

## A COMPOSITE SPLITTING ALGORITHM FOR SOLVING FIXED POINT AND VARIATIONAL INCLUSION PROBLEMS IN HILBERT SPACES

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*In this paper, we present a composite splitting method for solving fixed point and variational inclusion problems in a real Hilbert space. The introduced method consists of forward-backward method, Tseng-type method and self-adaptive method. Under some additional conditions, we prove that the sequence generated by the splitting method strongly converges to a solution of fixed point and variational inclusion problems.*

**Keywords:** fixed point, variational inclusion, monotone operator, pseudocontraction.

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### 1. Introduction

Let  $\mathcal{H}$  be a real Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and induced norm  $\|\cdot\|$ . Let  $g : \mathcal{H} \rightrightarrows 2^{\mathcal{H}}$  be a set-valued operator and  $h : \mathcal{H} \rightarrow \mathcal{H}$  be a single-valued operator. In this paper, we investigate the variational inclusion problem which aims to find a point  $u^\dagger \in \mathcal{H}$  such that

$$0 \in (g + h)(u^\dagger). \quad (1)$$

The reason why we are interested in the variational inclusion problem (1) is that is closely related to the following well-known minimization problem

$$\min_{x \in \mathcal{H}} \{G(x) + H(x)\}, \quad (2)$$

where  $G, H : \mathcal{H} \rightarrow \mathbf{R} \cup \{+\infty\}$  are two proper, lower semicontinuous and convex functions such that  $G$  is subdifferentiable and  $H$  is differentiable. As a matter of fact, if set  $g = \partial G$  and  $h = \nabla H$ , then solving (2) is equivalent to solving (1).

Now, it is well known that variational inclusion problems offer a model framework for discussing many interesting problems, such as fixed point problems ([19–21, 27]), optimization problems ([12, 17, 18, 24]), split problems ([10, 11, 29, 31, 32, 34, 39]), equilibrium problems ([30, 48]) and variational inequalities ([3, 4, 28, 33, 35–38, 41, 42, 46]). Numerous iterative algorithms are studied and designed for finding a solution of the variational inclusion (1), see [1, 2, 7, 8, 16, 43, 45]. Especially, an interesting algorithm for solving (1) is the forward-backward algorithm ([13–15]) which generates a sequence  $\{x_n\}$  as follows:  $x_0 \in \mathcal{H}$ ,

$$x_{n+1} = (I + \varpi_n g)^{-1}(I - \varpi_n h)(x_n), \quad n \geq 0, \quad (3)$$

where  $\varpi_n$  is a positive constant for all  $n \geq 0$ .

In the sequel, we use  $(g + h)^{-1}(0)$  to stand for the solution set of the variational inclusion (1). If  $g$  is maximal monotone and  $h$  is strongly monotone or inverse strongly monotone, then the sequence  $\{x_n\}$  generated by (3) converges weakly to some point in

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$(g + h)^{-1}(0)$ . Recently, Cholamjiak, Hieu and Cho [6] combined forward-backward method and Tseng's method ([23]) for solving (1) where the operator  $h$  is plain monotone.

In this paper, we consider a fixed point problem of finding a point  $u^\dagger \in \mathcal{H}$  such that

$$f(u^\dagger) = u^\dagger, \quad (4)$$

where  $f : \mathcal{H} \rightarrow \mathcal{H}$  is a pseudocontractive operator. Use  $\text{Fix}(f)$  to denote the solution set of (4). We are interested in pseudocontractive operators due to this kind of operators is closely related to monotone or/and accretive operators ([5, 9]). There are many iterative algorithms for solving fixed point problem (4), see [22, 25, 44].

Motivated and inspired by the work in the literature, in this paper we consider a common problem of finding a point  $u^\dagger \in \mathcal{H}$  such that

$$u^\dagger \in (g + h)^{-1}(0) \cap \text{Fix}(f). \quad (5)$$

We present a composite splitting method for solving fixed point of pseudocontractive operator and variational inclusion problems in a real Hilbert space  $\mathcal{H}$ . The introduced method consists of forward-backward method, Tseng-type method and self-adaptive method. Under some additional conditions, we prove that the sequence generated by the splitting method strongly converges to a point in  $(g + h)^{-1}(0) \cap \text{Fix}(f)$ .

## 2. Preliminaries

Let  $\mathcal{H}$  be a real Hilbert space. Use “ $\rightharpoonup$ ” and “ $\rightarrow$ ” to denote weak convergence and strong convergence, respectively. Let  $\{x_n\} \subset \mathcal{H}$  be a sequence. Write  $\omega_w(x_n) = \{x^\dagger : \exists \{x_{n_i}\} \subset \{x_n\} \text{ such that } x_{n_i} \rightharpoonup x^\dagger (i \rightarrow \infty)\}$ .

