

C^* -ALGEBRA VALUED EXTENDED b -METRIC SPACES AND FIXED POINT RESULTS WITH AN APPLICATION

Mohammad Asim¹ and Mohammad Imdad²

In this paper, we introduce the notion of C^ -algebra valued extended b -metric spaces and utilize the same to prove an analogue of Banach Contraction Principle. We adopt an example to exhibit the utility of our main result. Finally, we apply our result to examine the existence and uniqueness of solution for a system of Fredholm integral equations.*

Keywords: C^* -algebra; C^* -algebra valued extended b -metric space; fixed point.

2000 Mathematics Subject Classification 47H10, 54H25, 46L07.

1. Introduction

Fixed point theory continues to be a fascinating subject of research despite having a history of more than hundred years. The attraction of fixed point theory lies in its application which belongs to numerous domain. The first fundamental result on fixed point for contractive-type mappings is essentially the well known result namely Banach contraction principle by Banach [9] in 1922, which turns out to be very effective tool in guaranteeing the existence and uniqueness of solution of various types of diverse problems arising in several domains within and beyond mathematics. The classical Banach contraction principle has been extended and generalized in number of different directions (see [8, 22, 3, 11, 10, 4, 5, 6, 7, 19]). To enhance the domain of applicability, I.A. Bakhtin [8] and S. Czerwinski [11] introduced the concept of b -metric space as a note improvement of metric spaces and proved fixed point results as an analogue of Banach contraction principle. Indeed, many researchers are dealing with the fixed point theory for singlevalued and multivalued mappings in b -metric spaces and by now there exists a considerable literature in such spaces (see [15, 12, 24, 27, 1, 16, 26]). On the other hand, Kamran et al. [17] introduced a new type of generalized b -metric space and termed it as extended b -metric space. Thereafter, several researchers proved

¹Department of Mathematics, Aligarh Muslim University, Aligarh-202002, India, e-mail: mailto:asim27@gmail.com

²Department of Mathematics, Aligarh Muslim University, Aligarh-202002, India, e-mail: mailto:midad@gmail.com

some existence and uniqueness results on fixed point in extended b -metric spaces (see [25, 23, 13, 18]).

In 2014, Ma et al. [20] established the notion of C^* -algebra valued metric spaces (in short C^* -avMS) by replacing the range set \mathbb{R} with a unital C^* -algebra which is more general class than class of metric spaces and utilize the same to prove some fixed point results in such spaces. One year later, again Ma et al. [21] introduce the notion of C^* -algebra valued b -metric spaces as a generalization of C^* -avMS and proved some fixed point results also used their results as an applications for an integral type operator.

Inspired by foregoing observations, we enlarge the class of C^* -avbMS by introducing the class of C^* -avEbMS and utilize the same to prove fixed point result. We also furnish some examples which demonstrate the utility of our main result. Moreover, we our main result to examine the existence and uniqueness of solution for a system of integral type operator.

2. Preliminaries

In this section, we collect notions, definitions and auxiliary results which are needed in our subsequent discussions.

Throughout the paper, we denote \mathcal{A} by an unital (*i.e.*, unity element I) C^* -algebra with linear involution $*$ such that for all $\rho, \varsigma \in \mathcal{A}$, $(\rho\varsigma)^* = \varsigma^*\rho^*$ and $\rho^{**} = \rho$. Let \mathcal{A} be an unital C^* -algebra with unity element I , then we denote $\mathcal{A}^I = \{a \in \mathcal{A}; ab = ba, a \succcurlyeq I \text{ and } \forall b \in \mathcal{A}\}$. A positive element $\rho \in \mathcal{A}$ is denoted by $0_{\mathcal{A}} \preccurlyeq \rho$, if $\rho = \rho^*$ and $\sigma(\rho) = \{\lambda \in \mathbb{R} : \lambda I - \rho \text{ is non-invertible}\} \subseteq [0, \infty)$, where $0_{\mathcal{A}}$ is a zero element in \mathcal{A} . The partial ordering on \mathcal{A} can be defined as follows: $\rho \preccurlyeq \varsigma$ if and only if $0_{\mathcal{A}} \preccurlyeq \varsigma - \rho$. The pair $(\mathcal{A}, *)$ is said to be an unital $*$ -algebra, if it contains the unity element I . A unital $*$ -algebra $(\mathcal{A}, *)$ is called a Banach $*$ -algebra, if it satisfies $\|\rho^*\| = \|\rho\|$ along with a complete sub-multiplicative norm. A Banach C^* -algebra satisfying $\|\rho^*\rho\| = \|\rho\|^2$, for all $\rho \in \mathcal{A}$ is called a C^* -algebra.

