

ON α -LOCALLY DOUBLY DIAGONALLY DOMINANT MATRICES

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In the paper, the authors introduce a new type of α -locally doubly diagonally dominant matrices, which is indeed a new subclass of H -matrices, present several new criteria for judging non-singular H -matrices according to the theory of the new type of α -locally doubly diagonally dominant matrices, and illustrate effectiveness and advantages of the proposed criteria by some numerical examples.

Keywords: non-singular H -matrix, α -locally doubly diagonally dominant matrix, criteria, irreducibility, non-zero element chain, numerical example

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1. Introduction

It is well known that H -matrices play an important role in the matrix theory, computational mathematics, and mathematical physics. See [1, 2, 11]. In recent years, a lot of work devoted to giving direct and iterative criteria for judging whether a certain matrix A is a non-singular H -matrix or not. See [3, 5, 6, 7, 8, 9, 10, 12, 13, 15, 16, 17, 18, 19, 20, 21]. In practice, if the coefficient matrix A of the linear system $Ax = b$ is an H -matrix, then many classical iterative methods are convergent. See [2, Chapters 7] and [4]. Therefore, it is significant to look for numerical methods of judging non-singular H -matrices and to provide effective and practical criteria.

In this paper, we will introduce a new type of α -locally doubly diagonally dominant matrices, present several new criteria for non-singular H -matrices, and illustrate effectiveness and advantages of the proposed criteria by numerical examples.

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2. Definitions and lemmas

We recall some notation, definitions, and lemmas.

Let $\mathbb{C}^{n \times n}$ be the set of all $n \times n$ complex matrices, \mathbb{N} the set of all positive integers, and $A = (a_{ij}) \in \mathbb{C}^{n \times n}$. For $i \in \mathbb{N}$, let

$$P_i(A) = \sum_{j \neq i} |a_{ij}|, \quad R_i(A) = \sum_{j \neq i} |a_{ji}|, \quad q_i = \frac{P_i(A)}{|a_{ii}|}.$$

Definition 2.1 ([17, p. 294]). Let $A = (a_{ij}) \in \mathbb{C}^{n \times n}$. The comparison matrix of A , denoted by $\mu(A) = (m_{ij})_{n \times n}$, is defined by

$$m_{ij} = \begin{cases} |a_{ij}|, & i = j, \\ -|a_{ij}|, & i \neq j. \end{cases}$$

A matrix A is said to be an M -matrix if $A = \mu(A)$ and the real parts of eigenvalues of A are positive. A matrix A is said to be an H -matrix if $\mu(A)$ is an M -matrix.

Remark 1. By Definition 2.1, it is easy to see that every H -matrix is non-singular. If A is an H -matrix such that $\mu(A)$ is non-singular, then all diagonal entries of A are non-zero. See [3, p. 2361]. Thus, in what follows, we always assume that $a_{ii} \neq 0$ for all $i \in \mathbb{N}$.

Definition 2.2 ([5, Definition 1.1], [14, p. 233], and [16, p. 120]). A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is called to be (row) diagonally dominant, denoted by $A \in D_0$, if

$$|a_{ii}| \geq P_i(A), \quad i \in \mathbb{N}. \quad (2.1)$$

A matrix A is said to be strictly diagonally dominant, denoted by $A \in D$, if all the inequalities in (2.1) are strict. A matrix A is said to be generalized strictly diagonally dominant, if there exists a positive diagonal matrix X such that AX is strictly diagonally dominant.

Remark 2. It was said in [6, p. 318] and [16, p. 120] that A is a non-singular H -matrix if and only if A is a generalized strictly diagonally dominant matrix.

Definition 2.3 ([5, Definition 1.1]). If \mathbb{N}_1 and \mathbb{N}_2 are non-empty, proper, and disjoint subsets of \mathbb{N} such that $\mathbb{N}_1 \cup \mathbb{N}_2 = \mathbb{N}$, then we say that $(\mathbb{N}_1, \mathbb{N}_2)$ is a separation of \mathbb{N} .

