD(\alpha)$, if

$$P_i(A) > \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t, \quad P_j(A) > \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| q_t,$$

and

$$\begin{aligned}
& \left(P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t \right)^\alpha \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| q_t \right)^{1-\alpha} \\
& > \left(\sum_{t \in \mathbb{N}_2} |a_{it}| q_t \right)^\alpha \left(\sum_{t \in \mathbb{N}_1} |a_{jt}| q_t \right)^{1-\alpha} \quad (3.1)
\end{aligned}$$

hold for all $i \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$.

Definition 3.2. An irreducible matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be irreducibly α -locally doubly diagonally dominant if

- (1) the inequalities in (3.1) hold with \geq instead of $>$,
- (2) at least one of the inequalities in (3.1) strictly holds, and
- (3) A satisfies other conditions of Definition 3.1.

Definition 3.3. A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be α -locally doubly diagonally dominant with a non-zero element chain if

- (1) the inequalities in (3.1) hold with \geq instead of $>$,
- (2) for all $i \in \{i_1, \dots, i_k\} \cup \{j_1, \dots, j_l\}$, there exist a non-zero element chain $a_{i_1} a_{i_1 i_2} \dots a_{i_1 i^*} \neq 0$ such that $i^* \in (\mathbb{N}_1 \setminus \{i_1, \dots, i_k\}) \cup (\mathbb{N}_2 \setminus \{j_1, \dots, j_l\}) \neq \emptyset$ and

$$\begin{aligned}
& \left(P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t \right)^\alpha \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| q_t \right)^{1-\alpha} \\
& = \left(\sum_{t \in \mathbb{N}_1} |a_{jt}| q_t \right)^\alpha \left(\sum_{t \in \mathbb{N}_2} |a_{it}| q_t \right)^{1-\alpha} \quad (3.2)
\end{aligned}$$

hold for all $i \in \{i_1, \dots, i_k\} \subset \mathbb{N}_1$ and $j \in \{j_1, \dots, j_l\} \subset \mathbb{N}_2$, and

- (3) A satisfies other conditions of Definition 3.1.

Now we start off to provide some new criteria for non-singular H -matrices.

Theorem 3.1. Let $A = (a_{ij}) \in \mathbb{C}^{n \times n}$. If $A \in SLDD(\alpha)$, then A is a non-singular H -matrix.

Proof. If $\sum_{t \in \mathbb{N}_2} |a_{it}| q_t \neq 0$ for $i \in \mathbb{N}_1$, since $A \in SLDD(\alpha)$, then there exists a positive number d such that

$$\min_{i \in \mathbb{N}_1} K_i > d > \max_{j \in \mathbb{N}_2} k_j, \quad (3.3)$$

where

$$K_i = \frac{P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t}{\sum_{t \in \mathbb{N}_2} |a_{it}| q_t} \quad \text{and} \quad k_j = \frac{\sum_{t \in \mathbb{N}_1} |a_{jt}| q_t}{P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| q_t}$$

for $i \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$.

Let

$$x_t = \begin{cases} q_t, & t \in \mathbb{N}_1, \\ dq_t, & t \in \mathbb{N}_2, \end{cases} \quad X = \text{diag}(x_1, x_2, \dots, x_n), \quad B = AX = (b_{ij})_{n \times n}. \quad (3.4)$$

For $i \in \mathbb{N}_1$, the double inequality (3.3) implies that

$$\begin{aligned} |b_{ii}| - P_i(B) &= P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - d \sum_{t \in \mathbb{N}_2} |a_{it}|q_t \\ &> P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - K_i \sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0. \end{aligned}$$

For $j \in \mathbb{N}_2$, the double inequality (3.3) means that

$$\begin{aligned} |b_{jj}| - P_j(B) &= d \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t \\ &> k_j \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t = 0. \end{aligned}$$

Then $|b_{ii}| > P_i(B)$ for $i \in \mathbb{N}$. Hence, A is a non-singular H -matrix in this case.

If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$ for $i \in \mathbb{N}_1$, by Definition 3.1, we have $P_j(A) > \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t$ for all $j \in \mathbb{N}_2$. Consequently, there exists $d > 0$ satisfying

$$d \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) > \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t. \quad (3.5)$$

Making use of (3.4) to (3.5) yields $|b_{ii}| > P_i(B)$ for $i \in \mathbb{N}$. Therefore, A is a non-singular H -matrix. The proof of Theorem 3.1 is completed. \square

Theorem 3.2. *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is an irreducibly α -locally doubly diagonally dominant matrix, then A is a non-singular H -matrix.*

Proof. In view of the irreducibility of A , there exists $a_{jt} \neq 0$ for $t \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$.