The following definition is introduced by Ma et al. [20]:

Definition 2.1. *Let $A \neq \emptyset$. The mapping $d : A \times A \rightarrow \mathcal{A}$ is called a C^* -av metric on A , if it satisfies the following (for all $\varsigma, \sigma, \rho \in A$):*

- (1) $d(\varsigma, \sigma) \succcurlyeq 0_{\mathcal{A}}$ and $d(\varsigma, \sigma) = 0_{\mathcal{A}}$ iff $\varsigma = \sigma$;
- (2) $d(\varsigma, \sigma) = d(\sigma, \varsigma)$;
- (3) $d(\varsigma, \sigma) \preccurlyeq d(\varsigma, \rho) + d(\rho, \sigma)$.

The triplet (A, \mathcal{A}, d) is called a C^ -avMS.*

I.A. Bakhtin [8] and S. Czerwinski [11] introduced the notion of b -metric spaces.

Definition 2.2. *Let $A \neq \emptyset$. The mapping $d : X \times X \rightarrow \mathbb{R}_+$ is said to be a b -metric with coefficient $b \geq 1$, if σ satisfies the following (for all $\varsigma, \sigma, \rho \in A$):*

- (1) $d(\varsigma, \sigma) = 0$ if and only if $\varsigma = \sigma$;

- (2) $d(\varsigma, \sigma) = d(\sigma, \varsigma);$
- (3) $d(\varsigma, \sigma) \leq b[d(\varsigma, \rho) + d(\rho, \sigma)].$

Then the pair (A, d) is said to be a *b*-metric space.

In 2015, again Ma et al. [21] introduced the notion of *C**-av *b*-metric space as follows:

Definition 2.3. Let $A \neq \emptyset$ and $s \in \mathcal{A}$ such that $s \succcurlyeq I$. The mapping $d : A \times A \rightarrow \mathcal{A}$ is called a *C**-av *b*-metric on A , if it satisfies the following (for all $\varsigma, \sigma, \rho \in A$):

- (1) $d(\varsigma, \sigma) \succcurlyeq 0_{\mathcal{A}}$ and $d(\varsigma, \sigma) = 0_{\mathcal{A}}$ iff $\varsigma = \sigma$;
- (2) $d(\varsigma, \sigma) = d(\sigma, \varsigma);$
- (3) $d(\varsigma, \sigma) \preccurlyeq s[d(\varsigma, \rho) + d(\rho, \sigma)].$

The triplet (A, \mathcal{A}, d) is called a *C**-avbMS.

In 2017, T. Kamran et al. [17] introduced the following definition of extended *b*-metric spaces.

Definition 2.4. Let $A \neq \emptyset$ and $\xi : X \times X \rightarrow [1, \infty)$. The mapping $d : X \times X \rightarrow \mathbb{R}_+$ is said to be an extended *b*-metric, if σ satisfies the following (for all $\varsigma, \sigma, \rho \in A$):

- (1) $d(\varsigma, \sigma) = 0$ if and only if $\varsigma = \sigma$;
- (2) $d(\varsigma, \sigma) = d(\sigma, \varsigma);$
- (3) $d(\varsigma, \sigma) \leq \xi(\varsigma, \sigma)[d(\varsigma, \rho) + d(\rho, \sigma)].$

Then the pair (A, d) is said to be an extended *b*-metric space.

Remark 2.1. Clearly, if $s = I$ then a *C**-avbMS reduced to a *C**-avMS.

3. Results

In this section, we introduce yet another type of generalized *C**-avMS, which we refer as *C**-avEbMS. We also establish a fixed point theorem besides deducing natural corollaries. Now, we define *C**-algebra valued extended *b*-metric space (in short *C**-avEbMS) as follows:

Definition 3.1. Let $A \neq \emptyset$ and $\xi : A \times A \rightarrow \mathcal{A}^I$. The mapping $d_{\xi} : A \times A \rightarrow \mathcal{A}$ is called a *C**-av extended *b*-metric on A , if it satisfies the following (for all $\varsigma, \sigma, \rho \in A$):

- (1) $d_{\xi}(\varsigma, \sigma) \succcurlyeq 0_{\mathcal{A}}$ and $d_{\xi}(\varsigma, \sigma) = 0_{\mathcal{A}}$ iff $\varsigma = \sigma$;
- (2) $d_{\xi}(\varsigma, \sigma) = d_{\xi}(\sigma, \varsigma);$
- (3) $d_{\xi}(\varsigma, \sigma) \preccurlyeq \xi(\varsigma, \sigma)[d_{\xi}(\varsigma, \rho) + d_{\xi}(\rho, \sigma)].$

The triplet $(A, \mathcal{A}, d_{\xi})$ is called a *C**-avEbMS.