Definition 2.4 ([19, p. 3]). A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be irreducibly diagonally dominant if it is irreducible and at least one of the inequalities in (2.1) strictly holds.

Definition 2.5 ([6, Definition 2]). A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is called diagonally dominant with non-zero element chain, if the inequality (2.1) is valid for all $i \in \mathbb{N}$, where at least one strictly inequality holds and, for every i with $|a_{ii}| = P_i(A)$, there exists a non-zero elements chain $a_{ij_1} a_{j_1 j_2} \dots a_{j_{k-1} j_k} \neq 0$ such that $|a_{j_k j_k}| > P_{j_k}(A)$.

Definition 2.6 ([9, Definition 1]). Let $\alpha \in [0, 1]$, $A = (a_{ij}) \in \mathbb{C}^{n \times n}$, and $(\mathbb{N}_1, \mathbb{N}_2)$ be a separation of \mathbb{N} . If, for all $i \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$,

$$|a_{jj}| - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| > 0$$

and

$$\begin{aligned} \left(P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t \right)^\alpha \left(|a_{jj}| - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| \right)^{1-\alpha} \\ > \left(\sum_{t \in \mathbb{N}_1} |a_{jt}| q_t \right)^{1-\alpha} \left(\sum_{t \in \mathbb{N}_2} |a_{it}| \right)^\alpha, \end{aligned}$$

then A is said to be an α -SGD matrix.

We also need the following lemmas.

Lemma 2.1 ([19, Theorem 1]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is irreducibly diagonally dominant, then A is a non-singular H -matrix.*

Lemma 2.2 ([6, p. 322]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is a diagonally dominant matrix with non-zero element chain, then A is a non-singular H -matrix.*

Lemma 2.3 ([9, Theorem 1]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is an α -SGD matrix, then A is a non-singular H -matrix.*

Lemma 2.4 ([8, p. 241] and [18, Theorem 1]). *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is a non-singular H -matrix, then there exists at least one $i \in \mathbb{N}$ such that $|a_{ii}| > P_i(A)$.*

Lemma 2.5 ([6, Lemma 1]). *Let $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ be a matrix whose diagonal entries are non-zero, $\delta = \{i | i \in \mathbb{N}, P_i(A) > 0\}$, and $A(\delta)$, whose rows and columns are indexed by δ , a sub-matrix of A . Then A is a non-singular H -matrix if and only if $A(\delta)$ is a non-singular H -matrix.*

3. Main results

We first introduce a new type of α -locally doubly diagonally dominant matrices as follows.

Definition 3.1. Let $\alpha \in [0, 1]$ and $(\mathbb{N}_1, \mathbb{N}_2)$ be a separation of \mathbb{N} . A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be strictly α -locally doubly diagonally dominant, denoted by $A \in SLDD(\alpha)$, if

$$P_i(A) > \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}| q_t, \quad P_j(A) > \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}| q_t,$$

and

$$\begin{aligned}
& \left(P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t \right)^\alpha \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right)^{1-\alpha} \\
& > \left(\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \right)^\alpha \left(\sum_{t \in \mathbb{N}_1} |a_{jt}|q_t \right)^{1-\alpha} \quad (3.1)
\end{aligned}$$

hold for all $i \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$.

Definition 3.2. An irreducible matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be irreducibly α -locally doubly diagonally dominant if

- (1) the inequalities in (3.1) hold with \geq instead of $>$,
- (2) at least one of the inequalities in (3.1) strictly holds, and
- (3) A satisfies other conditions of Definition 3.1.