Recall that an operator  $f : \mathcal{H} \rightarrow \mathcal{H}$  is said to be pseudocontractive if

$$\langle f(u) - f(u^\dagger), u - u^\dagger \rangle \leq \|u - u^\dagger\|^2, \quad \forall u, u^\dagger \in \mathcal{H}. \quad (6)$$

Note that the inequality (2) is equivalent to

$$\begin{aligned} \|f(u) - f(u^\dagger)\|^2 &\leq \|u - u^\dagger\|^2 + \|(I - f)u - (I - f)u^\dagger\|^2, \\ \Leftrightarrow \langle u - u^\dagger, (I - f)u - (I - f)u^\dagger \rangle &\geq 0, \end{aligned}$$

for all  $u, u^\dagger \in \mathcal{H}$ .

Let  $h : \mathcal{H} \rightarrow \mathcal{H}$  be a mapping.  $h$  is said to be

- (i) monotone if  $\langle h(x) - h(y), x - y \rangle \geq 0, \forall x, y \in \mathcal{H}$ .
- (ii)  $L$ -Lipschitz continuous if  $\|h(x) - h(y)\| \leq L\|x - y\|, \forall x, y \in \mathcal{H}$ , where  $L > 0$  is a constant. If  $L < 1$ , then  $h$  is said to be  $L$ -contractive.

Recall that a bounded linear operator  $B : \mathcal{H} \rightarrow \mathcal{H}$  is said to be  $\sigma$ -strongly positive if there exists a constant  $\sigma > 0$  such that  $\langle B(x), x \rangle \geq \sigma\|x\|^2, \forall x \in \mathcal{H}$ .

Let  $g : \mathcal{H} \rightrightarrows 2^{\mathcal{H}}$  be a mapping.  $g$  is said to be monotone if and only if  $\forall p, q \in \mathcal{H}, \langle p - q, u - v \rangle \geq 0$  where  $u \in g(p)$  and  $v \in g(q)$ . A monotone operator  $g$  is said to be maximal monotone if and only if its graph is not strictly contained in the graph of any other monotone operator. Let  $g : \mathcal{H} \rightarrow 2^{\mathcal{H}}$  be a maximal monotone operator. Define its resolvent  $\text{Res}_\varpi^g : \mathcal{H} \rightarrow \mathcal{H}$  by  $\text{Res}_\varpi^g := (I + \varpi g)^{-1}$  where  $\varpi > 0$  is any constant. It is well-known that  $\text{Res}_\varpi^g$  is a single-valued operator and  $x \in (g + h)^{-1}(0) \Leftrightarrow x = \text{Res}_\varpi^g(I - \varpi h)(x)$ .

Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $\mathcal{H}$ . Recall the orthogonal projection  $\text{proj}_C : \mathcal{H} \rightarrow C$ , denoted by  $\text{proj}_C(x) := \arg \min_{y \in C} \|x - y\|$  satisfies the following inequality ([40])

$$x \in \mathcal{H}, \langle x - \text{proj}_C(x), y - \text{proj}_C(x) \rangle \leq 0, \quad \forall y \in C. \quad (7)$$

In any Hilbert space  $\mathcal{H}$ ,  $\forall u, u^\dagger \in \mathcal{H}$  and  $\forall \varsigma \in \mathcal{R}$ , we have

$$\|\varsigma u + (1 - \varsigma)u^\dagger\|^2 = \varsigma\|u\|^2 + (1 - \varsigma)\|u^\dagger\|^2 - \varsigma(1 - \varsigma)\|u - u^\dagger\|^2. \quad (8)$$

**Lemma 2.1** ([30, 47]). *Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $\mathcal{H}$ . Let  $f : C \rightarrow C$  be an  $L$ -Lipschitz pseudocontractive operator. Then,*

- (i)  $f$  is demiclosed, i.e.,  $u_n \rightharpoonup \tilde{z}$  and  $f(u_n) \rightarrow z^\dagger \Rightarrow f(\tilde{z}) = z^\dagger$ .
- (ii)  $\forall \tilde{u} \in C$  and  $u^\dagger \in \text{Fix}(f)$ , we have

$$\|f[(1-\tau)\tilde{u} + \tau f(\tilde{u})] - u^\dagger\|^2 \leq \|\tilde{u} - u^\dagger\|^2 + (1-\tau)\|f[(1-\tau)\tilde{u} + \tau f(\tilde{u})] - \tilde{u}\|^2,$$

where  $0 < \tau < \frac{1}{\sqrt{1+L^2}+1}$ .

