

PROJECTIVE COVARIANT φ -MAPS

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In this paper we construct a projective covariant representation associated with a φ -map and a projective covariant quasi-representation associated with a projective (u, u') -covariant φ -map. We gave a projective version of a result in [13] as a Stinespring's representation theorem for pairs of completely positive, symmetric, invariant, multilinear maps.

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1. Introduction

Asadi [2] and Bhat, Ramesh and Sumesh [5] provided a representation theorem for a class of maps on Hilbert C^* -modules, as a generalization of Stinespring's representation theorem for completely positive maps on C^* -algebras.

Trivedi [20] gave a Stinespring type theorem for τ -maps in the context of von Neumann algebras. He proved a decomposition of τ -maps in terms of quasi-representations, which generalize the notion of representations of Hilbert C^* -modules on Hilbert spaces and a covariant version of this result, by defining a covariant τ -maps using the notion of C^* -correspondence.

In this paper we construct a projective covariant representation associated with a φ -map and a projective covariant quasi-representation associated with a projective (u, u') -covariant φ -map. We gave a projective version of a result in [13] as a Stinespring's representation theorem for pairs of completely positive, symmetric, invariant, multilinear maps.

Definition 1.1. ([17]) A **pre-Hilbert A -module** is a complex vector space E which is also a right A -module, compatible with the complex algebra structure, equipped with an A -valued inner product $\langle \cdot, \cdot \rangle : E \times E \rightarrow A$ which is \mathbb{C} - and A -linear in its second variable and satisfies the following relations:

- (1) $\langle \xi, \eta \rangle^* = \langle \eta, \xi \rangle$ for every $\xi, \eta \in E$;
- (2) $\langle \xi, \xi \rangle \geq 0$ for every $\xi \in E$;
- (3) $\langle \xi, \xi \rangle = 0$ if and only if $\xi = 0$.

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We say that E is a **Hilbert A -module** if E is complete with respect to the topology determined by the norm $\|\cdot\|$ given by $\|\xi\| = \sqrt{\|\langle \xi, \xi \rangle\|}$.

Definition 1.2. ([19], [1]) Let A and B be two C^* -algebras and let $M_n(A)$, respectively $M_n(B)$ denote the $*$ -algebra of all $n \times n$ matrices over A , respectively B with the algebraic operations and the topology obtained by regarding it as a direct sum of n^2 copies of A , respectively B . A linear map $\varphi: A \rightarrow B$ is **completely positive** if the linear map $\varphi^{(n)}: M_n(A) \rightarrow M_n(B)$, defined by $\varphi^{(n)}([a_{ij}]_{i,j=1}^n) = [\varphi(a_{ij})]_{i,j=1}^n$ is positive for all positive integers n .

Definition 1.3. ([16]) Let G be a locally compact group with identity e and let \mathbb{T} be the group of complex numbers of modulus one. A **multiplier** ω of G is a function $\omega: G \times G \rightarrow \mathbb{T}$ with the properties :

- i) $\omega(x, e) = \omega(e, x) = 1$ for all $x \in G$;
- ii) $\omega(x, y)\omega(xy, z) = \omega(x, yz)\omega(y, z)$ for all $x, y, z \in G$.

Definition 1.4. ([15]) A multiplier is **normalized** if $\omega(x, x^{-1}) = 1$ for all $x \in G$.

Definition 1.5. ([3], [4]) Let H be a Hilbert space and G a locally compact group with the identity e . A **projective representation** of G with multiplier ω is a map $u: G \rightarrow \mathcal{U}(H)$ such that

- i) $u_{gg'} = \omega(g, g')u_g u_{g'}$ for all $g, g' \in G$;
- ii) $u_e = I_H$, where I_H is the identity operator on H .

Definition 1.6. ([21]) A **C^* -dynamical system** is a triple (G, A, α) , where G is a locally compact group, A is a C^* -algebra and α is a continuous action of G on A , i.e. a continuous homomorphism $\alpha: G \rightarrow \text{Aut}(A)$, where $\text{Aut}(A)$ is the group of automorphism of A .

Definition 1.7. ([7]) Let (G, A, α) be a C^* -dynamical system and let u be a projective unitary representation of G on a Hilbert space H . We say that a completely positive linear map $\varphi: A \rightarrow \mathcal{L}(H)$ is **projective u -covariant** with respect to the C^* -dynamical system (G, A, α) if $\varphi(\alpha_g(a)) = u_g \varphi(a) u_g^*$ for all $a \in A$ and $g \in G$.

Definition 1.8. ([5]) Let E be a Hilbert C^* -module over a C^* -algebra A and let H_1, H_2 be Hilbert spaces. Let $\varphi: A \rightarrow \mathcal{L}(H_1)$ be a linear map. A map $\Phi: E \rightarrow \mathcal{L}(H_1, H_2)$ is called :

- i) **φ -map** if $\langle \Phi(x), \Phi(y) \rangle = \varphi(\langle x, y \rangle)$, for all $x, y \in E$;
- ii) **φ -morphism** if Φ is a φ -map and φ is a morphism;
- iii) **φ -representation** if Φ is a φ -morphism and φ is a representation.