Definition 3.3. A matrix $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is said to be α -locally doubly diagonally dominant with a non-zero element chain if

- (1) the inequalities in (3.1) hold with \geq instead of $>$,
- (2) for all $i \in \{i_1, \dots, i_k\} \cup \{j_1, \dots, j_l\}$, there exist a non-zero element chain $a_{ir_1}a_{r_1r_2} \dots a_{r_li^*} \neq 0$ such that $i^* \in (\mathbb{N}_1 \setminus \{i_1, \dots, i_k\}) \cup (\mathbb{N}_2 \setminus \{j_1, \dots, j_l\}) \neq \emptyset$ and

$$\begin{aligned}
& \left(P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t \right)^\alpha \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right)^{1-\alpha} \\
& = \left(\sum_{t \in \mathbb{N}_1} |a_{jt}|q_t \right)^\alpha \left(\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \right)^{1-\alpha} \quad (3.2)
\end{aligned}$$

hold for all $i \in \{i_1, \dots, i_k\} \subset \mathbb{N}_1$ and $j \in \{j_1, \dots, j_l\} \subset \mathbb{N}_2$, and

- (3) A satisfies other conditions of Definition 3.1.

Now we start off to provide some new criteria for non-singular H -matrices.

Theorem 3.1. Let $A = (a_{ij}) \in \mathbb{C}^{n \times n}$. If $A \in SLDD(\alpha)$, then A is a non-singular H -matrix.

Proof. If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \neq 0$ for $i \in \mathbb{N}_1$, since $A \in SLDD(\alpha)$, then there exists a positive number d such that

$$\min_{i \in \mathbb{N}_1} K_i > d > \max_{j \in \mathbb{N}_2} k_j, \quad (3.3)$$

where

$$K_i = \frac{P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t}{\sum_{t \in \mathbb{N}_2} |a_{it}|q_t} \quad \text{and} \quad k_j = \frac{\sum_{t \in \mathbb{N}_1} |a_{jt}|q_t}{P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t}$$

for $i \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$.

Let

$$x_t = \begin{cases} q_t, & t \in \mathbb{N}_1, \\ dq_t, & t \in \mathbb{N}_2, \end{cases} \quad X = \text{diag}(x_1, x_2, \dots, x_n), \quad B = AX = (b_{ij})_{n \times n}. \quad (3.4)$$

For $i \in \mathbb{N}_1$, the double inequality (3.3) implies that

$$\begin{aligned} |b_{ii}| - P_i(B) &= P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - d \sum_{t \in \mathbb{N}_2} |a_{it}|q_t \\ &> P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - K_i \sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0. \end{aligned}$$

For $j \in \mathbb{N}_2$, the double inequality (3.3) means that

$$\begin{aligned} |b_{jj}| - P_j(B) &= d \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t \\ &> k_j \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t = 0. \end{aligned}$$

Then $|b_{ii}| > P_i(B)$ for $i \in \mathbb{N}$. Hence, A is a non-singular H -matrix in this case.

If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$ for $i \in \mathbb{N}_1$, by Definition 3.1, we have $P_j(A) > \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t$ for all $j \in \mathbb{N}_2$. Consequently, there exists $d > 0$ satisfying

$$d \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) > \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t. \quad (3.5)$$

Making use of (3.4) to (3.5) yields $|b_{ii}| > P_i(B)$ for $i \in \mathbb{N}$. Therefore, A is a non-singular H -matrix. The proof of Theorem 3.1 is completed. \square

Theorem 3.2. *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is an irreducibly α -locally doubly diagonally dominant matrix, then A is a non-singular H -matrix.*

Proof. In view of the irreducibility of A , there exists $a_{jt} \neq 0$ for $t \in \mathbb{N}_1$ and $j \in \mathbb{N}_2$.

If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$ for $i \in \mathbb{N}_1$, by Definition 3.2, it is easy to see that A is a non-singular H -matrix.

If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \neq 0$ for $i \in \mathbb{N}_1$, by the same arguments as above, we have

$$d \triangleq \min_{i \in \mathbb{N}_1} K_i = \max_{j \in \mathbb{N}_2} k_j, \quad (3.6)$$

which means that $d > 0$.