**Lemma 2.2** ([26]). *Suppose that  $\{a_n\} \subset (0, \infty)$ ,  $\{b_n\} \subset (0, 1)$  and  $\{c_n\}$  are three real number sequences. Suppose that  $a_{n+1} \leq (1-b_n)a_n + a_n c_n, \forall n \geq 0$ ,  $\sum_{n=1}^{\infty} b_n = \infty$  and  $\limsup_{n \rightarrow \infty} c_n \leq 0$ . Then  $\lim_{n \rightarrow \infty} a_n = 0$ .*

### 3. Main results

In this section, we introduce an iterative algorithm and prove that it converges strongly to an element in  $\text{Fix}(f) \cap (g+h)^{-1}$ . Let  $\mathcal{H}$  be a real Hilbert space. Let  $f : \mathcal{H} \rightarrow \mathcal{H}$  be an  $L_1$ -Lipschitz pseudocontractive operator and  $g : \mathcal{H} \rightarrow 2^{\mathcal{H}}$  be a maximal monotone operator. Let  $h : \mathcal{H} \rightarrow \mathcal{H}$  be an  $L_2$ -Lipschitz monotone operator and  $\varphi : \mathcal{H} \rightarrow \mathcal{H}$  be a  $\kappa$ -contractive operator. Let  $B : \mathcal{H} \rightarrow \mathcal{H}$  be a  $\sigma$ -strong positive bounded linear operator. Suppose that  $\Omega := \text{Fix}(f) \cap (g+h)^{-1} \neq \emptyset$ .

Let  $\{\varsigma_n\}_{n=0}^{\infty} \subset (0, 1]$ ,  $\{\tau_n\}_{n=0}^{\infty} \subset (0, 1)$ ,  $\{\lambda_n\}_{n=0}^{\infty} \subset (0, 1)$  and  $\{\gamma_n\}_{n=0}^{\infty} \subset (0, 1)$  be four real number sequences. Let  $\delta \in (0, 1)$  and  $\alpha \in (0, \sigma/\kappa)$  be two constants. In what follows, suppose that  $\lim_{n \rightarrow \infty} \gamma_n = 0$ ,  $\sum_{n=0}^{\infty} \gamma_n = \infty$ ,  $\{\varsigma_n\}_{n=0}^{\infty} \subset [\underline{\varsigma}, \bar{\varsigma}] \subset (0, 1]$  and  $0 < \vartheta < \lambda_n < \tau_n < \frac{1}{\sqrt{1+L_1^2}+1} (\forall n \geq 0)$ .

Next, we present an iterative algorithm for finding an element in  $\Omega$ .

**Algorithm 3.1.** *Let  $x_0 \in \mathcal{H}$  be an initial value and  $\varpi_0 > 0$  be a fixed constant.*

*Step 1. Let  $x_n$  be known. Compute*

$$\begin{cases} z_n = \text{Res}_{\varpi_n}^g(x_n - \varpi_n h(x_n)), \\ y_n = z_n - \varpi_n(h(z_n) - h(x_n)), \\ u_n = (1 - \varsigma_n)x_n + \varsigma_n y_n. \end{cases} \quad (9)$$

*Step 2. Compute*

$$\begin{cases} v_n = (1 - \tau_n)u_n + \tau_n f(u_n), \\ w_n = (1 - \lambda_n)u_n + \lambda_n f(v_n). \end{cases} \quad (10)$$

*Step 3. Compute*

$$x_{n+1} = \alpha \gamma_n \varphi(x_n) + (I - \gamma_n B)w_n. \quad (11)$$

*Step 4. Update*

$$\varpi_{n+1} = \begin{cases} \min \left\{ \varpi_n, \frac{\delta \|x_n - z_n\|}{\|h(x_n) - h(z_n)\|} \right\}, & \text{if } x_n \neq z_n, \\ \varpi_n, & \text{else.} \end{cases} \quad (12)$$

Replace  $n$  by  $n + 1$  and return to Step 1.

**Remark 3.1.** *We have the following statements: (i)  $\text{Res}_{\varpi_n}^g(x_n - \varpi_n h(x_n)) = x_n \Rightarrow x_n \in (g+h)^{-1}(0)$ . (ii)  $\varpi_n \geq \varpi_{n+1} \geq \min\{\varpi_0, \frac{\delta}{L_2}\}$  and  $\lim_{n \rightarrow \infty} \varpi_n = \varpi > 0$ . (iii) By the assumptions, we deduce that  $\text{proj}_{\Omega} \circ (I - B + \alpha \varphi)$  is contractive. Thus,  $\text{proj}_{\Omega} \circ (I - B + \alpha \varphi)$  has a unique fixed point in  $\Omega$ , denoted by  $z^\dagger$ . Therefore,  $\langle \alpha \varphi(z^\dagger) - B(z^\dagger), x - z^\dagger \rangle \leq 0, \forall x \in \Omega$ .*

**Proposition 3.1.** *The sequence  $\{x_n\}$  generated by Algorithm 3.1 is bounded.*

*Proof.* From (9), we have

$$\begin{aligned}\|y_n - z^\dagger\|^2 &= \|z_n - z^\dagger - \varpi_n(h(z_n) - h(x_n))\|^2 \\ &= \|z_n - z^\dagger\|^2 - 2\varpi_n\langle h(z_n) - h(x_n), z_n - z^\dagger \rangle + \varpi_n^2\|h(x_n) - h(z_n)\|^2.\end{aligned}\quad (13)$$