2. Main results

Following the results in [5] and [8], we generalize them in the projective covariant case.

Theorem 2.1. *Let E be a Hilbert B -module, let (G, A, α) be a unital C^* -dynamical system and let H_1, H_2 be two Hilbert spaces. If u is a projective unitary representation of G on H_1 with the normalized multiplier ω and $\varphi: A \rightarrow \mathcal{L}(H_1)$ is a unital projective u -covariant completely positive linear map and $\Phi: E \rightarrow \mathcal{L}(H_1, H_2)$ a φ -map, then there are :*

- (i) K_1, K_2 Hilbert spaces;
- (ii) a unital representation $\pi: A \rightarrow \mathcal{B}(K_1)$ and a π -representation $\psi: E \rightarrow \mathcal{L}(K_1, K_2)$;
- (iii) a projective unitary representation v of G on K_1 with the multiplier ω ;
- (iv) $V: H_1 \rightarrow K_1$ an isometry and $W: H_2 \rightarrow K_2$ a co-isometry such that for all $a \in A, g \in G$ and $x \in E$,
 - (a) $\varphi(a) = V^*\pi(a)V$,
 - (b) $u_g = V^*v_gV$,
 - (c) π is projective v -covariant,
 - (d) $\Phi(x) = W^*\psi(x)V$.

Proof. Following the proof of Stinespring's Theorem (Theorem 1.1.1, [1]), we form the algebraic tensor product $A \otimes_{alg} H_1$ and endow it with a pre-inner product by setting $\langle a \otimes \xi, b \otimes \zeta \rangle_{A \otimes_{alg} H_1} = (\varphi(b^*a)\xi|\zeta)_{H_1}$. To obtain K_1 we divide $A \otimes_{alg} H_1$ by the kernel $N = \{z \in A \otimes_{alg} H_1 | \langle z, z \rangle_{A \otimes_{alg} H_1} = 0\}$ of $\langle \cdot, \cdot \rangle_{A \otimes_{alg} H_1}$ and complete. K_1 becomes a Hilbert space with respect to the inner product given by $\langle z_1 + N, z_2 + N \rangle_{K_1} = \langle z_1, z_2 \rangle_{A \otimes_{alg} H_1}$, $z_1, z_2 \in A \otimes_{alg} H_1$.

The isometry $V: H_1 \rightarrow K_1$ is defined by $V\xi = 1_A \otimes \xi + N$ for all $\xi \in H_1$. It is easy to check that $V^*: K_1 \rightarrow H_1$ is given by $V^*(a \otimes \xi + N) = \varphi(a)\xi$.

The representation π of A on K_1 is defined by $\pi(a)(b \otimes \xi + N) = (ab) \otimes \xi + N$ for all $\xi \in H_1, a, b \in A$.

We define $v: G \rightarrow \mathcal{L}(K_1)$ by setting $v_g(a \otimes \xi + N) = \alpha_g(a) \otimes u_g\xi + N$ for all $a \in A, g \in G, \xi \in H_1$.

Since $\langle v_g(a \otimes \xi + N), v_g(b \otimes \zeta + N) \rangle_{K_1} = \langle \alpha_g(a) \otimes u_g\xi + N, \alpha_g(b) \otimes u_g\zeta + N \rangle_{K_1} = \langle \alpha_g(a) \otimes u_g\xi, \alpha_g(b) \otimes u_g\zeta \rangle_{A \otimes_{alg} H_1} = (\varphi(\alpha_g(b)^*\alpha_g(a))u_g\xi|u_g\zeta)_{H_1} = (\varphi(\alpha_g(b^*)\alpha_g(a))u_g\xi|u_g\zeta)_{H_1} = (\varphi(\alpha_g(b^*a))u_g\xi|u_g\zeta)_{H_1} = (u_g\varphi(b^*a)u_g^*u_g\xi|u_g\zeta)_{H_1} = (\varphi(b^*a)\xi|\zeta)_{H_1} = \langle a \otimes \xi, b \otimes \zeta \rangle_{A \otimes_{alg} H_1} = \langle a \otimes \xi + N, b \otimes \zeta + N \rangle_{K_1}$, for all $g \in G, a, b \in A, \xi, \zeta \in H_1$, v_g extends linearly to an isometry on K_1 . It can be easily verified that v_g is a unitary operator on K_1 .

We show now that v is a projective representation with the multiplier ω . Let $a \in A, g_1, g_2 \in G, \xi \in H_1$. Since α is a group homomorphism and u is a projective representation with the multiplier ω , we have

$$\begin{aligned} v_{g_1g_2}(a \otimes \xi + N) &= \alpha_{g_1g_2}(a) \otimes u_{g_1g_2}\xi + N = \alpha_{g_1}(a)\alpha_{g_2}(a) \otimes \omega(g_1, g_2)u_{g_1}u_{g_2}\xi + N \\ &= \omega(g_1, g_2)\alpha_{g_1}(\alpha_{g_2}(a)) \otimes u_{g_1}(u_{g_2}\xi) + N = \omega(g_1, g_2)v_{g_1}(\alpha_{g_2}(a) \otimes u_{g_2}\xi + N) \\ &= \omega(g_1, g_2)v_{g_1}v_{g_2}(a \otimes \xi + N). \end{aligned}$$

So we proved that v is a projective representation with the multiplier ω .