From (3.4) and (3.6), it follows that

$$|b_{ii}| - P_i(B) = P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - d \sum_{t \in \mathbb{N}_2} |a_{it}|q_t$$

$$\geq P_i(A) - \sum_{\substack{t \in \mathbb{N}_1 \\ t \neq i}} |a_{it}|q_t - K_i \sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$$

for $i \in \mathbb{N}_1$ and that

$$\begin{aligned} |b_{jj}| - P_j(B) &= d|a_{jj}|q_j - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t - d \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \\ &= d \left(P_j(A) - \sum_{\substack{t \in \mathbb{N}_2 \\ t \neq j}} |a_{jt}|q_t \right) - \sum_{t \in \mathbb{N}_1} |a_{jt}|q_t \geq 0 \end{aligned}$$

for $j \in \mathbb{N}_2$. Consequently, by Definition 3.2, it follows that $|b_{ii}| \geq P_i(B)$ for all $i \in \mathbb{N}$, in which at least one strict inequality is valid. Since A is irreducible, then B is an irreducibly diagonally dominant matrix. Thus, in light of Lemma 2.1, we obtain that B is a non-singular H -matrix, and so is A . The proof of Theorem 3.2 is completed. \square

Theorem 3.3. *If $A = (a_{ij}) \in \mathbb{C}^{n \times n}$ is an α -locally doubly diagonally dominant matrix with a non-zero elements chain, then A is a non-singular H -matrix.*

Proof. If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t = 0$ for all $i \in \mathbb{N}_1$, then it is easy to see that A is a non-singular H -matrix. If $\sum_{t \in \mathbb{N}_2} |a_{it}|q_t \neq 0$ for $i \in \mathbb{N}_1$, by similar arguments as above, we obtain $d \triangleq \min_{i \in \mathbb{N}_1} K_i = \max_{j \in \mathbb{N}_2} k_j > 0$. Utilizing (3.2) and (3.4), by Definition 3.3, we obtain $|b_{ii}| - P_i(B) \geq 0$ for $i \in \{j_1, \dots, j_l\} \cup \{i_1, \dots, i_k\}$, that is, $|b_{ii}| \geq P_i(B)$ for $i \in (\mathbb{N}_1 \setminus \{i_1, \dots, i_k\}) \cup (\mathbb{N}_2 \setminus \{j_1, \dots, j_l\})$. This means that B is a diagonally dominant matrix with non-zero elements chain. Furthermore, by Lemma 2.2, we obtain that B is a non-singular H -matrix, and so is A . The proof of Theorem 3.3 is completed. \square

Remark 3. From Theorem 3.1, we find that the type of α -locally doubly diagonally dominant matrices is a subclass of H -matrices. Hence, the introduction of α -locally doubly diagonally dominant matrices well extends the theory of H -matrices.

4. Numerical Examples

We now illustrate effectiveness and advantages of the above proposed criteria by several numerical examples.

Example 4.1. Let

$$A = \begin{bmatrix} 3 & 2 & 6 & 0 \\ 1 & 6.8 & 3 & 4 \\ 1 & 2 & 9 & 4 \\ 0 & 2 & 2 & 8 \end{bmatrix}$$

and $(\mathbb{N}_1, \mathbb{N}_2)$ be a separation of $\mathbb{N} = \{1, 2, 3, 4\}$. If \mathbb{N}_1 and \mathbb{N}_2 satisfy one of the following cases:

$$\begin{aligned} \mathbb{N}_1 &= \{1\}, \quad \mathbb{N}_2 = \{2, 3, 4\}; \quad \mathbb{N}_1 = \{2\}, \quad \mathbb{N}_2 = \{1, 3, 4\}; \quad \mathbb{N}_1 = \{3\}, \\ \mathbb{N}_2 &= \{1, 2, 4\}; \quad \mathbb{N}_1 = \{4\}, \quad \mathbb{N}_2 = \{1, 2, 3\}; \quad \mathbb{N}_1 = \{1, 2\}, \quad \mathbb{N}_2 = \{3, 4\}; \end{aligned}$$