If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$ for $i \in \mathbb{N}_1$, by Definition 3.2, it is easy to see that A is a non-singular H -matrix.

If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \neq 0$ for $i \in \mathbb{N}_1$, by the same arguments as above, we have

$$d \triangleq \min_{i \in \mathbb{N}_1} K_i = \max_{j \in \mathbb{N}_2} k_j, \quad (3.6)$$

which means that $d > 0$.

From (3.4) and (3.6), it follows that

$$|b_{ii}| - P_i(B) = P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - d \sum_{t \in \mathbb{N}_2} |a_{it}|q_t$$

$$\geq P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - K_i \sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$$

for $i \in \mathbb{N}_1$ and that

$$\begin{aligned} |b_{jj}| - P_j(B) &= d|a_{jj}|q_j - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t - d \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \\ &= d \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t \geq 0 \end{aligned}$$

for $j \in \mathbb{N}_2$. Consequently, by Definition 3.2, it follows that $|b_{ii}| \geq P_i(B)$ for all $i \in \mathbb{N}$, in which at least one strict inequality is valid. Since A is irreducible, then B is an irreducibly diagonally dominant matrix. Thus, in light of Lemma 2.1, we obtain that B is a non-singular H -matrix, and so is A . The proof of Theorem 3.2 is completed. \square

Theorem 3.3. *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is an α -locally doubly diagonally dominant matrix with a non-zero elements chain, then A is a non-singular H -matrix.*

Proof. If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$ for all $i \in \mathbb{N}_1$, then it is easy to see that A is a non-singular H -matrix. If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \neq 0$ for $i \in \mathbb{N}_1$, by similar arguments as above, we obtain $d \triangleq \min_{i \in \mathbb{N}_1} K_i = \max_{j \in \mathbb{N}_2} k_j > 0$. Utilizing (3.2) and (3.4), by Definition 3.3, we obtain $|b_{ii}| - P_i(B) \geq 0$ for $i \in \{j_1, \dots, j_l\} \cup \{i_1, \dots, i_k\}$, that is, $|b_{ii}| \geq P_i(B)$ for $i \in (\mathbb{N}_1 \setminus \{i_1, \dots, i_k\}) \cup (\mathbb{N}_2 \setminus \{j_1, \dots, j_l\})$. This means that B is a diagonally dominant matrix with non-zero elements chain. Furthermore, by Lemma 2.2, we obtain that B is a non-singular H -matrix, and so is A . The proof of Theorem 3.3 is completed. \square

Remark 3. From Theorem 3.1, we find that the type of α -locally doubly diagonally dominant matrices is a subclass of H -matrices. Hence, the introduction of α -locally doubly diagonally dominant matrices well extends the theory of H -matrices.

4. Numerical Examples

We now illustrate effectiveness and advantages of the above proposed criteria by several numerical examples.

Example 4.1. Let

$$A = \begin{bmatrix} 3 & 2 & 6 & 0 \\ 1 & 6.8 & 3 & 4 \\ 1 & 2 & 9 & 4 \\ 0 & 2 & 2 & 8 \end{bmatrix}$$

and $(\mathbb{N}_1, \mathbb{N}_2)$ be a separation of $\mathbb{N} = \{1, 2, 3, 4\}$. If \mathbb{N}_1 and \mathbb{N}_2 satisfy one of the following cases:

$$\begin{aligned} \mathbb{N}_1 &= \{1\}, \quad \mathbb{N}_2 = \{2, 3, 4\}; \quad \mathbb{N}_1 = \{2\}, \quad \mathbb{N}_2 = \{1, 3, 4\}; \quad \mathbb{N}_1 = \{3\}, \\ \mathbb{N}_2 &= \{1, 2, 4\}; \quad \mathbb{N}_1 = \{4\}, \quad \mathbb{N}_2 = \{1, 2, 3\}; \quad \mathbb{N}_1 = \{1, 2\}, \quad \mathbb{N}_2 = \{3, 4\}; \end{aligned}$$

$$\mathbb{N}_1 = \{1, 3\}, \quad \mathbb{N}_2 = \{2, 4\}; \quad \mathbb{N}_1 = \{1, 4\}, \quad \mathbb{N}_2 = \{2, 3\}; \quad \mathbb{N}_1 = \{2, 3\}, \\ \mathbb{N}_2 = \{1, 4\}; \quad \mathbb{N}_1 = \{2, 4\}, \quad \mathbb{N}_2 = \{1, 3\};$$

then A is not an α -SGD matrix and does not satisfy the corresponding conditions in [9, Theorem 1]. But, when \mathbb{N}_1 and \mathbb{N}_2 satisfy one of the above cases, by Theorem 3.1, it is easy to see that A is a non-singular H -matrix.