Let $a, b, x, y \in A$ and $\xi, \zeta \in H_1$. We have

$$\begin{aligned}
& (\varphi(y^*b^*ax)\xi|\zeta)_{H_1} = (\varphi((by)^*ax)\xi|\zeta)_{H_1} = \langle ax \otimes \xi, by \otimes \zeta \rangle_{A \otimes_{alg} H_1} \\
& = \langle \pi(a)(x \otimes \xi), \pi(b)(y \otimes \zeta) \rangle_{A \otimes_{alg} H_1} = \langle \pi(b)^*\pi(a)(x \otimes \xi), y \otimes \zeta \rangle_{A \otimes_{alg} H_1} \\
& = \langle \pi(b^*)\rho(a)(x \otimes \xi), y \otimes \zeta \rangle_{A \otimes_{alg} H_1} = \langle \pi(b^*a)(x \otimes \xi), y \otimes \zeta \rangle_{A \otimes_{alg} H_1} \\
& = \langle (b^*ax) \otimes \xi, y \otimes \zeta \rangle_{A \otimes_{alg} H_1} = \langle (y^*b^*ax) \otimes \xi, 1_A \otimes \zeta \rangle_{A \otimes_{alg} H_1} \\
& = \langle (y^*b^*ax1_A) \otimes \xi, 1_A \otimes \zeta \rangle_{A \otimes_{alg} H_1} = \langle \pi(y^*b^*ax)(1_A \otimes \xi), 1_A \otimes \zeta \rangle_{A \otimes_{alg} H_1} \\
& = \langle \pi(y^*b^*ax)V\xi, V\zeta \rangle_{A \otimes_{alg} H_1} = (V^*\pi(y^*b^*ax)V\xi|\zeta)_{H_1}.
\end{aligned}$$

Hence $V^*\pi(c)V = \varphi(c)$, $\forall c \in A$, so condition (a) is verified.

We verify now condition (b). Let $g \in G$ and $\xi \in H_1$. We have

$$\begin{aligned}
V^*v_gV\xi &= V^*v_g(1_A \otimes \xi + N) = V^*(\alpha_g(1_A) \otimes u_g\xi + N) = V^*(1_A \otimes u_g\xi + N) = \\
\varphi(1_A)u_g\xi &= I_H u_g\xi = u_g\xi, \text{ because } \varphi \text{ is unital.}
\end{aligned}$$

We prove condition (c). Let $a, b \in A, g \in G, \xi \in H_1$.

$$\begin{aligned}
& \text{Then } v_g\pi(a)v_g^*(b \otimes \xi + N) = v_g\pi(a)v_{g^{-1}}(b \otimes \xi + N) \\
& = v_g\pi(a)(\alpha_{g^{-1}}(b) \otimes u_{g^{-1}}\xi + N) = v_g(a\alpha_{g^{-1}}(b) \otimes u_{g^{-1}}\xi + N) \\
& = \alpha_g(a\alpha_{g^{-1}}(b)) \otimes (u_g u_{g^{-1}}\xi) + N = \alpha_g(a)\alpha_g(\alpha_{g^{-1}}(b)) \otimes \overline{\omega(g, g^{-1})}u_{gg^{-1}}\xi + N \\
& = \alpha_g(a)\alpha_{gg^{-1}}(b) \otimes I_H \xi + N = \alpha_g(a)b \otimes \xi + N = \pi(\alpha_g(a))(b \otimes \xi + N), \text{ so } \pi \text{ is} \\
& \text{projective } v\text{-covariant.}
\end{aligned}$$

Let $K_2 = [\Phi(E)H_1]$. We define $\psi: E \rightarrow \mathcal{L}(K_1, K_2)$ by

$$\psi(x)(\pi(a)V\xi) = \Phi(xa)\xi,$$

for all $a \in A, \xi \in H_1, x \in E$.

We show that $\psi(x)$ is well defined and bounded.

$$\begin{aligned}
& \|\psi(x)(\pi(a)V\xi)\|^2 = \|\Phi(xa)\xi\|^2 = \langle \Phi(xa)\xi, \Phi(xa)\xi \rangle = \langle \xi, (\Phi(xa))^*\Phi(xa)\xi \rangle \\
& = \langle \xi, \varphi(a^*\langle x, x \rangle a)V\xi \rangle = \langle \xi, V^*\pi(a^*\langle x, x \rangle a)V\xi \rangle = \langle \pi(a)V\xi, \pi(\langle x, x \rangle)\pi(a)V\xi \rangle \\
& \leq \|\pi(\langle x, x \rangle)\| \|\pi(a)V\xi\|^2 \leq \|x\|^2 \|\pi(a)V\xi\|^2.
\end{aligned}$$

Hence, $\psi(x)$ can be extended to K_1 .