$$\begin{aligned} \mathbb{N}_1 = \{1, 3\}, \quad \mathbb{N}_2 = \{2, 4\}; \quad \mathbb{N}_1 = \{1, 4\}, \quad \mathbb{N}_2 = \{2, 3\}; \quad \mathbb{N}_1 = \{2, 3\}, \\ \mathbb{N}_2 = \{1, 4\}; \quad \mathbb{N}_1 = \{2, 4\}, \quad \mathbb{N}_2 = \{1, 3\}; \end{aligned}$$

then A is not an α -SGD matrix and does not satisfy the corresponding conditions in [9, Theorem 1]. But, when \mathbb{N}_1 and \mathbb{N}_2 satisfy one of the above cases, by Theorem 3.1, it is easy to see that A is a non-singular H -matrix.

Example 4.2. Consider

$$A = \begin{bmatrix} 3 & 2 & 6 & 0 \\ 1 & 6.8 & 3 & 4 \\ 1 & 2 & 9 & 4 \\ 0 & 2 & 2 & 10 \end{bmatrix}.$$

By [15, Theorems 2.1 and 2.2], we have

$$\begin{aligned} r_1 &= \min \left\{ \frac{\alpha_3 - \gamma_3}{|a_{33}| - \gamma_3}, \frac{\alpha_4 - \gamma_4}{|a_{44}| - \gamma_4} \right\} = \min \left\{ \frac{12}{37}, \frac{1}{19} \right\} = \frac{1}{19}, \\ r_2 &= \max \left\{ \frac{\beta_3}{\alpha_3 + \beta_3 - \gamma_3}, \frac{\beta_4}{\alpha_4 + \beta_4 - \gamma_4} \right\} = \max \left\{ \frac{5}{9}, \frac{9}{11} \right\} = \frac{9}{11}. \end{aligned}$$

Since $|a_{11}| = 3 < |a_{13}|(\delta_3 - r_1) + |a_{14}|(\delta_4 - r_1) + \beta_1 = 6.350\dots$, the matrix A does not satisfy the corresponding conditions in [15, Theorem 2.1]. Since $|a_{11}| = 3 < r_2(|a_{13}|\delta_3 + |a_{14}|\delta_4) + \beta_1 = 5.818\dots$, the matrix A does not satisfy the corresponding conditions in [15, Theorem 2.2] yet.

In virtue of [13, Theorem 2], we obtain

$$\begin{aligned} M_1 &= \{(2, 3)\}, \quad M_2 = \{(1, 2), (1, 3), (1, 4)\}, \\ M_3 &= \{(2, 4), (3, 4)\}, \quad M_4 = M_5 = M_6 = \emptyset, \end{aligned}$$

and

$$\begin{aligned} \frac{R_2(A)R_3(A) - |a_{22}a_{33}|}{R_2(A)R_3(A) - P_2(A)P_3(A)} &= 0.48, \\ \frac{|a_{11}a_{22}| - R_1(A)R_2(A)}{P_1(A)P_2(A) - R_1(A)R_2(A)} &= 0.161\dots, \\ \frac{|a_{11}a_{33}| - R_1(A)R_3(A)}{P_1(A)P_3(A) - R_1(A)R_3(A)} &= 0.147\dots, \\ \frac{|a_{11}a_{44}| - R_1(A)R_4(A)}{P_1(A)P_4(A) - R_1(A)R_4(A)} &= 0.875. \end{aligned}$$

Obviously,

$$\begin{aligned} \max_{(s,t) \in M_1} \frac{R_s(A)R_t(A) - |a_{ss}||a_{tt}|}{R_s(A)R_t(A) - P_s(A)P_t(A)} &= 0.48 \\ &> \min_{(i,j) \in M_2} \frac{|a_{ii}||a_{jj}| - R_i(A)R_j(A)}{P_i(A)P_j(A) - R_i(A)R_j(A)} = 0.147\dots \end{aligned}$$

Therefore, the matrix A does not satisfy the conditions of [13, Theorem 2].