Observe that  $\|z_n - z^\dagger\|^2 = \|x_n - z^\dagger\|^2 + 2\langle z_n - x_n, z_n - z^\dagger \rangle - \|x_n - z_n\|^2$ . By (13), we get

$$\begin{aligned}\|y_n - z^\dagger\|^2 &= \|x_n - z^\dagger\|^2 - 2\varpi_n\langle h(z_n) - h(x_n), z_n - z^\dagger \rangle - \|x_n - z_n\|^2 \\ &\quad + 2\langle z_n - x_n, z_n - z^\dagger \rangle + \varpi_n^2\|h(x_n) - h(z_n)\|^2 \\ &= \|x_n - z^\dagger\|^2 + \varpi_n^2\|h(x_n) - h(z_n)\|^2 - \|x_n - z_n\|^2 \\ &\quad + 2\langle z_n - x_n - \varpi_n(h(z_n) - h(x_n)), z_n - z^\dagger \rangle.\end{aligned}\quad (14)$$

Since  $z_n = (I + \varpi_n g)^{-1}(x_n - \varpi_n h(x_n))$ ,

$$x_n - \varpi_n h(x_n) \in z_n + \varpi_n g(z_n). \quad (15)$$

It yields

$$x_n - z_n - \varpi_n(h(x_n) - h(z_n)) \in \varpi_n(g(z_n) + h(z_n)). \quad (16)$$

Since  $z^\dagger \in (g + h)^{-1}$ , we have  $0 \in \varpi_n(g + h)z^\dagger$ . By the monotonicity of  $\varpi_n(g + h)$  and (16), we obtain

$$\langle x_n - z_n - \varpi_n(h(x_n) - h(z_n)), z_n - z^\dagger \rangle \geq 0. \quad (17)$$

According to (12), we have  $\|h(x_n) - h(z_n)\| \leq \frac{\delta\|x_n - z_n\|}{\varpi_{n+1}}$ . Combining (14) with (17), we acquire

$$\|y_n - z^\dagger\|^2 \leq \|x_n - z^\dagger\|^2 - \left(1 - \delta^2 \frac{\varpi_n^2}{\varpi_{n+1}^2}\right)\|x_n - z_n\|^2. \quad (18)$$

In the light of (7) and (9), we achieve

$$\begin{aligned}\|u_n - z^\dagger\|^2 &= \|(1 - \varsigma_n)(x_n - z^\dagger) + \varsigma_n(y_n - z^\dagger)\|^2 \\ &= (1 - \varsigma_n)\|x_n - z^\dagger\|^2 + \varsigma_n\|y_n - z^\dagger\|^2 - (1 - \varsigma_n)\varsigma_n\|x_n - y_n\|^2.\end{aligned}$$

This together with (18) implies that

$$\begin{aligned}\|u_n - z^\dagger\|^2 &\leq \|x_n - z^\dagger\|^2 - \varsigma_n\left(1 - \delta^2 \frac{\varpi_n^2}{\varpi_{n+1}^2}\right)\|x_n - z_n\|^2 - (1 - \varsigma_n)\varsigma_n\|x_n - y_n\|^2 \\ &\leq \|x_n - z^\dagger\|^2.\end{aligned}\quad (19)$$

From (7), we gain

$$\begin{aligned}\|w_n - z^\dagger\|^2 &= \|(1 - \lambda_n)(u_n - z^\dagger) + \lambda_n(f(v_n) - z^\dagger)\|^2 \\ &= (1 - \lambda_n)\|u_n - z^\dagger\|^2 - \lambda_n(1 - \lambda_n)\|f(v_n) - u_n\|^2 + \lambda_n\|f(v_n) - z^\dagger\|^2.\end{aligned}\quad (20)$$

Applying Lemma 2.1, we deduce

$$\begin{aligned}\|f(v_n) - z^\dagger\|^2 &= \|f[(1 - \tau_n)u_n + \tau_n f(u_n)] - z^\dagger\|^2 \\ &\leq \|u_n - z^\dagger\|^2 + (1 - \tau_n)\|f(v_n) - u_n\|^2.\end{aligned}\quad (21)$$

Substituting (21) into (20), we receive

$$\begin{aligned}\|w_n - z^\dagger\|^2 &\leq (1 - \lambda_n)\|u_n - z^\dagger\|^2 - \lambda_n(1 - \lambda_n)\|f(v_n) - u_n\|^2 \\ &\quad + \lambda_n\|u_n - z^\dagger\|^2 + \lambda_n(1 - \tau_n)\|f(v_n) - u_n\|^2 \\ &= \|u_n - z^\dagger\|^2 - \lambda_n(\tau_n - \lambda_n)\|f(v_n) - u_n\|^2 \\ &\leq \|u_n - z^\dagger\|^2.\end{aligned}\quad (22)$$