We prove that ψ is a π -morphism. Let $x, y \in E, a, b \in A, \xi, \zeta \in H_1$.

$$\begin{aligned}
& \langle \psi(x)^*\psi(y)(\pi(b)V\xi), \pi(a)V\zeta \rangle = \langle \Phi(yb)\xi, \Phi(xa)\zeta \rangle = \langle (\Phi(xa))^*\Phi(yb)\xi, \zeta \rangle \\
& = \langle \varphi(\langle xa, yb \rangle)\xi, \zeta \rangle = \langle V^*\pi(a)^*\pi(\langle x, y \rangle)\pi(b)V\zeta \rangle = \langle \pi(\langle x, y \rangle)(\pi(b)V\xi), \pi(b)V\zeta \rangle
\end{aligned}$$

Thus, $\psi(x)^*\psi(y) = \pi(\langle x, y \rangle)$.

Let W be the orthogonal projection onto K_2 . Then $W^*: K_2 \rightarrow H_2$ is the inclusion map (because, obviously, $K_2 \subseteq H_2$). Hence $WW^* = I_{K_2}$, that means W is a coisometry.

For $x \in E, \xi \in H_1$, we have

$$W^*\psi(x)V\xi = \psi(x)V\xi = \psi(x)(\pi(1_A)V\xi) = \Phi(x)\xi, \text{ so (d) holds. } \quad \square$$

Remark 2.1. *The pair of triples $((\pi, V, K_1), (\psi, W, K_2))$ is a projective covariant Stinespring representation of (φ, Φ) if conditions (i) – (iv) of Theorem 2.1 are satisfied.*

Definition 2.1. ([20]) *Let A be a C^* -algebra, E a Hilbert A -module and let H, K be two Hilbert spaces. A map $\psi: E \rightarrow \mathcal{L}(H, K)$ is called **quasi-representation** if there is a $*$ -homomorphism $\pi: A \rightarrow \mathcal{L}(H)$ such that*

$$\langle \psi(y)f_1, \psi(x)f_2 \rangle = \langle \pi(\langle x, y \rangle)f_1, f_2 \rangle$$

for all $x, y \in E, f_1, f_2 \in H$.

We say that π is associated to ψ .

Quasi-representations generalize the notion of representations of Hilbert C^* -modules on Hilbert spaces.

Definition 2.2. ([14]) Let G be a locally compact group. A continuous action of G on a full Hilbert A -module E is a group morphism $\eta: G \rightarrow \text{Aut}(E)$, where $\text{Aut}(E)$ is the group of all isomorphisms of Hilbert C^* -modules from E to E , such that the map $(t, x) \mapsto \eta_t(x)$ from $G \times E$ to E is continuous. The triple (G, E, η) is called a **dynamical system on Hilbert C^* -modules**.

Remark 2.2. ([14]) Any C^* -dynamical system (G, A, α) can be regarded as a dynamical system on Hilbert C^* -modules.

Any continuous action η of G on E induces a unique continuous action α^η of G on A such that $\alpha_t^\eta(\langle x, y \rangle) = \langle \eta_t(x), \eta_t(y) \rangle$ for all $x, y \in E, t \in G$.

Moreover, for all $x \in E$ and $a \in A$, we have $\eta_t(xa) = \eta_t(x)\alpha_t^\eta(a)$.

Definition 2.3. Let E be a Hilbert C^* -module over a C^* -algebra A , (G, η, E) a dynamical system and H, K two Hilbert spaces, $v: G \rightarrow \mathcal{U}(H)$ and $w: G \rightarrow \mathcal{U}(K)$ two projective unitary representations. A quasi-representation $\psi: E \rightarrow \mathcal{L}(H, K)$ is called **projective (w, v) -covariant** with respect to (G, η, E) if

$$\psi(\eta_t(\xi)) = w_t \psi(\xi) v_t^*$$

for all $\xi \in E, t \in G$. Then (ψ, v, w, H, K) is called a **projective covariant quasi-representation** of (G, η, E) .

Definition 2.4. Let E be a Hilbert C^* -module over a C^* -algebra A , (G, η, E) a dynamical system and H, K two Hilbert spaces, $u: G \rightarrow \mathcal{U}(H)$ and $u': G \rightarrow \mathcal{U}(K)$ two projective unitary representations. A φ -map $\Phi: E \rightarrow \mathcal{L}(H, K)$ is called **projective (u', u) -covariant** with respect to (G, η, E) if

$$\Phi(\eta_t(\xi)) = u'_t \Phi(\xi) u_t^*$$

for all $\xi \in E, t \in G$.

Remark 2.3. If E is full and $\Phi: E \rightarrow F$ is a φ -map which is projective (u', u) -covariant with respect to (G, η, E) , then the map φ is projective u -covariant with respect to the induced C^* -dynamical system (G, α^η, A) .