Remark 3.1. Observe that, if $\xi(\varsigma, \sigma) = s \succcurlyeq I$, then $(A, \mathcal{A}, d_{\xi})$ reduces to a *C**-avbMS (see [21]).

$$\begin{array}{ccccc}
\text{Metric space} & \longrightarrow & \text{b-metric space} & \longrightarrow & \text{Extended b-metric space} \\
\downarrow & & \downarrow & & \downarrow \\
C^*\text{-avMS} & \longrightarrow & C^*\text{-avbMS} & \longrightarrow & C^*\text{-avEbMS}
\end{array}$$

Example 3.1. Let $A = \mathbb{R}$ and $\mathcal{A} = M_2(\mathbb{C})$, the class of bounded and linear operators on a Hilbert space \mathbb{C}^2 . Define a mapping $\xi : A \times A \rightarrow \mathcal{A}$ by (for all $\varsigma, \sigma \in \chi$):

$$\xi(\varsigma, \sigma) = \begin{cases} \begin{bmatrix} |\varsigma - \sigma|^{p-1} & 0 \\ 0 & |\varsigma - \sigma|^{p-1} \end{bmatrix} & \text{if } \varsigma \neq \sigma \\ I_{2 \times 2} & \text{if } \varsigma = \sigma \end{cases}$$

where $I_{2 \times 2}$ is a square identity matrix in \mathcal{A} and $k > 0$ is a constant.

Define $d_\xi : A \times A \rightarrow \mathcal{A}$ by (for all $\varsigma, \sigma \in A$):

$$d_\xi(\varsigma, \sigma) = \begin{bmatrix} |\varsigma - \sigma|^p & 0 \\ 0 & |\varsigma - \sigma|^p \end{bmatrix}$$

Then (A, \mathcal{A}, d_ξ) be a C^* -avEbMS.

Proof. By routine calculation one can verify, conditions (i) – (ii) of Definition 3.1. Now, we give the following inequality (for all $\alpha, \beta \in A$):

$$\begin{bmatrix} (\alpha + \beta)^p & 0 \\ 0 & (\alpha + \beta)^p \end{bmatrix} \leq \begin{bmatrix} (\alpha + \beta)^{p-1} & 0 \\ 0 & (\alpha + \beta)^{p-1} \end{bmatrix} \begin{bmatrix} \alpha^p + \beta^p & 0 \\ 0 & \alpha^p + \beta^p \end{bmatrix}.$$

Above inequality is trivial for $\alpha = \beta = 0$. For $|\alpha| \geq 1$ or $|\beta| \geq 1$, we obtain

$$\begin{aligned}
\begin{bmatrix} (\alpha + \beta)^p & 0 \\ 0 & k(\alpha + \beta)^p \end{bmatrix} &= \frac{\begin{bmatrix} (\alpha + \beta)^p & 0 \\ 0 & (\alpha + \beta)^p \end{bmatrix}}{\begin{bmatrix} \alpha^p + \beta^p & 0 \\ 0 & \alpha^p + \beta^p \end{bmatrix}} \begin{bmatrix} \alpha^p + \beta^p & 0 \\ 0 & \alpha^p + \beta^p \end{bmatrix} \\
&\leq \frac{\begin{bmatrix} (\alpha + \beta)^p & 0 \\ 0 & (\alpha + \beta)^p \end{bmatrix}}{\begin{bmatrix} \alpha + \beta & 0 \\ 0 & \alpha + \beta \end{bmatrix}} \begin{bmatrix} \alpha^p + \beta^p & 0 \\ 0 & \alpha^p + \beta^p \end{bmatrix} \\
&= \begin{bmatrix} (\alpha + \beta)^{p-1} & 0 \\ 0 & (\alpha + \beta)^{p-1} \end{bmatrix} \begin{bmatrix} \alpha^p + \beta^p & 0 \\ 0 & \alpha^p + \beta^p \end{bmatrix}.
\end{aligned}$$

Finally, we set $\alpha = \varsigma - \rho$, $\beta = \rho - \sigma$ and obtain

$$\begin{aligned}
\begin{bmatrix} |\varsigma - \rho|^p & 0 \\ 0 & |\varsigma - \rho|^p \end{bmatrix} &\leq \begin{bmatrix} |\varsigma - \rho|^{p-1} & 0 \\ 0 & |\varsigma - \rho|^{p-1} \end{bmatrix} \left(\begin{bmatrix} |\varsigma - \rho|^p & 0 \\ 0 & |\varsigma - \rho|^p \end{bmatrix} \right. \\
&\quad \left. + \begin{bmatrix} |\varsigma - \rho|^p & 0 \\ 0 & |\varsigma - \rho|^p \end{bmatrix} \right).
\end{aligned}$$

Therefore,

$$d_\xi(\varsigma, \sigma) \leq \xi(\varsigma, \sigma)(d_\xi(\varsigma, \rho) + d_\xi(\rho, \sigma)).$$

Hence, (A, \mathcal{A}, d_ξ) is a C^* -avEbMS. \square

Remark 3.2. Observe that $\sup\{\xi(\varsigma, \sigma); \varsigma, \sigma \in \chi\} = \infty$. Thus, d_ξ is not a C^* -avbMS.