Taking into account (11), (19) and (22), we derive

$$\begin{aligned}
\|x_{n+1} - z^\dagger\| &= \|\alpha\gamma_n\varphi(x_n) + (I - \gamma_n B)w_n - z^\dagger\| \\
&= \|\alpha\gamma_n(\varphi(x_n) - \varphi(z^\dagger)) + (I - \gamma_n B)(w_n - z^\dagger) + \gamma_n(\alpha\varphi(z^\dagger) - B(z^\dagger))\| \\
&\leq \alpha\gamma_n\|\varphi(x_n) - \varphi(z^\dagger)\| + |I - \gamma_n B|\|w_n - z^\dagger\| + \gamma_n\|\alpha\varphi(z^\dagger) - B(z^\dagger)\| \\
&\leq \alpha\gamma_n\kappa\|x_n - z^\dagger\| + (1 - \sigma\gamma_n)\|w_n - z^\dagger\| + \gamma_n\|\alpha\varphi(z^\dagger) - B(z^\dagger)\| \\
&\leq [1 - (\sigma - \alpha\kappa)\gamma_n]\|x_n - z^\dagger\| + \gamma_n\|\alpha\varphi(z^\dagger) - B(z^\dagger)\|.
\end{aligned} \tag{23}$$

By induction, we have  $\|x_n - z^\dagger\| \leq \max\{\|\alpha\varphi(z^\dagger) - B(z^\dagger)\|/(\sigma - \alpha\kappa), \|x_0 - z^\dagger\|\}$  and the sequence  $\{x_n\}$  is bounded.  $\square$

**Proposition 3.2.**  $\omega_w(x_n) \subset \text{Fix}(f)$ .

*Proof.* On account of (11), we achieve

$$\begin{aligned}
\|x_{n+1} - z^\dagger\|^2 &= \|\alpha\gamma_n(\varphi(x_n) - \varphi(z^\dagger)) + (I - \gamma_n B)(w_n - z^\dagger) + \gamma_n(\alpha\varphi(z^\dagger) - B(z^\dagger))\|^2 \\
&\leq \|(I - \gamma_n B)(w_n - z^\dagger)\|^2 + 2\alpha\gamma_n\langle\varphi(x_n) - \varphi(z^\dagger), x_{n+1} - z^\dagger\rangle \\
&\quad + 2\gamma_n\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle \\
&\leq (1 - \sigma\gamma_n)^2\|w_n - z^\dagger\|^2 + 2\alpha\kappa\gamma_n\|x_n - z^\dagger\|\|x_{n+1} - z^\dagger\| \\
&\quad + 2\gamma_n\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle \\
&\leq (1 - \sigma\gamma_n)^2\|w_n - z^\dagger\|^2 + \alpha\kappa\gamma_n\|x_n - z^\dagger\|^2 + \alpha\kappa\gamma_n\|x_{n+1} - z^\dagger\|^2 \\
&\quad + 2\gamma_n\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle.
\end{aligned}$$

It follows that

$$\begin{aligned}
\|x_{n+1} - z^\dagger\|^2 &\leq \frac{(1 - \sigma\gamma_n)^2}{1 - \alpha\kappa\gamma_n}\|w_n - z^\dagger\|^2 + \frac{\alpha\kappa\gamma_n}{1 - \alpha\kappa\gamma_n}\|x_n - z^\dagger\|^2 \\
&\quad + \frac{2\gamma_n}{1 - \alpha\kappa\gamma_n}\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle.
\end{aligned} \tag{24}$$

Substituting (19) and (22) into (24), we attain

$$\begin{aligned}
\|x_{n+1} - z^\dagger\|^2 &\leq \frac{(1 - \sigma\gamma_n)^2}{1 - \alpha\kappa\gamma_n}(\|x_n - z^\dagger\|^2 - \varsigma_n(1 - \delta^2\frac{\varpi_n^2}{\varpi_{n+1}^2})\|x_n - z_n\|^2 \\
&\quad - (1 - \varsigma_n)\varsigma_n\|x_n - y_n\|^2 - \lambda_n(\tau_n - \lambda_n)\|f(v_n) - u_n\|^2) \\
&\quad + \frac{\alpha\kappa\gamma_n}{1 - \alpha\kappa\gamma_n}\|x_n - z^\dagger\|^2 + \frac{2\gamma_n}{1 - \alpha\kappa\gamma_n}\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle.
\end{aligned}$$

It follows that

$$\begin{aligned}
\|x_{n+1} - z^\dagger\|^2 &\leq [1 - \frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n}]\|x_n - z^\dagger\|^2 + \frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n} \times \left(-\frac{(1 - \sigma\gamma_n)^2}{2(\sigma - \alpha\kappa)}\right. \\
&\quad \times \varsigma_n(1 - \delta^2\frac{\varpi_n^2}{\varpi_{n+1}^2})\frac{\|x_n - z_n\|^2}{\gamma_n} - \frac{(1 - \sigma\gamma_n)^2}{2(\sigma - \alpha\kappa)}(1 - \varsigma_n)\varsigma_n\frac{\|x_n - y_n\|^2}{\gamma_n} \\
&\quad - \frac{(1 - \sigma\gamma_n)^2}{2(\sigma - \alpha\kappa)}\lambda_n(\tau_n - \lambda_n)\frac{\|f(v_n) - u_n\|^2}{\gamma_n} + \frac{\sigma^2\gamma_n}{2(\sigma - \alpha\kappa)}M \\
&\quad \left. + \frac{1}{\sigma - \alpha\kappa}\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle\right),
\end{aligned} \tag{25}$$

where  $M$  is a constant such that  $M \geq \sup_n\{\|x_n - z^\dagger\|^2 + \|x_n - x^*\|\}$ .