Theorem 2.2. Let E be a full Hilbert C^* -module over a C^* -algebra A , (G, η, E) a dynamical system and H, K two Hilbert spaces, $u: G \rightarrow \mathcal{U}(H)$ and $u': G \rightarrow \mathcal{U}(K)$ two projective unitary representations. If $\varphi: A \rightarrow \mathcal{L}(H)$ is completely positive and $\Phi: E \rightarrow \mathcal{L}(H, K)$ is a φ -map which is (u', u) -covariant with respect to (G, η, E) , then there are

- 1) a) a Hilbert space X with a projective covariant representation (π, v) of (G, α^η, A)
- b) an isometry $V: H \rightarrow X$ such that
 - i) $\varphi(a)\xi = V^* \pi(a) V \xi$ for all $a \in A, \xi \in H$

- ii) $v_t V \xi = V u_t \xi$ for all $t \in G, \xi \in H$
- 2) a Hilbert space Y and a projective covariant quasi-representation (ψ, v, w, X, Y) of (G, η, E) such that π is associated to ψ
- 3) a coisometry $S: K \rightarrow Y$ such that
- $\Phi(x)\xi = S^* \psi(x) V \xi$ for all $x \in E, \xi \in H$
 - $w_t S l = S u_t' l$ for all $t \in G, l \in K$

Proof. 1) a) Let $\langle \cdot, \cdot \rangle$ be a A -valued positive semi-inner product on $A \otimes_{alg} H$ defined by

$$\langle a \otimes \xi, b \otimes \zeta \rangle_{A \otimes_{alg} H} = (\varphi(a^* b) \xi | \zeta)_H$$

for all $a, b \in A, \xi, \zeta \in H$.

Let $N = \{z \in A \otimes_{alg} H | \langle z, z \rangle_{A \otimes_{alg} H} = 0\}$.

$\langle \cdot, \cdot \rangle$ extends naturally on the quotient $A \otimes_{alg} H / N$. To obtain X we complete $A \otimes_{alg} H / N$.

Let $\pi: A \rightarrow \mathcal{L}(X)$ defined by

$$\pi(a)(b \otimes \xi + N) = ab \otimes \xi + N$$

for all $a, b \in A, \xi \in H$

and $v: G \rightarrow \mathcal{U}(X)$ defined by

$$v_t(a \otimes \xi + N) = \alpha_t^\eta(a) \otimes u_t(\xi) + N$$

for all $a \in A, \xi \in H, t \in G$.

Since $\langle v_t(a \otimes \xi + N), v_t(b \otimes \zeta + N) \rangle = \langle \alpha_t^\eta(a) \otimes u_t(\xi) + N, \alpha_t^\eta(b) \otimes u_t(\zeta) + N \rangle = (\varphi((\alpha_t^\eta(a))^* \alpha_t^\eta(b)) u_t(\xi) | u_t(\zeta))_H = (\varphi(\alpha_t^\eta(a^*) \alpha_t^\eta(b)) u_t(\xi) | u_t(\zeta))_H = (u_t^* \varphi(\alpha_t^\eta(a^* b)) u_t(\xi) | \zeta)_H = (\varphi(a^* b) \xi | \zeta)_H = \langle a \otimes \xi + N, b \otimes \zeta + N \rangle$, by the covariance of φ , v_t extends to an isometry on X .

We verify that v is a projective representation with the multiplier ω . Let $a \in A, \xi \in H, t_1, t_2 \in G$. We have

$$v_{t_1 t_2}(a \otimes \xi + N) = \alpha_{t_1 t_2}^\eta(a) \otimes u_{t_1 t_2}(\xi) + N = \alpha_{t_1}^\eta \alpha_{t_2}^\eta(a) \otimes \omega(t_1, t_2) u_{t_1} u_{t_2}(\xi) + N = \omega(t_1, t_2) v_{t_1}(\alpha_{t_2}^\eta(a) \otimes u_{t_2}(\xi) + N) = \omega(t_1, t_2) v_{t_1} v_{t_2}(a \otimes \xi + N)$$

We prove that π is a covariant representation.

$$\begin{aligned} v_t \pi(a) v_t^*(b \otimes \zeta + N) &= v_t \pi(a) (\alpha_{t^{-1}}^\eta(b) \otimes u_{t^{-1}}(\zeta) + N) = \\ v_t (\alpha_{t^{-1}}^\eta(a) \otimes u_{t^{-1}}(\zeta) + N) &= \alpha_t^\eta(a) \alpha_{t^{-1}}^\eta(\alpha_{t^{-1}}^\eta(b)) \otimes u_t u_{t^{-1}} \zeta + N = \\ \alpha_t^\eta(a) b \otimes \omega(t, t^{-1}) u_{t t^{-1}} \zeta + N &= \alpha_t^\eta(a) b \otimes \zeta + N = \pi(\alpha_t^\eta(a))(b \otimes \zeta + N) \end{aligned}$$

b) Let $V: H \rightarrow X$ defined by

$$V \xi = 1_A \otimes \xi + N$$

for all $\xi \in H$. It can be easily checked that $V^*: X \rightarrow H$,

$$V^*(a \otimes \xi + N) = \varphi(a) \xi.$$

i) This condition is verified as in the proof of Theorem 2.1 (iv) (a).

ii) $v_t V \xi = v_t(1_A \otimes \xi + N) = \alpha_t^\eta(1_A) \otimes u_t(\xi) + N = 1_A \otimes u_t(\xi) + N = V u_t \xi$

2) Let $Y = [\Phi(E)H]$.