Let (A, \mathcal{A}, d_ξ) be a C^* -avEbMS. Then open ball of center $\varsigma \in A$ and radius $0_{\mathcal{A}} \prec \epsilon \in \mathcal{A}$ is defined by:

$$B_{d_\xi}(\varsigma, \epsilon) = \{\sigma \in A : d_\xi(\varsigma, \sigma) \prec \epsilon\}.$$

Similarly, the closed ball with center $\varsigma \in A$ and radius $\epsilon \succ 0$ is defined by:

$$B_{d_\xi}[\varsigma, \epsilon] = \{\sigma \in A : d_\xi(\varsigma, \sigma) \preccurlyeq \epsilon\}.$$

The family of open balls (for all $\varsigma \in A$ and $\epsilon \succ 0$)

$$\mathcal{U}_{d_\xi} = \{B_{d_\xi}(\varsigma, \epsilon) : \varsigma \in A, \epsilon \succ 0_{\mathcal{A}}\},$$

forms a basis of some topology τ_d on A .

Lemma 3.1. Let (A, τ_{d_ξ}) be a topological space and $f : A \rightarrow A$. If f is continuous then every sequence $\{\varsigma_n\} \subseteq A$ such that $\varsigma_n \rightarrow \varsigma$ implies $f\varsigma_n \rightarrow f\varsigma$. The converse holds if A is metrizable.

Definition 3.2. A sequence $\{\varsigma_n\}$ in (A, \mathcal{A}, d_ξ) is called convergent (with respect to \mathcal{A}), if for given $\epsilon \succ 0_{\mathcal{A}}$, there exists $N \in \mathbb{N}$ such that $d_\xi(\varsigma_n, \varsigma) \prec \epsilon$, for all $n > N$. We denote it by

$$\lim_{n \rightarrow \infty} d_\xi(\varsigma_n, \varsigma) = 0_{\mathcal{A}}.$$

Definition 3.3. A sequence $\{\varsigma_n\}$ in (A, \mathcal{A}, d_ξ) is called Cauchy sequence (with respect to \mathcal{A}), if for given $\epsilon \succ 0_{\mathcal{A}}$, there exists $N \in \mathbb{N}$ such that $d_\xi(\varsigma_n, \varsigma_m) \prec \epsilon$, for all $n, m > N$. We denote it by

$$\lim_{n \rightarrow \infty} d_\xi(\varsigma_n, \varsigma_m) = 0_{\mathcal{A}}.$$

Definition 3.4. The triplet (A, \mathcal{A}, d_ξ) is called complete C^* -avEbMS if every Cauchy in A is convergent to a point ς in A .

Observe that, in general a *b*-metric is not a continuous functional and so is a C^* -avEbMS.

Example 3.2. [14] Let $X = \mathbb{N} \cup \infty$ and a mapping $d : X \times X \rightarrow \mathbb{R}_+$ defined by:

$$d(\varsigma, \sigma) = \begin{cases} 0_{\mathcal{A}} & \text{if } \varsigma = \sigma \\ |\frac{1}{\varsigma} - \frac{1}{\sigma}| & \text{if } \varsigma, \sigma \text{ are even or } \varsigma\sigma = \infty \\ 5 & \text{if } \varsigma, \sigma \text{ are odd or } \varsigma \neq \sigma \\ 5 & \text{otherwise.} \end{cases}$$

Then (X, d) is a *b*-metric space with $s = 3$ but it is not continuous.

Lemma 3.2. *Let (A, \mathcal{A}, d_ξ) be a C^* -avEbMS. If d_ξ is continuous then every convergent sequence has a unique limit.*

Our main result runs as follows:

Theorem 3.1. *Let (A, \mathcal{A}, d_ξ) be complete C^* -avEbMS and $f : X \rightarrow X$ satisfies that the following:*

$$d_\xi(f\varsigma, f\sigma) \preccurlyeq c^* d_\xi(\varsigma, \sigma) c, \quad \forall \varsigma, \sigma \in A. \quad (1)$$

where, $c \in \mathcal{A}$ with $\|c\| < 1$ and $\lim_{n,m \rightarrow \infty} \xi(\varsigma_n, \varsigma_m) \|c\| \prec I$. Then f has a unique fixed point $\varsigma \in A$.

Proof. Choose $\varsigma_0 \in A$ and construct an iterative sequence $\{\varsigma_n\}$ by:

$$\varsigma_1 = f\varsigma_0, \quad \varsigma_2 = f\varsigma_1 = f^2\varsigma_0, \quad \varsigma_3 = f\varsigma_2 = f^3\varsigma_0, \dots, \quad \varsigma_n = f\varsigma_{n-1} = f^n\varsigma_0, \dots$$

Let, we denote $\Delta = d_\xi(\varsigma_0, \varsigma_1)$. Now, we assert that $\lim_{n,m \rightarrow \infty} d_\xi(\varsigma_n, \varsigma_{n+1}) = 0_{\mathcal{A}}$. On setting $\varsigma = \varsigma_n$ and $\sigma = \varsigma_{n+1}$ in equation (1), we get

$$\begin{aligned} d_\xi(\varsigma_n, \varsigma_{n+1}) &= d_\xi(f\varsigma_{n-1}, f\varsigma_n) = c^* d_\xi(\varsigma_{n-1}, \varsigma_n) c \\ &\preccurlyeq (c^*)^2 d_\xi(\varsigma_{n-2}, \varsigma_{n-1}) c^2 \\ &\preccurlyeq \dots \\ &\preccurlyeq (c^*)^n d_\xi(\varsigma_0, \varsigma_1) c^n \\ &\preccurlyeq (c^*)^n \Delta c^n. \end{aligned}$$