Put  $a_n = \|x_n - z^\dagger\|^2$ ,  $b_n = \frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n}$  and

$$\begin{aligned} c_n &= -\frac{(1 - \sigma\gamma_n)^2}{2(\sigma - \alpha\kappa)}\varsigma_n(1 - \delta^2\frac{\varpi_n^2}{\varpi_{n+1}^2})\frac{\|x_n - z_n\|^2}{\gamma_n} - \frac{(1 - \sigma\gamma_n)^2}{2(\sigma - \alpha\kappa)}(1 - \varsigma_n)\varsigma_n\frac{\|x_n - y_n\|^2}{\gamma_n} \\ &\quad - \frac{(1 - \sigma\gamma_n)^2}{2(\sigma - \alpha\kappa)}\lambda_n(\tau_n - \lambda_n)\frac{\|f(v_n) - u_n\|^2}{\gamma_n} + \frac{\sigma^2\gamma_n}{2(\sigma - \alpha\kappa)}M \\ &\quad + \frac{1}{\sigma - \alpha\kappa}\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle, \end{aligned} \quad (26)$$

for all  $n \geq 0$ .

Owing to (25) and (26), we have

$$a_{n+1} \leq (1 - b_n)a_n + b_n c_n, \quad \forall n \geq 0. \quad (27)$$

Next, we show  $-1 \leq \limsup_{n \rightarrow \infty} c_n < +\infty$ . First, from (26), we have

$$\begin{aligned} c_n &\leq \frac{\sigma^2\gamma_n}{2(\sigma - \alpha\kappa)}M + \frac{1}{\sigma - \alpha\kappa}\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n+1} - z^\dagger\rangle \\ &\leq \frac{\sigma^2M}{2(\sigma - \alpha\kappa)} + \frac{M}{\sigma - \alpha\kappa}\|\alpha\varphi(z^\dagger) - B(z^\dagger)\|, \end{aligned}$$

which implies that  $\limsup_{n \rightarrow \infty} c_n < +\infty$ . Now, we show  $\limsup_{n \rightarrow \infty} c_n \geq -1$  by reduction to absurdity. Suppose that  $\limsup_{n \rightarrow \infty} c_n < -1$ . Then there exists  $N_0$  such that  $c_n < -1, \forall n \geq N_0$ . On account of (27), we achieve  $a_{n+1} \leq a_n - b_n$  when  $n \geq N_0$ . This implies that  $a_{n+1} \leq a_{N_0} - \sum_{k=N_0}^n b_k$ . It follows that  $\limsup_{n \rightarrow \infty} a_n \leq a_{N_0} - \limsup_{n \rightarrow \infty} \sum_{k=N_0}^n b_k = -\infty$ . This contradicts the hypothesis. So,  $-1 \leq \limsup_{n \rightarrow \infty} c_n < +\infty$ . Choose any  $x^\dagger \in \omega_w(x_n)$ . Then, there is a subsequence  $\{n_i\} \subset \{n\}$  such that  $x_{n_i} \rightharpoonup x^\dagger$  as  $i \rightarrow \infty$  and

$$\begin{aligned} \limsup_{n \rightarrow \infty} c_n &= \lim_{i \rightarrow \infty} c_{n_i} = \lim_{i \rightarrow \infty} \left[ -\frac{(1 - \sigma\gamma_{n_i})^2}{2(\sigma - \alpha\kappa)}\varsigma_{n_i}(1 - \delta^2\frac{\varpi_{n_i}^2}{\varpi_{n_i+1}^2})\frac{\|x_{n_i} - z_{n_i}\|^2}{\gamma_{n_i}} \right. \\ &\quad - \frac{(1 - \sigma\gamma_{n_i})^2}{2(\sigma - \alpha\kappa)}(1 - \varsigma_{n_i})\varsigma_{n_i}\frac{\|x_{n_i} - y_{n_i}\|^2}{\gamma_{n_i}} + \frac{1}{\sigma - \alpha\kappa}\langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n_i+1} - z^\dagger\rangle \\ &\quad \left. - \frac{(1 - \sigma\gamma_{n_i})^2}{2(\sigma - \alpha\kappa)}\lambda_{n_i}(\tau_{n_i} - \lambda_{n_i})\frac{\|f(v_{n_i}) - u_{n_i}\|^2}{\gamma_{n_i}} + \frac{\sigma^2\gamma_{n_i}}{2(\sigma - \alpha\kappa)}M \right]. \end{aligned} \quad (28)$$