Example 4.2. Consider

$$A = \begin{bmatrix} 3 & 2 & 6 & 0 \\ 1 & 6.8 & 3 & 4 \\ 1 & 2 & 9 & 4 \\ 0 & 2 & 2 & 10 \end{bmatrix}.$$

By [15, Theorems 2.1 and 2.2], we have

$$r_1 = \min \left\{ \frac{\alpha_3 - \gamma_3}{|a_{33}| - \gamma_3}, \frac{\alpha_4 - \gamma_4}{|a_{44}| - \gamma_4} \right\} = \min \left\{ \frac{12}{37}, \frac{1}{19} \right\} = \frac{1}{19}, \\ r_2 = \max \left\{ \frac{\beta_3}{\alpha_3 + \beta_3 - \gamma_3}, \frac{\beta_4}{\alpha_4 + \beta_4 - \gamma_4} \right\} = \max \left\{ \frac{5}{9}, \frac{9}{11} \right\} = \frac{9}{11}.$$

Since $|a_{11}| = 3 < |a_{13}|(\delta_3 - r_1) + |a_{14}|(\delta_4 - r_1) + \beta_1 = 6.350\dots$, the matrix A does not satisfy the corresponding conditions in [15, Theorem 2.1]. Since $|a_{11}| = 3 < r_2(|a_{13}|\delta_3 + |a_{14}|\delta_4) + \beta_1 = 5.818\dots$, the matrix A does not satisfy the corresponding conditions in [15, Theorem 2.2] yet.

In virtue of [13, Theorem 2], we obtain

$$M_1 = \{(2, 3)\}, \quad M_2 = \{(1, 2), (1, 3), (1, 4)\}, \\ M_3 = \{(2, 4), (3, 4)\}, \quad M_4 = M_5 = M_6 = \emptyset,$$

and

$$\frac{R_2(A)R_3(A) - |a_{22}a_{33}|}{R_2(A)R_3(A) - P_2(A)P_3(A)} = 0.48, \\ \frac{|a_{11}a_{22}| - R_1(A)R_2(A)}{P_1(A)P_2(A) - R_1(A)R_2(A)} = 0.161\dots, \\ \frac{|a_{11}a_{33}| - R_1(A)R_3(A)}{P_1(A)P_3(A) - R_1(A)R_3(A)} = 0.147\dots, \\ \frac{|a_{11}a_{44}| - R_1(A)R_4(A)}{P_1(A)P_4(A) - R_1(A)R_4(A)} = 0.875.$$

Obviously,

$$\max_{(s,t) \in M_1} \frac{R_s(A)R_t(A) - |a_{ss}||a_{tt}|}{R_s(A)R_t(A) - P_s(A)P_t(A)} = 0.48 \\ > \min_{(i,j) \in M_2} \frac{|a_{ii}||a_{jj}| - R_i(A)R_j(A)}{P_i(A)P_j(A) - R_i(A)R_j(A)} = 0.147\dots$$

Therefore, the matrix A does not satisfy the conditions of [13, Theorem 2].

Nevertheless, if we choose $\mathbb{N}_1 = \{1, 2\}$, $\mathbb{N}_2 = \{3, 4\}$, and $\alpha = \frac{1}{2}$, then

$$[P_1(A) - |a_{12}|q_2]^\alpha [P_3(A) - |a_{34}|q_4]^{1-\alpha} = 5.522\dots,$$

$$\begin{aligned}
& [|a_{13}|q_3 + |a_{14}|q_4]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 4.839 \dots, \\
& [P_1(A) - |a_{12}|q_2]^\alpha [P_4(A) - |a_{43}|q_3]^{1-\alpha} = 3.715 \dots, \\
& [|a_{13}|q_3 + |a_{14}|q_4]^\alpha [|a_{41}|q_1 + |a_{42}|q_2]^{1-\alpha} = 3.313 \dots, \\
& [P_2(A) - |a_{21}|q_1]^\alpha [P_3(A) - |a_{34}|q_4]^{1-\alpha} = 5.366 \dots, \\
& [|a_{23}|q_3 + |a_{24}|q_4]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 4.443 \dots, \\
& [P_2(A) - |a_{21}|q_1]^\alpha [P_4(A) - |a_{43}|q_3]^{1-\alpha} = 3.610 \dots, \\
& [|a_{23}|q_3 + |a_{24}|q_4]^\alpha [|a_{41}|q_1 + |a_{42}|q_2]^{1-\alpha} = 3.042 \dots
\end{aligned}$$

By Theorem 3.1, we derive that A is a non-singular H -matrix.