Now, we assert that $\{\zeta_n\}$ is Cauchy sequence. For any $n, m \in \mathbb{N}$ such that $n < m$, we have

$$\begin{aligned}
 d_\xi(\zeta_n, \zeta_m) &\preccurlyeq \xi(\zeta_n, \zeta_m) [d_\xi(\zeta_n, \zeta_{n+1}) + d_\xi(\zeta_{n+1}, \zeta_m)] \\
 &\preccurlyeq \xi(\zeta_n, \zeta_m) d_\xi(\zeta_n, \zeta_{n+1}) + \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) d_\xi(\zeta_{n+1}, \zeta_{n+2}) + \dots + \\
 &\quad \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) \dots \xi(\zeta_{m-2}, \zeta_m) \xi(\zeta_{m-1}, \zeta_m) d_\xi(\zeta_{m-1}, \zeta_m) \\
 &\preccurlyeq \xi(\zeta_n, \zeta_m) (c^*)^n \Delta c^n + \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) (c^*)^{n+1} \Delta c^{n+1} + \dots + \\
 &\quad \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) \dots \xi(\zeta_{m-2}, \zeta_m) \xi(\zeta_{m-1}, \zeta_m) (c^*)^{m-1} \Delta c^{m-1} \\
 &= \xi(\zeta_n, \zeta_m) (c^*)^n \Delta^{\frac{1}{2}} \Delta^{\frac{1}{2}} c^n + \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) (c^*)^{n+1} \Delta^{\frac{1}{2}} \Delta^{\frac{1}{2}} c^{n+1} + \dots + \\
 &\quad \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) \dots \xi(\zeta_{m-2}, \zeta_m) \xi(\zeta_{m-1}, \zeta_m) (c^*)^{m-1} \Delta^{\frac{1}{2}} \Delta^{\frac{1}{2}} c^{m-1} \\
 &= \xi(\zeta_n, \zeta_m) (\Delta^{\frac{1}{2}} c^n)^* (\Delta^{\frac{1}{2}} c^n) + \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) (\Delta^{\frac{1}{2}} c^{n+1})^* (\Delta^{\frac{1}{2}} c^{n+1}) + \dots + \\
 &\quad \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) \dots \xi(\zeta_{m-2}, \zeta_m) \xi(\zeta_{m-1}, \zeta_m) (\Delta^{\frac{1}{2}} c^{m-1})^* (\Delta^{\frac{1}{2}} c^{m-1}) \\
 &= \xi(\zeta_n, \zeta_m) |\Delta^{\frac{1}{2}} c^n|^2 + \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) |\Delta^{\frac{1}{2}} c^{n+1}|^2 + \dots + \\
 &\quad \xi(\zeta_n, \zeta_m) \xi(\zeta_{n+1}, \zeta_m) \dots \xi(\zeta_{m-2}, \zeta_m) \xi(\zeta_{m-1}, \zeta_m) |\Delta^{\frac{1}{2}} c^{m-1}|^2 \\
 &= \sum_{i=0}^{m-1} |\Delta^{\frac{1}{2}} c^{n+i}|^2 \prod_{j=0}^i \xi(\zeta_{n+j}, \zeta_m) \preccurlyeq \left\| \sum_{i=0}^{m-1} |\Delta^{\frac{1}{2}} c^{n+i}|^2 \right\| \prod_{j=0}^i \xi(\zeta_{n+j}, \zeta_m) \\
 &\preccurlyeq \sum_{i=0}^{m-1} \|\Delta\| \|c^{n+i}\|^2 \prod_{j=0}^i \xi(\zeta_{n+j}, \zeta_m) \preccurlyeq \|\Delta\| \sum_{i=0}^{m-1} \|c^{n+i}\|^2 \prod_{j=0}^i \xi(\zeta_{n+j}, \zeta_m),
 \end{aligned}$$

Observe that, the above inequality is dominated by

$$\sum_{i=0}^{m-1} \|c^{n+i}\|^2 \prod_{j=0}^i \xi(\zeta_{n+j}, \zeta_m) \preccurlyeq \sum_{i=0}^{m-1} \|c^i\|^2 \prod_{j=0}^i \xi(\zeta_j, \zeta_m).$$

Now, by using the ratio test, we have

$$\lim_{i \rightarrow \infty} \frac{\|c^{i+1}\|^2 \prod_{j=0}^{i+1} \xi(\zeta_j, \zeta_m)}{\|c^i\|^2 \prod_{j=0}^i \xi(\zeta_j, \zeta_m)} \preccurlyeq \lim_{i \rightarrow \infty} \xi(\zeta_i, \zeta_m) \|c\|^2 \prec I.$$