Let $w_t = u'_t/Y$ for all $t \in G$. Then $t \mapsto w_t$ is a projective representation of G .

We define $\psi: E \rightarrow \mathcal{L}(X, Y)$ by $\psi(x)(\pi(a)V\xi) = \Phi(xa)\xi$ for all $a \in A, \xi \in H, x \in E$.

We prove that ψ is a quasi-representation:

$$\begin{aligned} \langle \psi(y)(\pi(a)V\xi), \psi(x)(\pi(b)V\zeta) \rangle &= \langle \Phi(ya)\xi, \Phi(xb)\zeta \rangle = \\ \langle \varphi(\langle ya, xb \rangle)\xi, \zeta \rangle &= \langle V^*\pi(\langle ya, xb \rangle)V\xi, \zeta \rangle = \langle \pi(\langle ya, xb \rangle)V\xi, V\zeta \rangle = \\ \langle \pi(b)^*\pi(\langle x, y \rangle)\pi(a)V\xi, V\zeta \rangle &= \langle \pi(\langle x, y \rangle)\pi(a)V\xi, \pi(b)V\zeta \rangle, \text{ for all } a \in A, x, y \in E, \xi, \zeta \in H. \end{aligned}$$

We prove that ψ is projective (w, v) -covariant.

For all $a \in A, t \in G, x \in E, \xi \in H$, we have

$$\psi(\eta_t(x))(\pi(a)V\xi) = \Phi(\eta_t(x)a)\xi = \Phi(\eta_t(x)\alpha_t(\alpha_{t-1}^\eta(a)))\xi = \Phi(\eta_t(x\alpha_{t-1}^\eta(a)))\xi = u'_t\Phi(x\alpha_{t-1}^\eta(a))u_t^*\xi$$

$$\begin{aligned} \text{On the other hand, by 1) a) and 1) b) ii), } w_t\psi(x)v_t^*(\pi(a)V\xi) &= \\ w_t\psi(x)v_{t-1}(\pi(a)V\xi) &= w_t\psi(x)\pi(\alpha_{t-1}^\eta(a))v_{t-1}V\xi = w_t\psi(x)\pi(\alpha_{t-1}^\eta(a))Vu_{t-1}\xi = \\ w_t\psi(x)\pi(\alpha_{t-1}^\eta(a))Vu_t^*\xi &= w_t\Phi(x\alpha_{t-1}^\eta(a))u_t^*\xi = u'_t\Phi(x\alpha_{t-1}^\eta(a))u_t^*\xi \end{aligned}$$

3) By Theorem 5.2, [18], there is an orthogonal projection S from K into Y .

$$\text{a) } S^*\psi(x)V\xi = \psi(x)V\xi = \psi(x)(\pi(1_A)V\xi) = \Phi(x1_A)\xi = \Phi(x)\xi$$

b) It is clear. □

Definition 2.5. ([6], [13]) Let A be a C^* -algebra, H be a Hilbert space and k be a positive integer.

A k -linear map $\varphi: A^k \rightarrow \mathcal{L}(H)$ is called **symmetric** if $\varphi = \varphi^*$, where $\varphi^*: A^k \rightarrow \mathcal{L}(H)$ is the k -linear map given by $\varphi^*(a_1, a_2, \dots, a_k) = \varphi(a_k^*, \dots, a_2^*, a_1^*)^*$.

A k -linear map $\varphi: A^k \rightarrow \mathcal{L}(H)$ is called **completely bounded** if

$$\|\varphi\|_{cb} = \sup_n \|\varphi_n\| < \infty,$$

where $\varphi_n: M_n(A) \rightarrow \mathcal{L}(H^n)$, $\varphi_n(A_1, A_2, \dots, A_k) = [\sum_{l,r,\dots,t=1}^n \varphi(a_{1il}, a_{2lr}, \dots, a_{ktj})]_{i,j=1}^n$, for $A_l = [a_{lij}]_{i,j=1}^n \in M_n(A)$, $l = \overline{1, k}$ and $\|\varphi_n\| = \sup \{ \|\varphi_n(A_1, A_2, \dots, A_k)\|; A_l \in M_n(A), \|A_l\| \leq 1, l = \overline{1, k} \}$.