Since the sequence  $\{x_{n_i+1}\}$  is bounded, there exists a subsequence of  $\{x_{n_i+1}\}$ , without loss of generality, still denoted by  $\{x_{n_i+1}\}$  such that  $x_{n_i+1} \rightharpoonup \hat{x} (i \rightarrow \infty)$ . Thus,  $\lim_{i \rightarrow \infty} \langle\alpha\varphi(z^\dagger) - B(z^\dagger), x_{n_i+1} - z^\dagger\rangle = \langle\alpha\varphi(z^\dagger) - B(z^\dagger), \hat{x} - z^\dagger\rangle$  exists. It follows from (28) that

$$\begin{aligned} \lim_{i \rightarrow \infty} &\left[ -\frac{(1 - \sigma\gamma_{n_i})^2}{2(\sigma - \alpha\kappa)}\varsigma_{n_i}(1 - \delta^2\frac{\varpi_{n_i}^2}{\varpi_{n_i+1}^2})\frac{\|x_{n_i} - z_{n_i}\|^2}{\gamma_{n_i}} - \frac{(1 - \sigma\gamma_{n_i})^2}{2(\sigma - \alpha\kappa)} \right. \\ &\quad \times (1 - \varsigma_{n_i})\varsigma_{n_i}\frac{\|x_{n_i} - y_{n_i}\|^2}{\gamma_{n_i}} - \left. \frac{(1 - \sigma\gamma_{n_i})^2}{2(\sigma - \alpha\kappa)}\lambda_{n_i}(\tau_{n_i} - \lambda_{n_i})\frac{\|f(v_{n_i}) - u_{n_i}\|^2}{\gamma_{n_i}} \right] \end{aligned} \quad (29)$$

exists. Since  $\lim_{i \rightarrow \infty} \gamma_{n_i} = 0$ , from (29), we deduce

$$\lim_{i \rightarrow \infty} \|x_{n_i} - z_{n_i}\| = 0, \quad (30)$$

$$\lim_{i \rightarrow \infty} \|x_{n_i} - y_{n_i}\| = 0, \quad (31)$$

and

$$\lim_{i \rightarrow \infty} \|f(v_{n_i}) - u_{n_i}\| = 0. \quad (32)$$

Since  $h$  is  $L_2$ -Lipschitz continuous, by (30), we have

$$\lim_{i \rightarrow \infty} \|h(z_{n_i}) - h(x_{n_i})\| = 0. \quad (33)$$

Owing to  $u_{n_i} - x_{n_i} = \varsigma_{n_i}(y_{n_i} - x_{n_i})$  and (31), we derive

$$\lim_{i \rightarrow \infty} \|u_{n_i} - x_{n_i}\| = 0. \quad (34)$$

In accordance with (10), we receive

$$\begin{aligned} \|u_{n_i} - f(u_{n_i})\| &\leq \|u_{n_i} - f(v_{n_i})\| + \|f(v_{n_i}) - f(u_{n_i})\| \\ &\leq \|u_{n_i} - f(v_{n_i})\| + L_1 \|v_{n_i} - u_{n_i}\| \\ &= \|u_{n_i} - f(v_{n_i})\| + L_1 \tau_{n_i} \|u_{n_i} - f(u_{n_i})\|, \end{aligned}$$

which yields

$$\|u_{n_i} - f(u_{n_i})\| \leq \frac{1}{1 - L_1 \tau_{n_i}} \|u_{n_i} - f(v_{n_i})\|.$$

This together with (32) implies that

$$\lim_{i \rightarrow \infty} \|u_{n_i} - f(u_{n_i})\| = 0. \quad (35)$$

By (34), we have  $u_{n_i} \rightharpoonup x^\dagger$  because  $x_{n_i} \rightharpoonup x^\dagger$ . Applying Lemma 2.1 to (35), we deduce  $x^\dagger \in \text{Fix}(f)$ . Therefore,  $\omega_w(x_n) \subset \text{Fix}(f)$ .  $\square$

**Proposition 3.3.**  $\omega_w(x_n) \subset (g + h)^{-1}(0)$ .

*Proof.* Pick any  $(u^\dagger, v^\dagger) \in \text{Graph}(g + h)$ . Then,

$$v^\dagger - h(u^\dagger) \in g(u^\dagger). \quad (36)$$

Thanks to (15), we have

$$\frac{x_{n_i} - z_{n_i}}{\varpi_{n_i}} - h(x_{n_i}) \in g(z_{n_i}). \quad (37)$$

Since  $g$  is monotone, from (36) and (37), we acquire

$$\langle v^\dagger - h(u^\dagger) - \left( \frac{x_{n_i} - z_{n_i}}{\varpi_{n_i}} - h(x_{n_i}) \right), u^\dagger - z_{n_i} \rangle \geq 0.$$