Next, we say that (for all $m \geq 1$)

$$S_n = \sum_{i=0}^n \|c^i\|^2 \prod_{j=0}^i \xi(\zeta_j, \zeta_m) \quad \text{and} \quad S = \sum_{i=0}^{\infty} \|c^i\|^2 \prod_{j=0}^i \xi(\zeta_j, \zeta_m)$$

Consequently, we have

$$d_\xi(\zeta_n, \zeta_{n+p}) \preccurlyeq \|\Delta\| \|c^{2n}\| [S_{m-1} - S_n].$$

On making limit $n \rightarrow \infty$, we obtain that $\{\zeta_n\}$ is a Cauchy sequence in A . Since, A is complete then there exists $a \in A$ such that

$$\lim_{n \rightarrow \infty} d_\xi(\zeta_n, a) = 0_A.$$

Now, we will show that a is a fixed point of f . For any $n \in \mathbb{N}$, we have

$$\begin{aligned} d_\xi(f\varsigma, \varsigma) &\preccurlyeq \xi(f\varsigma, \varsigma)[d_\xi(f\varsigma, \varsigma_{n+1}) + d_\xi(\varsigma_{n+1}, \varsigma)] \\ &= \xi(f\varsigma, \varsigma)[d_\xi(f\varsigma, f\varsigma_n) + d_\xi(\varsigma_{n+1}, \varsigma)] \\ &\preccurlyeq \xi(f\varsigma, \varsigma)[c^*d_\xi(\varsigma, \varsigma_n)c + d_\xi(\varsigma_{n+1}, \varsigma)] \\ &\rightarrow 0_A \text{ as } n \rightarrow \infty. \end{aligned}$$

Therefore, ς is a fixed point of f . For the uniqueness part, suppose that $\varsigma, \sigma \in A$ such that $fa = a$ and $f\sigma = \sigma$. Then by employing 3.1, we have

$$d_\xi(\varsigma, \sigma) = d_\xi(f\varsigma, f\sigma) \preccurlyeq c^*d_\xi(\varsigma, \sigma)c,$$

so that

$$\begin{aligned} \|d_\xi(\varsigma, \sigma)\| &= \|d_\xi(f\varsigma, f\sigma)\| \\ &\leq \|c^*d_\xi(\varsigma, \sigma)c\| \\ &\leq \|c^*\|\|d_\xi(\varsigma, \sigma)\|\|c\| \\ &= \|c\|^2\|d_\xi(\varsigma, \sigma)\| \\ &< \|d_\xi(\varsigma, \sigma)\| \end{aligned}$$

deals a contradiction. Hence, $\varsigma = \sigma$, that is, f has a unique fixed point. This completes the proof. \square

Now, we furnish the following example which illustrates Theorem 3.1.

Example 3.3. *In Example 3.1, we define a map $f : A \rightarrow A$ by:*

$$f\varsigma = \frac{\varsigma}{5}, \text{ for all } \varsigma \in A.$$

*Observe that, $d_\xi(f\varsigma, f\sigma) \preccurlyeq c^*d_\xi(\varsigma, \sigma)c$, (for all $\varsigma, \sigma \in A$) satisfies with*

$$\rho = \begin{bmatrix} \frac{\sqrt{5}}{5} & 0 \\ 0 & \frac{\sqrt{5}}{5} \end{bmatrix} \in A \text{ and } \|\rho\| = \frac{\sqrt{5}}{5} = \frac{1}{\sqrt{5}} < 1.$$

Thus, all the hypothesis of Theorem 3.1 are satisfied and $\varsigma = 0$ is unique fixed point of f .

Now, we obtain following corollaries:

Corollary 3.1. *Theorem 2.1 of Z. Ma et al. [20] is immediate from Theorem 3.1.*

Proof. By taking $\xi(\varsigma, \sigma) = 1$, for all $\varsigma, \sigma \in A$, we obtain required result, \square

Corollary 3.2. *Theorem 2.1 of Z. Ma et al. [21] is immediate from Theorem 3.1.*

Proof. By taking $\xi(\varsigma, \sigma) = s$ (constant), for all $\varsigma, \sigma \in A$, we get required. \square

4. Application

As an application of Theorem 3.1, we find the existence and uniqueness results for a type of following integral equation:

$$\varsigma(\mu) = \int_E G(\mu, \nu, \varsigma(\nu)) d\nu + h(\mu), \quad \mu, \nu \in E, \quad (2)$$

where E is a measurable set, $G : E \times E \times \mathbb{R} \rightarrow \mathbb{R}$ and $h \in L^\infty(E)$.