A k -linear map $\varphi: A^k \rightarrow \mathcal{L}(H)$ is called **completely positive** if

$$\varphi_n(A_1, A_2, \dots, A_k) \geq 0$$

for all $(A_1, A_2, \dots, A_k) \in M_n(A)^k$ with $(A_1, A_2, \dots, A_k) = (A_k^*, \dots, A_2^*, A_1^*)$ and $A_m \geq 0$ if k is odd and $m = \lceil \frac{k+1}{2} \rceil$ and for all $n \in \mathbb{N}$.

Definition 2.6. ([11], [12], [13]) A k -linear map $\varphi: A^k \rightarrow \mathcal{L}(H)$ is called **invariant** if:

(a) for odd $k = 2m - 1$,

$$\varphi(a_1c_1, \dots, a_{m-1}c_{m-1}, a_m, a_{m+1}, \dots, a_k) = \varphi(a_1, \dots, a_{m-1}, a_m, c_m a_{m+1}, \dots, c_1 a_k)$$

for all $a_1, \dots, a_k, c_1, \dots, c_m \in A$,

(b) for even $k = 2m$,

$$\varphi(a_1c_1, \dots, a_m c_m, a_{m+1}, \dots, a_k) = \varphi(a_1, \dots, a_{m-1}, a_m, c_{m-1}a_{m+1}, \dots, c_1a_k)$$

for all $a_1, \dots, a_k, c_1, \dots, c_{m-1} \in A$.

Definition 2.7. ([13]) A k -**representation** of A on H is a k -linear map $\pi: A^k \rightarrow \mathcal{L}(H)$ with the properties:

(i) for each $l \in \{1, \dots, k\}$, the map $\pi_l: A \rightarrow \mathcal{L}(H)$ defined by $\pi_l(a) = \pi(1_A, \dots, 1_A, a, 1_A, \dots, 1_A)$ is a representation of A on H , where a is on the l -th position;

(ii) $\pi(a_1, \dots, a_k) = \pi_1(a_1) \cdots \pi_k(a_k)$ for all $a_1, \dots, a_k \in A$.

Definition 2.8. ([13]) Let A be a C^* -algebra, H, K be two Hilbert spaces, E be a Hilbert A -module and k be a positive integer. Let $\varphi: A^k \rightarrow \mathcal{L}(H)$ be a k -linear map and $\Phi: E^k \rightarrow \mathcal{L}(H, K)$ a map. Then

(1) Φ is called a φ -**map** if

$$\Phi(x_1, \dots, x_k)^* \Phi(y_1, \dots, y_k) = \varphi(\langle x_1, y_1 \rangle, \dots, \langle x_k, y_k \rangle)$$

for all $x_1, \dots, x_k, y_1, \dots, y_k \in E$.

(2) Φ is called a φ -**representation** of E if Φ is a φ -map and φ is a k -representation of A on H . In this case we say that the pair (Φ, φ) is a k -**representation** of E on H and K .

We say that a φ -map Φ is **symmetric** (respectively, **invariant**, **completely bounded**, **completely positive**) if the corresponding map φ is symmetric (respectively, invariant, completely bounded, completely positive). Similarly we can define symmetric, invariant, completely bounded, completely positive φ -representations of E .

Let (G, A, α) be a C^* -dynamical system. The action α naturally induces the action $\tilde{\alpha}: G \rightarrow \text{Aut}(A^k)$ by $\tilde{\alpha}_t(a_1, \dots, a_k) = (\alpha_t(a_1), \dots, \alpha_t(a_k))$ for all $a_1, \dots, a_k \in A$ and $t \in G$. ([11])

Following the definition in [11], [10], we introduce the notions of projective u -covariant k -linear map and projective $(\tilde{\tau}, v, u)$ -covariant k -linear map.

Definition 2.9. Let $u: G \rightarrow \mathcal{L}(H)$ be a projective unitary representation of G on H . A k -linear map $\varphi: A^k \rightarrow \mathcal{L}(H)$ is called **projective u -covariant** if

$$\varphi(\tilde{\alpha}_t(a_1, \dots, a_k)) = \varphi(\alpha_t(a_1), \dots, \alpha_t(a_k)) = u_t \varphi(a_1, \dots, a_k) u_t^*$$

for all $a_1, \dots, a_k \in A$ and $t \in G$.

Definition 2.10. Let E be a Hilbert A -module, H, K be two Hilbert spaces and $u: G \rightarrow \mathcal{L}(H)$ be a projective unitary representation. For any map $\tau_t: E \rightarrow E$ we define $\tilde{\tau}_t: E^k \rightarrow E^k$ by $\tilde{\tau}_t(x_1, \dots, x_k) = (\tau_t(x_1), \dots, \tau_t(x_k))$. A k -linear map $\Phi: E^k \rightarrow \mathcal{L}(H, K)$ is called **projective $(\tilde{\tau}, v, u)$ -covariant** if there is a map $\tau: G \rightarrow \mathcal{B}_A(E)$ and a projective unitary representation $v: G \rightarrow \mathcal{L}(K)$ such that

$$\Phi(\tilde{\tau}_t(x_1, \dots, x_k)) = \Phi(\tau_t(x_1), \dots, \tau_t(x_k)) = v_t \Phi(x_1, \dots, x_k) v_t^*$$

for all $x_1, \dots, x_k \in E$ and $t \in G$.