It follows that

$$\begin{aligned} \langle v^\dagger, u^\dagger - z_{n_i} \rangle &\geq \langle h(u^\dagger) - h(x_{n_i}) + \frac{x_{n_i} - z_{n_i}}{\varpi_{n_i}}, u^\dagger - z_{n_i} \rangle \\ &= \langle h(u^\dagger) - h(z_{n_i}), u^\dagger - z_{n_i} \rangle + \langle h(z_{n_i}) - h(x_{n_i}), u^\dagger - z_{n_i} \rangle \\ &\quad + \frac{1}{\varpi_{n_i}} \langle x_{n_i} - z_{n_i}, u^\dagger - z_{n_i} \rangle. \end{aligned} \quad (38)$$

Since  $h$  is monotone,  $\langle h(u^\dagger) - h(z_{n_i}), u^\dagger - z_{n_i} \rangle \geq 0$ . By (38), we get

$$\langle v^\dagger, u^\dagger - z_{n_i} \rangle \geq \langle h(z_{n_i}) - h(x_{n_i}), u^\dagger - z_{n_i} \rangle + \frac{1}{\varpi_{n_i}} \langle x_{n_i} - z_{n_i}, u^\dagger - z_{n_i} \rangle. \quad (39)$$

Owing to  $x_{n_i} \rightharpoonup x^\dagger$ , from (30), we also have  $z_{n_i} \rightharpoonup x^\dagger$ . Taking into account (30), and (33), we conclude that  $\langle v^\dagger, u^\dagger - x^\dagger \rangle \geq 0$  for all  $(u^\dagger, v^\dagger) \in \text{Graph}(g + h)$ . Thus,  $x^\dagger \in (g + h)^{-1}$ . Therefore,  $\omega_w(x_n) \in (g + h)^{-1}$ .  $\square$

Finally, we demonstrate the convergence of the sequence  $\{x_n\}$  generated by Algorithm 3.1.

**Theorem 3.1.** *The sequence  $\{x_n\}$  generated by Algorithm 3.1 converges strongly to  $z^\dagger$ .*

*Proof.* First, by Propositions 3.2 and 3.3, we have  $\omega_w(x_n) \in \Omega$ . From (10) and (11), we obtain

$$\begin{aligned} x_{n_i+1} - x_{n_i} &= \gamma_{n_i}(\alpha\varphi(x_{n_i}) - B(w_{n_i})) + (w_{n_i} - x_{n_i}) \\ &= \gamma_{n_i}(\alpha\varphi(x_{n_i}) - B(w_{n_i})) + (1 - \lambda_{n_i})(u_{n_i} - x_{n_i}) \\ &\quad + \lambda_{n_i}(f(v_{n_i}) - u_{n_i} + u_{n_i} - x_{n_i}). \end{aligned}$$

This together with (32) and (34) implies that  $\|x_{n_i+1} - x_{n_i}\| \rightarrow 0$ . Hence,  $x_{n_i+1} \rightharpoonup x^\dagger$  ( $i \rightarrow \infty$ ). According to (28), we derive

$$\begin{aligned} \limsup_{n \rightarrow \infty} c_n &\leq \lim_{i \rightarrow \infty} \left( \frac{\sigma^2 \gamma_{n_i}}{2(\sigma - \alpha\kappa)} M + \frac{1}{\sigma - \alpha\kappa} \langle \alpha\varphi(z^\dagger) - B(z^\dagger), x_{n_i+1} - z^\dagger \rangle \right) \\ &= \frac{1}{\sigma - \alpha\kappa} \langle \alpha\varphi(z^\dagger) - B(z^\dagger), x^\dagger - z^\dagger \rangle \leq 0. \end{aligned} \quad (40)$$

From (25), we obtain

$$\|x_{n+1} - z^\dagger\|^2 \leq [1 - \frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n}] \|x_n - z^\dagger\|^2 + \frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n} c_n, \quad (41)$$

It is obviously that  $\frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n} \rightarrow 0$  and  $\sum_n \frac{2(\sigma - \alpha\kappa)\gamma_n}{1 - \alpha\kappa\gamma_n} = +\infty$ . By Lemma 2.2, (40) and (41), we conclude that  $x_n \rightarrow z^\dagger$ . This completes the proof.  $\square$

#### 4. Conclusions

In this paper, we propose a composite splitting algorithm [Algorithm 3.1] for solving variational inclusion problem (1) and fixed point problem (4) in a real Hilbert space  $\mathcal{H}$ . The introduced algorithm [Algorithm 3.1] consists of forward-backward algorithm (3), Tseng-type algorithm (9) and self-adaptive rule (12). Under some additional conditions, we prove that the sequence  $\{x_n\}$  generated by the splitting algorithm [Algorithm 3.1] strongly converges to a point  $z^\dagger = \text{proj}_\Omega \circ (I - B + \alpha\varphi)z^\dagger$  which solves the variational inequality  $\langle \alpha\varphi(z^\dagger) - B(z^\dagger), x - z^\dagger \rangle \leq 0, \forall x \in \text{Fix}(f) \cap (g + h)^{-1}(0)$ .

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