Let $A = L^\infty(E)$, $H = L^2(E)$ and $L(H) = \mathcal{A}$. Define $d_\xi : A \times A \rightarrow \mathcal{A}$ by (for all $h, k, I \in A$, $p \geq 1$ and $\|\rho\| = k < 1$):

$$d_\xi(h, k) = \pi_{|h-k|^p}$$

where $\pi_u : H \rightarrow H$ is the multiplicative operator defined by:

$$\pi_u(\psi) = u \cdot \psi .$$

Now, define a mapping $\xi : A \times A \rightarrow \mathcal{A}$ by (for all $\varsigma, \sigma \in \chi$):

$$\xi(\varsigma, \sigma) = \begin{cases} \pi_{|h-k|^{p-1}} & \text{if } \varsigma \neq \sigma \\ I_{2 \times 2} & \text{if } \varsigma = \sigma \end{cases}$$

where $I_{2 \times 2}$ is an square identity matrix in \mathcal{A} and $k > 0$ is a constant. Note that, (A, \mathcal{A}, d_ξ) is a complete *C**-avEbMS.

Now, we state and prove our result as follows:

Theorem 4.1. *Suppose that (for all $\varsigma, \sigma \in A$)*

(1) *there exist a continuous function $\psi : E \times E \rightarrow \mathbb{R}$ and $k \in (0, 1)$ such that*

$$|G(\mu, \nu, \varsigma(\nu)) - G(\mu, \nu, \sigma(\nu))| \leq k |\psi(\mu, \nu)(\varsigma(\nu) - \sigma(\nu))|,$$

for all $\mu, \nu \in E$.

(2) $\sup_{\mu \in E} \int_E |\psi(\mu, \nu)| d\nu \leq 1$.

Then the integral equation (2) has a unique solution in A .

Proof. Define $f : A \rightarrow A$ by:

$$f\varsigma(\mu) = \int_E G(\mu, \nu, \varsigma(\nu)) d\nu + h(\mu), \quad \forall \mu, \nu \in E.$$

Set $\rho = kI$, then $\rho \in \mathcal{A}$. For any $u \in H$ and $p \geq 1$, we have

$$\begin{aligned}
\|d_\xi(f\varsigma, f\sigma)\| &= \sup_{\|u\|=1} (\pi_{|f\varsigma-f\sigma|^p+I} u, u) \\
&= \sup_{\|u\|=1} \int_E \left[\left| \int_E G(\mu, \nu, \varsigma(\nu)) - G(\mu, \nu, \sigma(\nu)) d\nu \right|^p \right] u(\mu) \bar{u}(\mu) d\mu \\
&\leq \sup_{\|u\|=1} \int_E \left[\int_E |G(\mu, \nu, \varsigma(\nu)) - G(\mu, \nu, \sigma(\nu))| d\nu \right]^p |u(\mu)|^2 d\mu \\
&\leq \sup_{\|u\|=1} \int_E \left[\int_E |k\psi(\mu, \nu)(\varsigma(\nu) - \sigma(\nu))| d\nu \right]^p |u(\mu)|^2 d\mu \\
&\leq k^p \sup_{\|u\|=1} \int_E \left[\int_E |\psi(\mu, \nu)| d\nu \right]^p |u(\mu)|^2 d\mu \|\varsigma - \sigma\|_\infty^p \\
&\leq k \sup_{\mu \in E} \int_E |\psi(\mu, \nu)| d\nu \sup_{\|u\|=1} \int_E |u(\mu)|^2 d\mu \|\varsigma - \sigma\|_\infty^p \\
&\leq k \|\varsigma - \sigma\|_\infty^p \\
&= \|c\| \|d_\xi(\varsigma, \sigma)\|.
\end{aligned}$$

Since, $\|c\| < 1$, so it is verified that the mapping f meets all the requirements of Theorem 3.1. Hence, f has a unique fixed point, means that the Fredholm integral Equation (2) has a unique solution. \square

5. Conclusions

As the C^* -avMS as well as C^* -avbMS are relatively new addition to the existing literature, therefore, we endeavor to further enrich this notion by introducing the idea of C^* -avEbMS wherein we replace the constant $s \geq 1$ by a function $\xi(\varsigma, \sigma)$. Our main result (i.e., Theorem 3.1) is an analogue of Banach contraction principle in C^* -avEbMS. An example is also adopted to highlight the realized improvements in our newly proved result. Finally, we apply Theorem 3.1 to examine the existence and uniqueness of solution for a system of Fredholm integral equation.

Acknowledgements

All the authors are grateful to two anonymous referees for their valuable suggestions and fruitful comments.

REFERENCES

- [1] MU. Ali, T. Kamran, M. Postolache. Solution of Volterra integral inclusion in b-metric spaces via new fixed point theorem. *Nonlinear Anal. Modelling Control*, 22(1), 17-30, (2017).
- [2] I. Altun, F. Sola and H. Simsek. Generalized contractions on partial metric spaces. *Topology and Its Applications*, 157(18), 2778-2785, (2010).