We prove now the multilinear projective version of the Stinespring's representation theorem for a pair of two k -linear maps. ([5], [11], [12], [13])

Theorem 2.3. *Let (G, A, α) be a unital C^* -dynamical system, $u: G \rightarrow \mathcal{L}(H)$ be a projective unitary representation of G on a Hilbert space H with the multiplier ω . Let $\varphi: A^k \rightarrow \mathcal{L}(H)$ be an invariant, symmetric, completely positive k -linear map, K be a Hilbert space, E be a Hilbert A -module and $\Phi: E^k \rightarrow \mathcal{L}(H, K)$ be a φ -map. If φ is projective u -covariant and Φ is projective $(\tilde{\tau}, v, u)$ -covariant, then there are H_φ, K_Φ two Hilbert spaces, an invariant, symmetric k -representation (Π_Φ, π_φ) of E on H_φ and K_Φ , a projective unitary representation σ of G on H_φ , a bounded linear operator $V_\varphi \in \mathcal{L}(H, H_\varphi)$ and a coisometry $W_\Phi: K \rightarrow K_\Phi$ such that:*

- a) *i) $H_\varphi = \overline{\text{sp}}\{\pi_\varphi(a_1, \dots, a_k)V_\varphi\xi \mid a_1, \dots, a_k \in A, \xi \in H\}$*
ii) $K_\Phi = \overline{\text{sp}}\{\Pi_\Phi(x_1, \dots, x_k)V_\varphi\xi \mid x_1, \dots, x_k \in E, \xi \in H\}$
- b) *$\varphi(a_1, \dots, a_k) = V_\varphi^* \pi_\varphi(a_1, \dots, a_k) V_\varphi$ for all $a_1, \dots, a_k \in A$;*
- c) *π_φ is projective σ -covariant : $\pi_\varphi(\tilde{\alpha}_t(a_1, \dots, a_k)) = \sigma_t \pi_\varphi(a_1, \dots, a_k) \sigma_t^*$ for all $a_1, \dots, a_k \in A, t \in G$;*
- d) *$V_\varphi u_t = \sigma_t V_\varphi$ for all $t \in G$;*
- e) *Π_Φ is projective $(\tilde{\tau}, v, \tilde{u})$ -covariant, where $\tilde{u}_t = \text{id}_{A^{\otimes m}} \otimes u_t$;*
- f) *$v_t \Pi_\Phi(x_1, \dots, x_k) \sigma_{t-1} = \Pi_\Phi(\tilde{\tau}_t(x_1, \dots, x_k))(\alpha_{t-1}^{\otimes m} \otimes \text{id}_H)$ for all $x_1, \dots, x_k \in E, t \in G$.*

The triple of pairs $((\Pi_\Phi, \pi_\varphi), (H_\varphi, K_\Phi), (V_\varphi, W_\Phi))$ is called the projective covariant Stinespring's representation associated to a k -linear φ -map.

Proof. By [10], [9], there is $(\pi_\varphi, H_\varphi, V_\varphi)$ the minimal Stinespring's representation associated to φ such that a)i) and b) hold,

There are $(\Pi_\Phi, K_\Phi, W_\Phi)$ as in Theorem 3.3 ([13]) and a)ii) holds.

We define the unitary representation σ of G on H_φ as in the proof of Proposition 4.1, [13].

We prove that σ is a projective representation with the multiplier ω .

Let $a_1, \dots, a_k \in A, \xi \in H, t_1, t_2 \in G$. We have

$$\begin{aligned} \sigma_{t_1 t_2}(\pi_\varphi(a_1, \dots, a_k)V_\varphi\xi) &= \pi_\varphi(\tilde{\alpha}_{t_1 t_2}(a_1, \dots, a_k))V_\varphi u_{t_1 t_2} \xi = \\ \pi_\varphi(\tilde{\alpha}_{t_1}(\tilde{\alpha}_{t_2}(a_1, \dots, a_k)))V_\varphi \omega(t_1, t_2) u_{t_1} u_{t_2} \xi &= \\ \omega(t_1, t_2) \pi_\varphi(\tilde{\alpha}_{t_1}(\tilde{\alpha}_{t_2}(a_1, \dots, a_k)))V_\varphi u_{t_1} u_{t_2} \xi &= \\ \omega(t_1, t_2) \sigma_{t_1}(\pi_\varphi(\alpha_{t_2}(a_1, \dots, a_k))V_\varphi u_{t_2} \xi) &= \omega(t_1, t_2) \sigma_{t_1} \sigma_{t_2}(\pi_\varphi(a_1, \dots, a_k)V_\varphi \xi) \end{aligned}$$

By Proposition 4.1 and Theorem 4.4 ([13]), c), d), e) and f) are satisfied. \square

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