Nevertheless, if we choose $\mathbb{N}_1 = \{1, 2\}$, $\mathbb{N}_2 = \{3, 4\}$, and $\alpha = \frac{1}{2}$, then

$$[P_1(A) - |a_{12}|q_2]^\alpha [P_3(A) - |a_{34}|q_4]^{1-\alpha} = 5.522\dots,$$

$$\begin{aligned}
& [|a_{13}|q_3 + |a_{14}|q_4]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 4.839 \dots, \\
& [P_1(A) - |a_{12}|q_2]^\alpha [P_4(A) - |a_{43}|q_3]^{1-\alpha} = 3.715 \dots, \\
& [|a_{13}|q_3 + |a_{14}|q_4]^\alpha [|a_{41}|q_1 + |a_{42}|q_2]^{1-\alpha} = 3.313 \dots, \\
& [P_2(A) - |a_{21}|q_1]^\alpha [P_3(A) - |a_{34}|q_4]^{1-\alpha} = 5.366 \dots, \\
& [|a_{23}|q_3 + |a_{24}|q_4]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 4.443 \dots, \\
& [P_2(A) - |a_{21}|q_1]^\alpha [P_4(A) - |a_{43}|q_3]^{1-\alpha} = 3.610 \dots, \\
& [|a_{23}|q_3 + |a_{24}|q_4]^\alpha [|a_{41}|q_1 + |a_{42}|q_2]^{1-\alpha} = 3.042 \dots
\end{aligned}$$

By Theorem 3.1, we derive that A is a non-singular H -matrix.

Example 4.3. Let

$$A = \begin{bmatrix} 4 & 0.5 & 6 \\ 2 & 12 & 8 \\ 2 & 10 & 14 \end{bmatrix}.$$

(1) In view of [10], we easily obtain the following conclusions:

- (a) When $k = 1$, we acquire $S_1 + S_2 + S_3 = 1 + \frac{5}{12} > 1$.
- (b) When $k = 2$, for a separation $(\mathbb{N}_1, \mathbb{N}_2)$ of $\mathbb{N} = \{1, 2, 3\}$,
 - (i) if $\mathbb{N}_1 = \{1\}$ and $\mathbb{N}_2 = \{2, 3\}$, then $S_1 = \frac{3}{2} > 1$;
 - (ii) if $\mathbb{N}_1 = \{2\}$ and $\mathbb{N}_2 = \{1, 3\}$, then $S_1 + S_3 = \frac{7}{5} > 1$;
 - (iii) if $\mathbb{N}_1 = \{3\}$ and $\mathbb{N}_2 = \{1, 2\}$, then $S_1 + S_2 = \frac{191}{140} > 1$.
- (c) When $k = 3$, it is easy to see that $S_1 = \frac{13}{8} > 1$.

Therefore, the matrix A does not satisfy the corresponding conditions in [10, Theorem 1].

(2) It is not difficult to realize that the matrix A does not satisfy the corresponding conditions in [7, Theorem 1] and [21, Theorems 1 and 2].

Nevertheless, if we choose $\mathbb{N}_1 = \{1, 2\}$, $\mathbb{N}_2 = \{3\}$, and $\alpha = \frac{1}{2}$, then

$$\begin{aligned}
& [P_1(A) - |a_{12}|q_2]^\alpha [P_3(A)]^{1-\alpha} = 8.544 \dots, \\
& [|a_{13}|q_3]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 7.718 \dots, \\
& [P_2(A) - |a_{21}|q_1]^\alpha [P_3(A)]^{1-\alpha} = 9, \\
& [|a_{23}|q_3]^\alpha [|a_{31}|q_1 + |a_{32}|q_2]^{1-\alpha} = 8.912 \dots
\end{aligned}$$

Using Theorem 3.1 gives that A is a non-singular H -matrix.

5. Conclusions

In conclusion, a new type of α -locally doubly diagonally dominant matrices are introduced, which is now known as a subclass of non-singular H -matrices. Moreover, the authors establish several new and practical criteria for judging non-singular H -matrices by involved matrices. Consequently, the criteria for identifying nonsingular H -matrices is well extended.

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