Example 4.3. Let

$$A = \begin{bmatrix} 4 & 0.5 & 6 \\ 2 & 12 & 8 \\ 2 & 10 & 14 \end{bmatrix}.$$

(1) In view of [10], we easily obtain the following conclusions:

- (a) When $k = 1$, we acquire $S_1 + S_2 + S_3 = 1 + \frac{5}{12} > 1$.
- (b) When $k = 2$, for a separation $(\mathbb{N}_1, \mathbb{N}_2)$ of $\mathbb{N} = \{1, 2, 3\}$,
 - (i) if $\mathbb{N}_1 = \{1\}$ and $\mathbb{N}_2 = \{2, 3\}$, then $S_1 = \frac{3}{2} > 1$;
 - (ii) if $\mathbb{N}_1 = \{2\}$ and $\mathbb{N}_2 = \{1, 3\}$, then $S_1 + S_3 = \frac{7}{5} > 1$;
 - (iii) if $\mathbb{N}_1 = \{3\}$ and $\mathbb{N}_2 = \{1, 2\}$, then $S_1 + S_2 = \frac{191}{140} > 1$.
- (c) When $k = 3$, it is easy to see that $S_1 = \frac{13}{8} > 1$.

Therefore, the matrix A does not satisfy the corresponding conditions in [10, Theorem 1].

(2) It is not difficult to realize that the matrix A does not satisfy the corresponding conditions in [7, Theorem 1] and [21, Theorems 1 and 2].

Nevertheless, if we choose $\mathbb{N}_1 = \{1, 2\}$, $\mathbb{N}_2 = \{3\}$, and $\alpha = \frac{1}{2}$, then

$$\begin{aligned}
& [P_1(A) - |a_{12}|q_2]^\alpha [P_3(A)]^{1-\alpha} = 8.544 \dots, \\
& [|a_{13}|q_3]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 7.718 \dots, \\
& [P_2(A) - |a_{21}|q_1]^\alpha [P_3(A)]^{1-\alpha} = 9, \\
& [|a_{23}|q_3]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 8.912 \dots
\end{aligned}$$

Using Theorem 3.1 gives that A is a non-singular H -matrix.

5. Conclusions

In conclusion, a new type of α -locally doubly diagonally dominant matrices are introduced, which is now known as a subclass of non-singular H -matrices. Moreover, the authors establish several new and practical criteria for judging non-singular H -matrices by involved matrices. Consequently, the criteria for identifying nonsingular H -matrices is well extended.

Acknowledgements

The first author was partially supported by the Hunan Provincial Innovation Foundation for Postgraduates under Grant No. CX2014B254 in China and the latter two authors were partially supported by the NNSF under Grant No. 11361038 of China.

The authors appreciate anonymous referees for their helpful suggestions to and valuable comments on the original version of this manuscript.