- [3] A. Amini-Harandi. Metric-like spaces, partial metric spaces and fixed points. *Fixed Point Theory Appl.*, 2012, Article ID 204, (2012).
- [4] M. Asim, A. R. Khan and M. Imdad. Rectangular M_b -metric spaces and fixed point results. *Journal of mathematical analysis*, 10(1), 10-18, (2019).
- [5] M. Asim, A. R. Khan and M. Imdad. Fixed point results in partial symmetric spaces with an application. *Axioms*, 8(13), doi:10.3390, (2019).
- [6] M. Asim, M. Imdad and S. Radenovic. Fixed point results in extended rectangular *b*-metric spaces with an application. *U.P.B. Sci. Bull., Series A*, 81(2), 11-20, (2019).
- [7] M. Asim and M. Imdad. Partial JS-metric spaces and fixed point results. *Indian Journal of Mathematics*, 61(2), 175-186, (2019).
- [8] I. A. Bakhtin. The contraction mapping principle in almost metric spaces. *Funct. Anal., Gos. Ped. Inst. Unianowsk*, 30, 26-37, (1989).
- [9] S. Banach. Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales. *Fund. Math.*, 3, 133-181, (1922).
- [10] A. Branciari. A fixed point theorem of Banach-Caccioppoli type on a class of generalized metric spaces, *Publ. Math.*, 57, 31-37, (2000).
- [11] S. Czerwinski. Contraction mappings in *b*-metric spaces. *Acta Mathematica et Informatica Universitatis Ostraviensis*, 1(1), 5-11, (1993).
- [12] S. Czerwinski. Nonlinear set-valued contraction mappings in *b*-metric spaces. *Atti Semin. Mat. Fis. Univ. Modena*, 46, 263-276, (1998).
- [13] N. Dung and V. Hang. Remarks on partial *b*-metric spaces and fixed point theorems. *Matematicki Vesnik*, 69(4), 231-240, (2017).
- [14] N. Hussain, D. Doric, Z. Kadelburg and S. Radenovic. Suzuki-type fixed point results in metric type spaces. *Fixed Point Theory Appl.*, 2012, Article ID 126, (2012).
- [15] M. Imdad, M. Asim and R. Gubran. Common fixed point theorems for g-Generalized contractive mappings in *b*-metric spaces. *Indian Journal of Mathematics*, 60(1), 85-105, (2018).
- [16] T. Kamran, M. Postolache, MU. Ali, Q. Kiran, Feng and Liu type F-contraction in *b*-metric spaces with application to integral equations, *J. Math. Anal.* 7(5), 18-27, (2016).
- [17] T. Kamran, M. Samreen and O.U. Ain. A Generalization of *b*-Metric Space and Some Fixed Point Theorems. *Mathematics*, 5(19), (2017).
- [18] P. Kumar, Z. K. Ansari and A. Garg. Fixed point theorems in partial *b*-metric spaces using contractive conditions. *Asian Research Journal of Mathematics*, 8(4), 1-11, (2018).
- [19] H. Long-Guang and Z. Xian. Cone metric spaces and fixed point theorems of contractive mappings. *J. Math. Anal. Appl.*, 332, 1468-1476, (2007).
- [20] Z. H. Ma, L. N. Jiang, H. K. Sun. *C**-algebra valued metric spaces and related fixed point theorems. *Fixed Point Theory Appl.*, 2014, Article ID 206, (2014).
- [21] Z. H. Ma and L. N. Jiang. *C**-algebra valued *b*-metric spaces and related fixed point theorems. *Fixed Point Theory Appl.*, 2015, Article ID 222, (2015).
- [22] S. G. Matthews. Partial metric topology. *Annals of the New York Academy of Sciences*, 728, 183-197, (1994).
- [23] Z. Mustafa, J. R. Roshan, V. Parvaneh, and Z. Kadelburg. Some common fixed point results in ordered partial *b*-metric spaces. *Journal of Inequalities and Applications*, 562(1), 562, 2013, (2013).
- [24] V. Parvaneh, J.R. Roshan and S. Radenovic. Existence of tripled coincidence points in ordered *b*-metric spaces and an application to a system of integral equations. *Fixed Point Theory Appl.*, 2013(130), (2013).

- [25] M. Samreen, T. Kamran, M. Postolache. Extended b-metric space, extended b-comparison function and nonlinear contractions. *U. Politeh. Buch. Ser. A*, 80(4), 21-28, (2018).
- [26] W. Shatanawi, M. Postolache. Coincidence and fixed point results for generalized weak contractions in the sense of Berinde on partial metric spaces. *Fixed Point Theory Appl.* 2013, Art. No. 54, (2013).
- [27] W. Shatanawi, A. Pitea, R. Lazovic. Contraction conditions using comparison functions on b-metric spaces, *Fixed Point Theory Appl.*, 2014, Art No. 135, (2014).
- [28] S. Shukla. Partial *b*-Metric Spaces and Fixed Point Theorems. *Mediterranean Journal of Mathematics*, 11(2), 703–711, (2014).
- [29] O. Valero. On Banach fixed point theorems for partial metric spaces. *Applied General Topology*, 6(2), 229-240, (2005).