REFERENCES

- [1] *M. Alanelli and A. Hadjidimos*, On iterative criteria for H - and non- H -matrices, *Appl. Math. Comput.* **188** (2007), no. 1, 19–30; Available online at <http://dx.doi.org/10.1016/j.amc.2006.09.089>.
- [2] *A. Berman and R. J. Plemmons*, *Nonnegative Matrices in the Mathematical Sciences*, Classics in Applied Mathematics, SIAM, Philadelphia, 1994.
- [3] *R. Bru, C. Corral, I. Giménez, and J. Mas*, Classes of general H -matrices, *Linear Algebra Appl.* **429** (2008), no. 10, 2358–2366; Available online at <http://dx.doi.org/10.1016/j.laa.2007.10.030>.
- [4] *M. T. Darvishi and P. Hessari*, On convergence of the generalized AOR method for linear systems with diagonally dominant coefficient matrices, *Appl. Math. Comput.* **176** (2006), no. 1, 128–133; Available online at <http://dx.doi.org/10.1016/j.amc.2005.09.051>.
- [5] *F. O. Farid*, Notes on matrices with diagonally dominant properties, *Linear Algebra Appl.* **435** (2011), no. 11, 2793–2812; Available online at <http://dx.doi.org/10.1016/j.laa.2011.04.045>.
- [6] *T.-B. Gan and T.-Z. Huang*, Simple criteria for nonsingular H -matrices, *Linear Algebra Appl.* **374** (2003), 317–326; Available online at [http://dx.doi.org/10.1016/S0024-3795\(03\)00646-3](http://dx.doi.org/10.1016/S0024-3795(03)00646-3).
- [7] *T. Han, Q. Lu, Z. Xu, and Y. E. Du*, Some new criteria for nonsingular H -matrices, *Gōngchéng Shùxué Xuébào* (Chinese J. Engrg. Math.) **28** (2011), no. 4, 498–504. (Chinese)
- [8] *T.-Z. Huang*, A note on generalized diagonally dominant matrices, *Linear Algebra Appl.* **225** (1995), 237–242; Available online at [http://dx.doi.org/10.1016/0024-3795\(93\)00368-A](http://dx.doi.org/10.1016/0024-3795(93)00368-A).
- [9] *T.-Z. Huang and C. X. Xu*, Generalized α -diagonal dominance, *Comput. Math. Appl.* **45** (2003), no. 10-11, 1721–1727; Available online at [http://dx.doi.org/10.1016/S0898-1221\(03\)00150-0](http://dx.doi.org/10.1016/S0898-1221(03)00150-0).
- [10] *C. Y. Leng*, Criteria for non-singular H -matrices, *Yìngyòng Shùxué Xuébào* (Acta Math. Appl. Sin.) **34** (2011), no. 1, 50–56. (Chinese)
- [11] *W. Li*, The infinity norm bound for the inverse of non-singular diagonal dominant matrices, *Appl. Math. Lett.* **21** (2008), no. 3, 258–263; Available online at <http://dx.doi.org/10.1016/j.aml.2007.03.018>.
- [12] *B.-S. Li, L. Li, M. Harada, H. Niki, and M. J. Tsatsomeros*, An iterative criterion for H -matrices, *Linear Algebra Appl.* **271** (1998), 179–190; Available online at [http://dx.doi.org/10.1016/S0024-3795\(98\)90070-2](http://dx.doi.org/10.1016/S0024-3795(98)90070-2).
- [13] *M. Li and Y.-X. Sun*, Practical criteria for H -matrices, *Appl. Math. Comput.* **211** (2009), no. 2, 427–433; Available online at <http://dx.doi.org/10.1016/j.amc.2009.01.083>.
- [14] *J.-Z. Liu, Y.-Q. Huang, and F.-Z. Zhang*, The Schur complements of generalized doubly diagonally dominant matrices, *Linear Algebra Appl.* **378** (2004) 231–244; Available online at <http://dx.doi.org/10.1016/j.laa.2003.09.012>.
- [15] *J.-Z. Liu and A.-Q. He*, Simple criteria for generalized diagonally dominant matrices, *Int. J. Comput. Math.* **85** (2008), no. 7, 1065–1072; Available online at <http://dx.doi.org/10.1080/00207160701472469>.

- [16] *J.-Z. Liu and F.-Z. Zhang*, Criteria and Schur complements of H -matrices, *J. Appl. Math. Comput.* **32** (2010), no. 1, 119–133; Available online at <http://dx.doi.org/10.1007/s12190-009-0237-6>.
- [17] *K. Ojiro, H. Niki, and M. Usui*, A new criterion for the H -matrix property, *J. Comput. Appl. Math.* **150** (2003), no. 2, 293–302; Available online at [http://dx.doi.org/10.1016/S0377-0427\(02\)00666-0](http://dx.doi.org/10.1016/S0377-0427(02)00666-0).
- [18] *M.-X. Pang*, A criterion for generalized diagonal dominance of matrices and its application, *Chinese Ann. Math. Ser. A* **6** (1985), no. 3, 323–330. (Chinese. An English summary appears in *Chinese Ann. Math. Ser. B* **6** (1985), no. 3, 376.)
- [19] *R. S. Varga*, On recurring theorems on diagonal dominance, *Linear Algebra Appl.* **13** (1976), no. 1-2, 1–9.
- [20] *L.-L. Wang, B.-Y. Xi, and F. Qi*, Necessary and sufficient conditions for identifying strictly geometrically α -bidiagonally dominant matrices, *Politehn. Univ. Bucharest Sci. Bull. Ser. A Appl. Math. Phys.* **76** (2014), no. 4, 57–66.
- [21] *J. Wang, Z. Xu, and Q. Lu*, A set of new criteria for generalized strictly diagonally dominant matrices, *Math. Numer. Sin.* **33** (2011), no. 3, 225–232. (Chinese)